Static Filters

Research Topics in Database Management

Niv Dayan

What is a Filter?

What is a Filter?

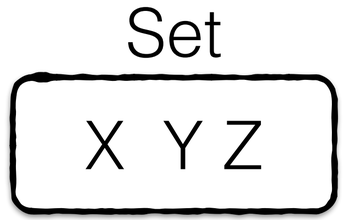
Does X exist? → 

Set

X Y Z

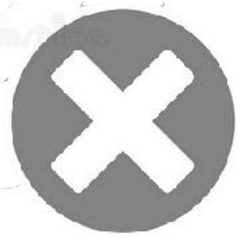
What is a Filter?

Does X exist? →  →



No false negatives

false positives with tunable probability



Why use a Filter?

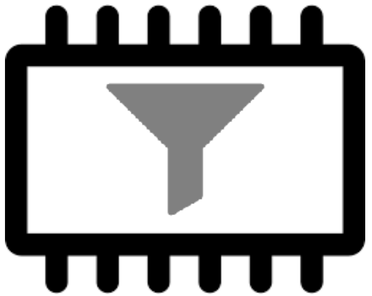
Data

Does key X exist

Data

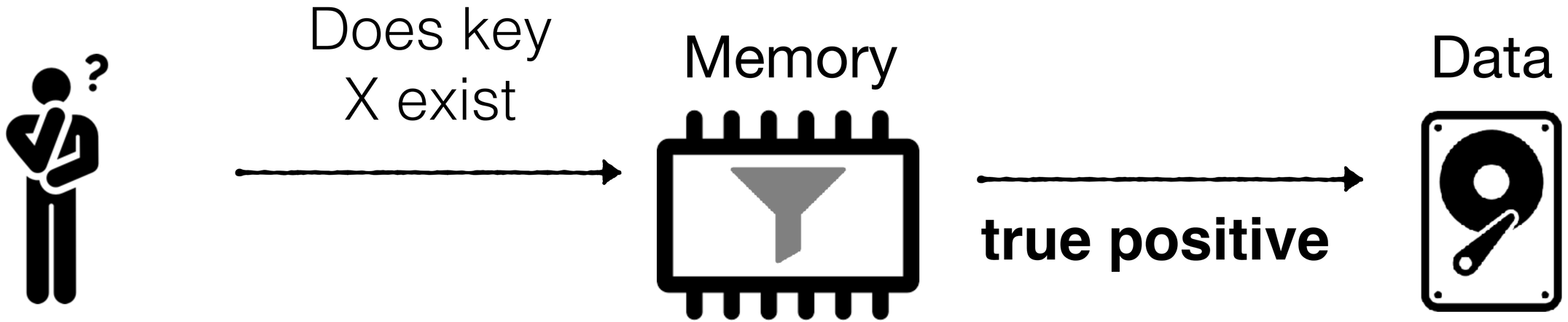
Does key X exist

Memory

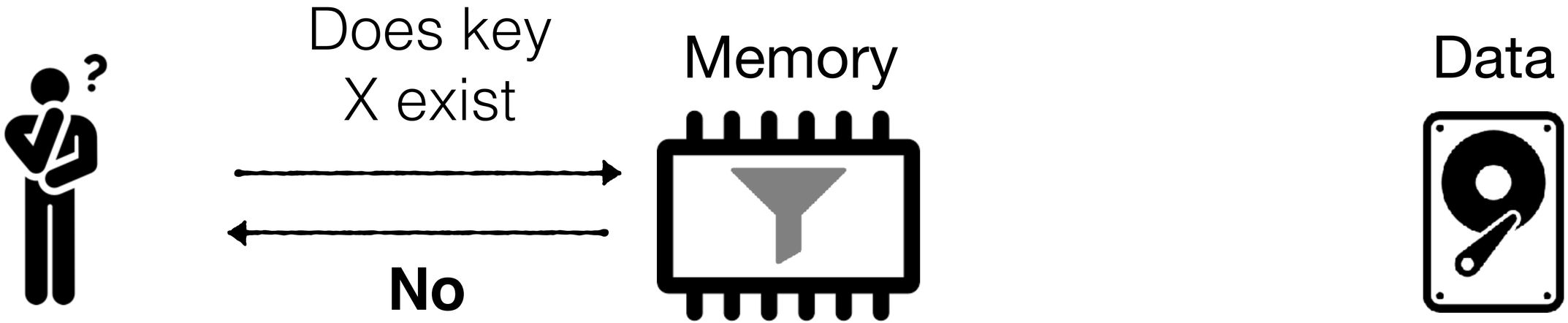


Data

If key X exists



If key X does not exist



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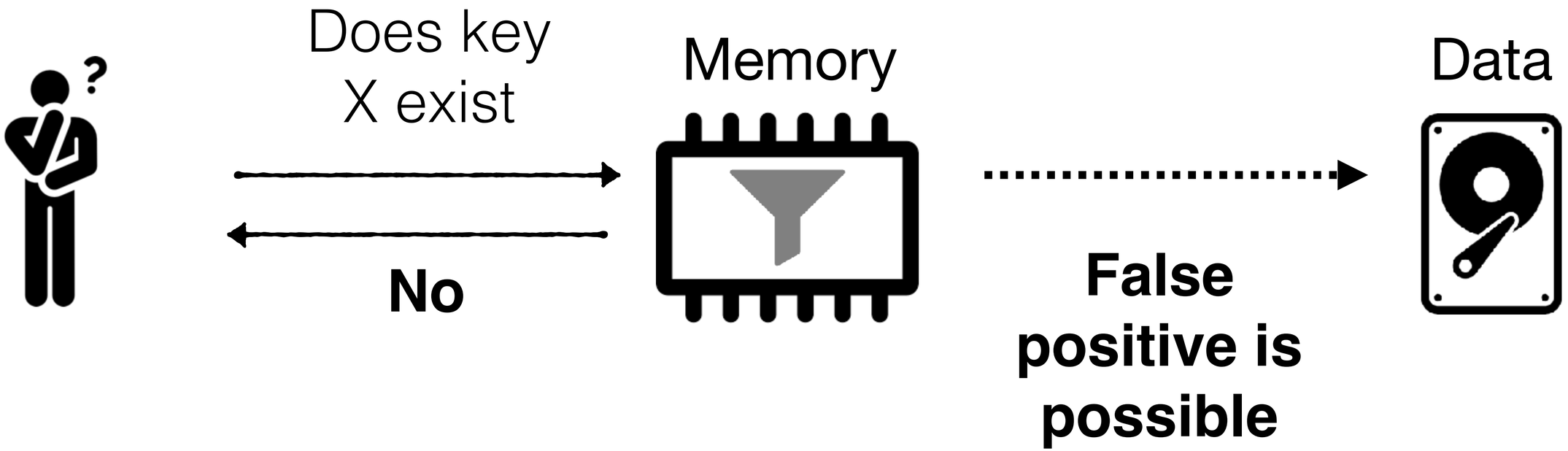

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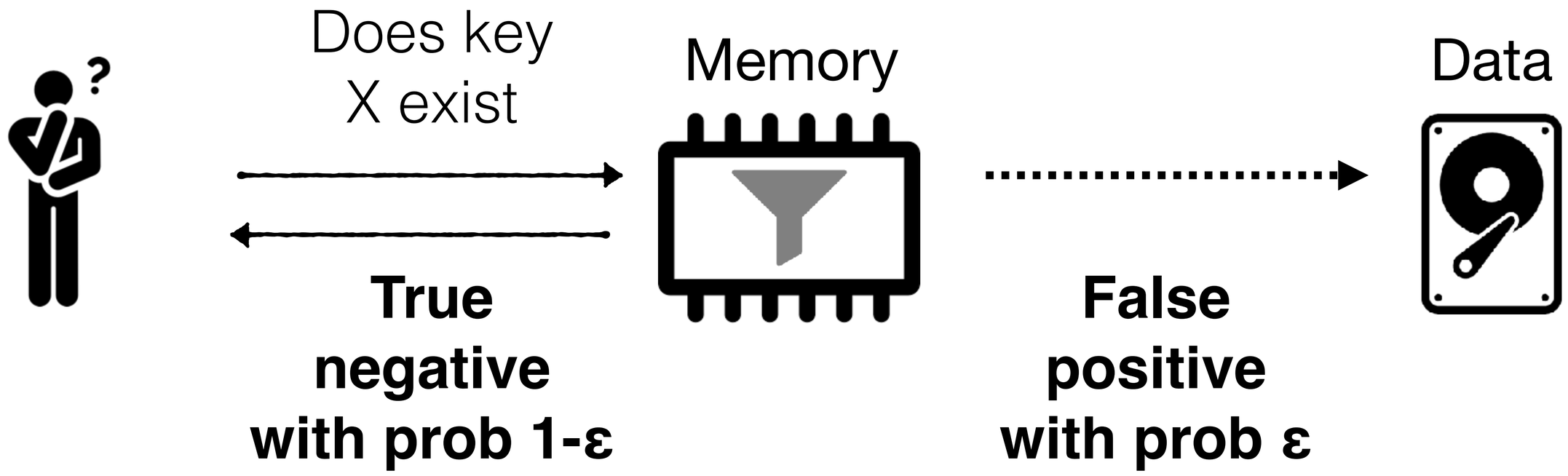

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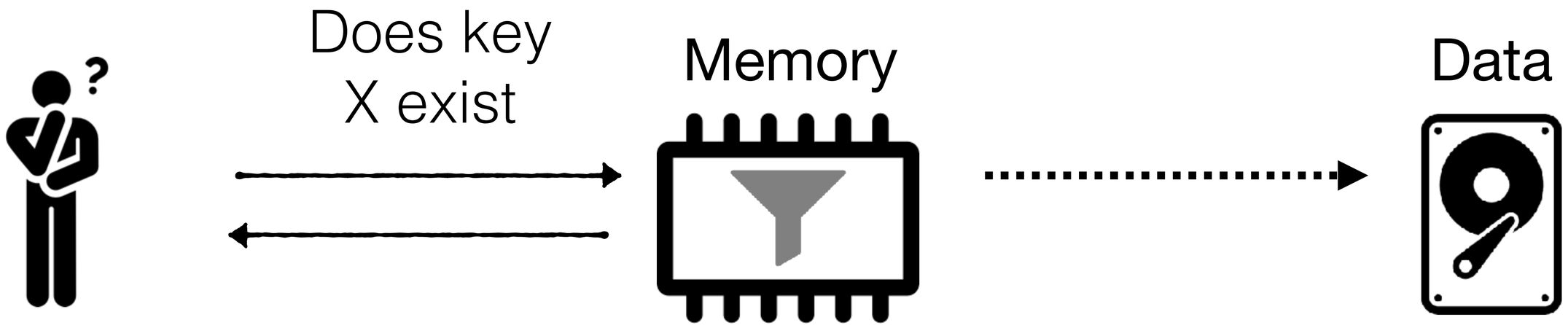
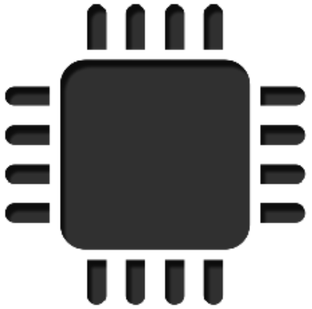


ε - false positive rate - FPR

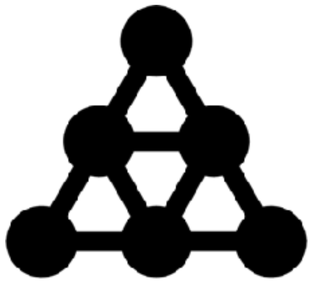
Why care about filters?

Widely used in systems

Hardware Optimizations



Algorithmic Reasoning/ Techniques

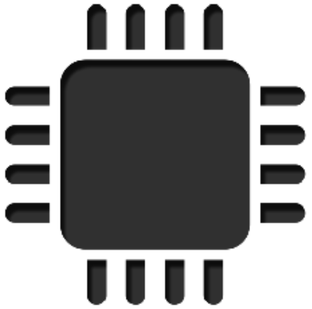


Why care about filters?

Widely used in systems

Means to learn

Hardware Optimizations



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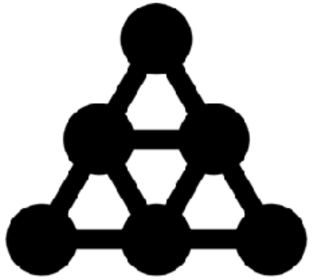
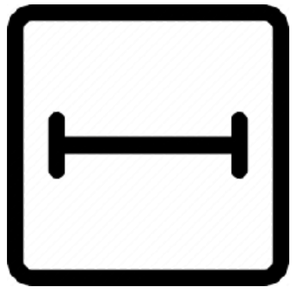


Static Filters

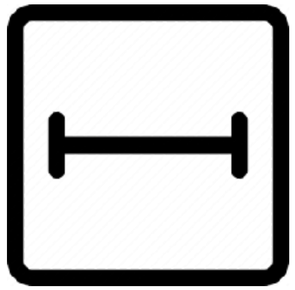
No deletes



No Resizing

Static Filters

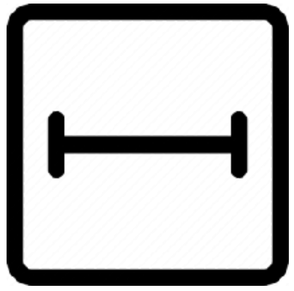
No deletes



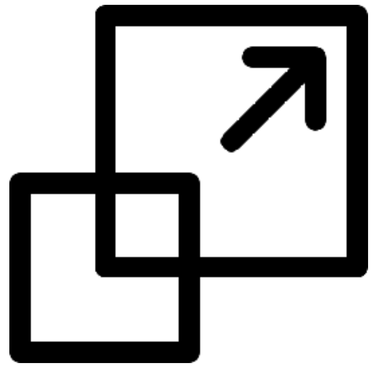
No Resizing

Modifications require rebuilding from scratch

Static Filters

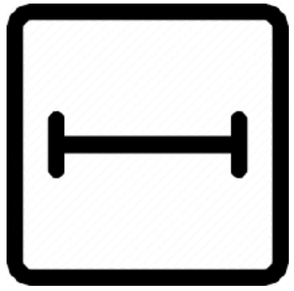


Dynamic Filters (next week)



Delete + Resize

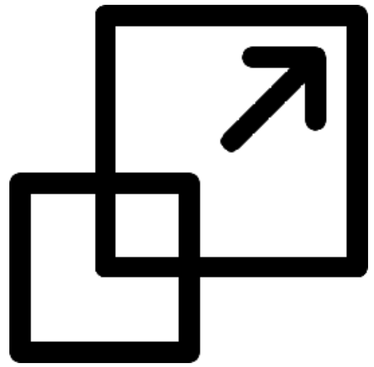
Static Filters



Fastest Queries

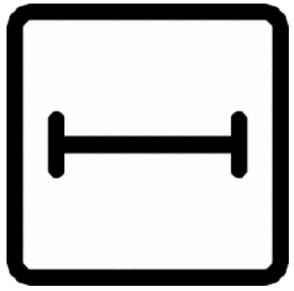
Lowest FPR

Dynamic Filters



Delete + Resize

Static Filters

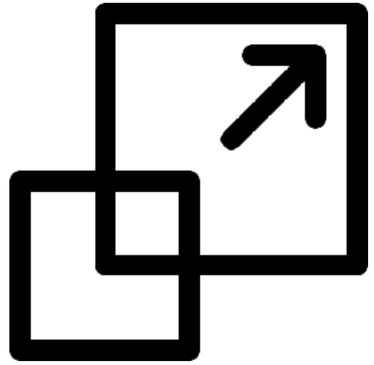


Fastest Queries

Lowest FPR

But not both at same time

Dynamic Filters



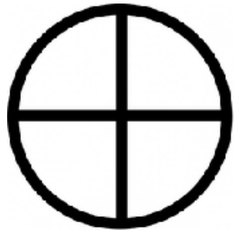
Delete + Resize

Static Filters

Bloom

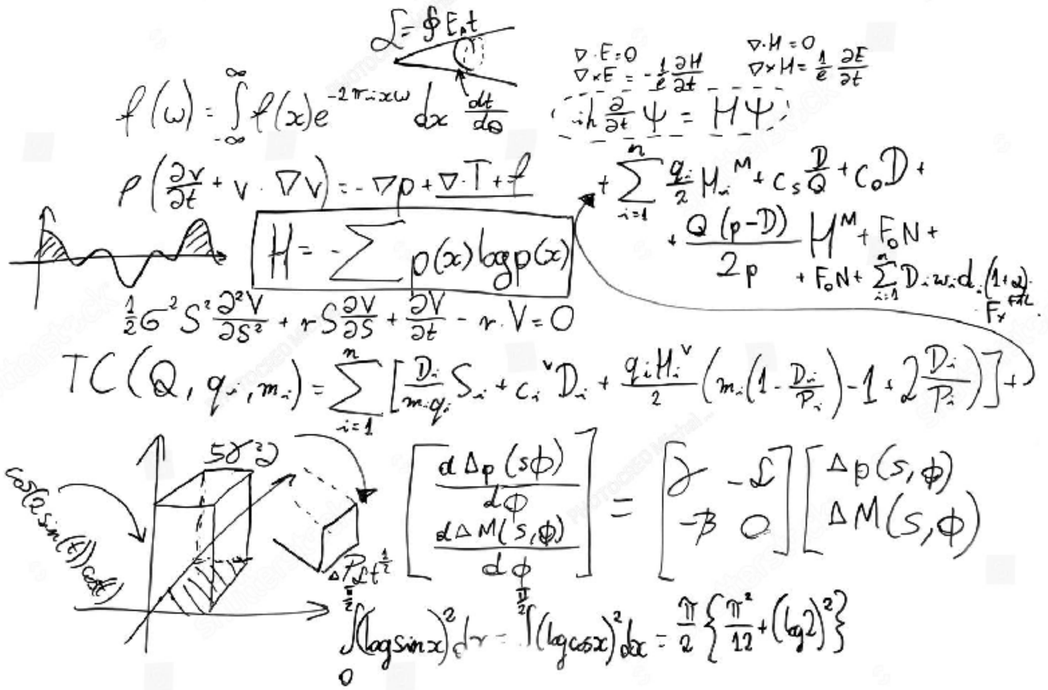
Fastest Queries

XOR



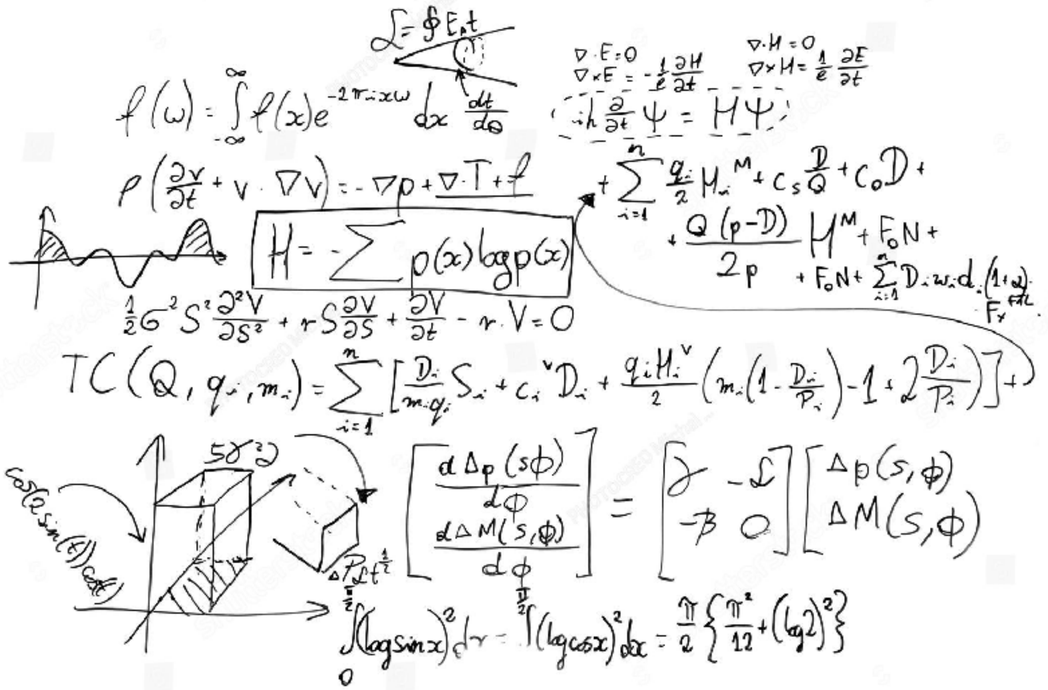
Lowest FPR

Note



Today is more mathematical than usual

Note



Today is more mathematical than usual

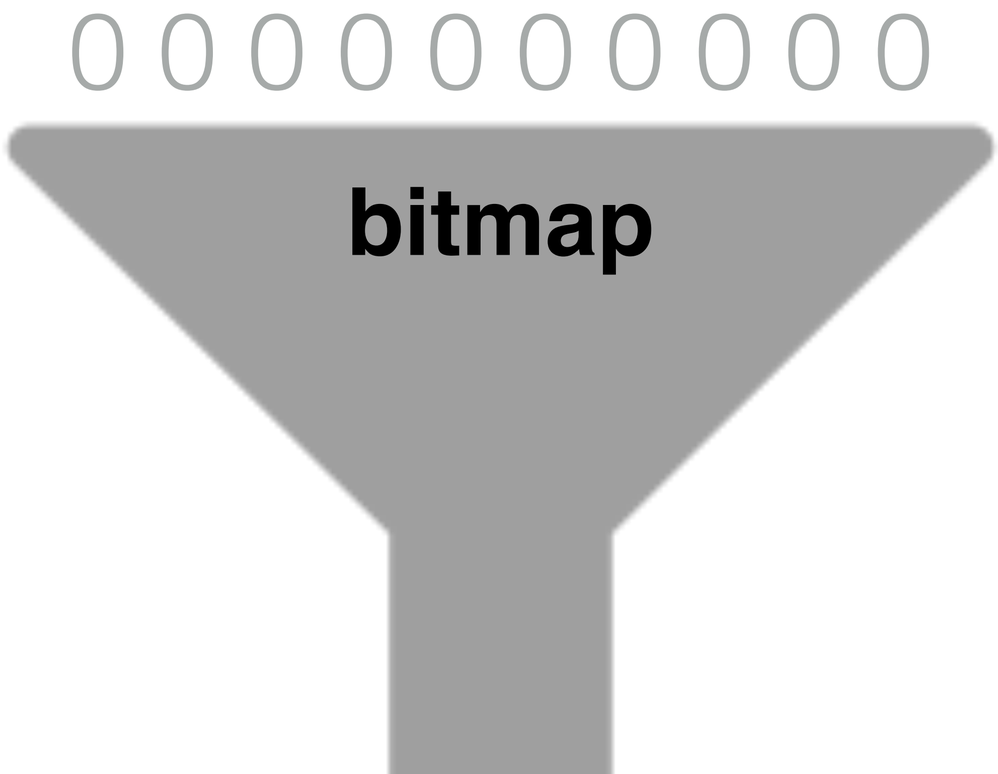
(Do not be intimidated)

Bloom Filters

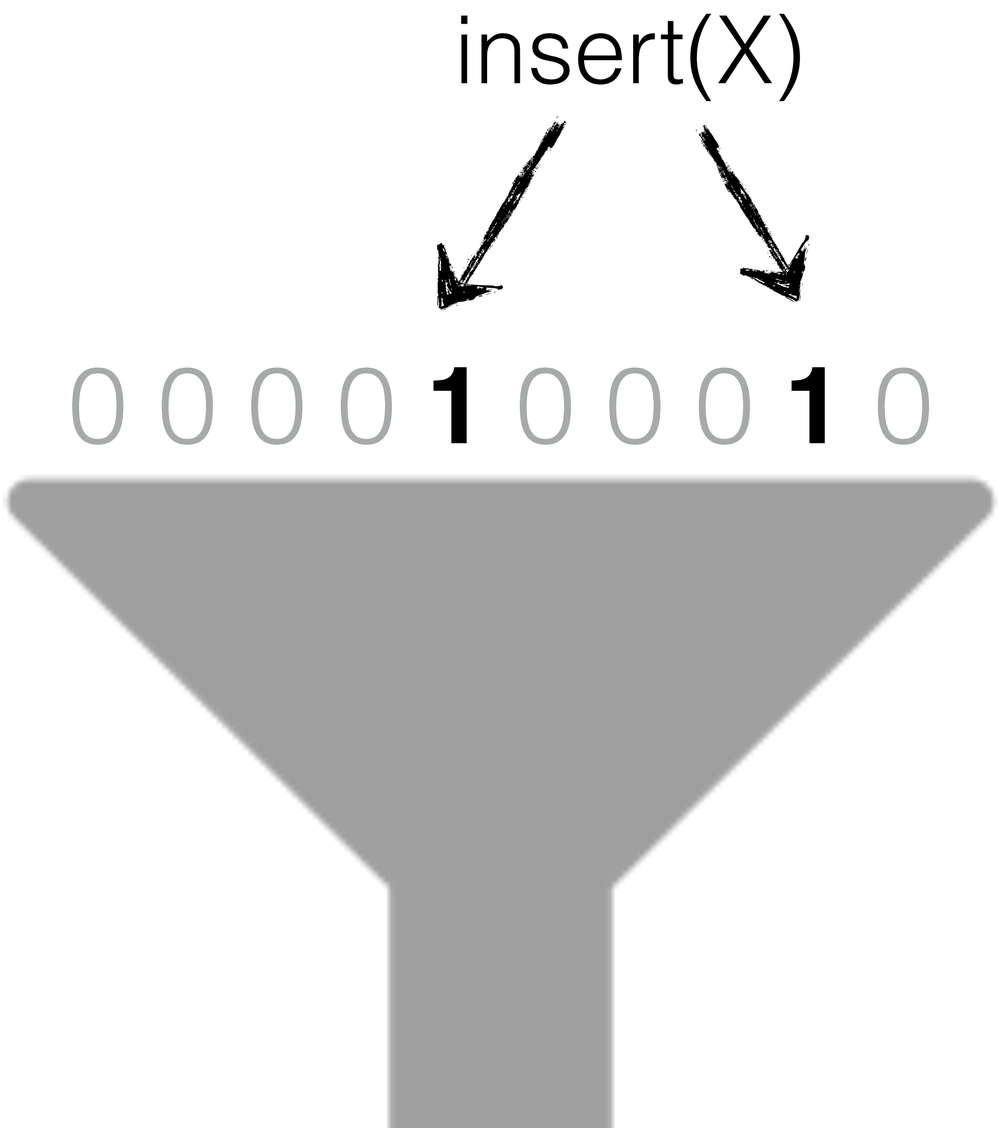
Bloom Filters

Space/time Trade-Offs in Hash Coding with Allowable Errors
Burton Howard Bloom. Communications of the ACM, 1970.

k hash functions



insert: Set from 0 to 1 or keep 1



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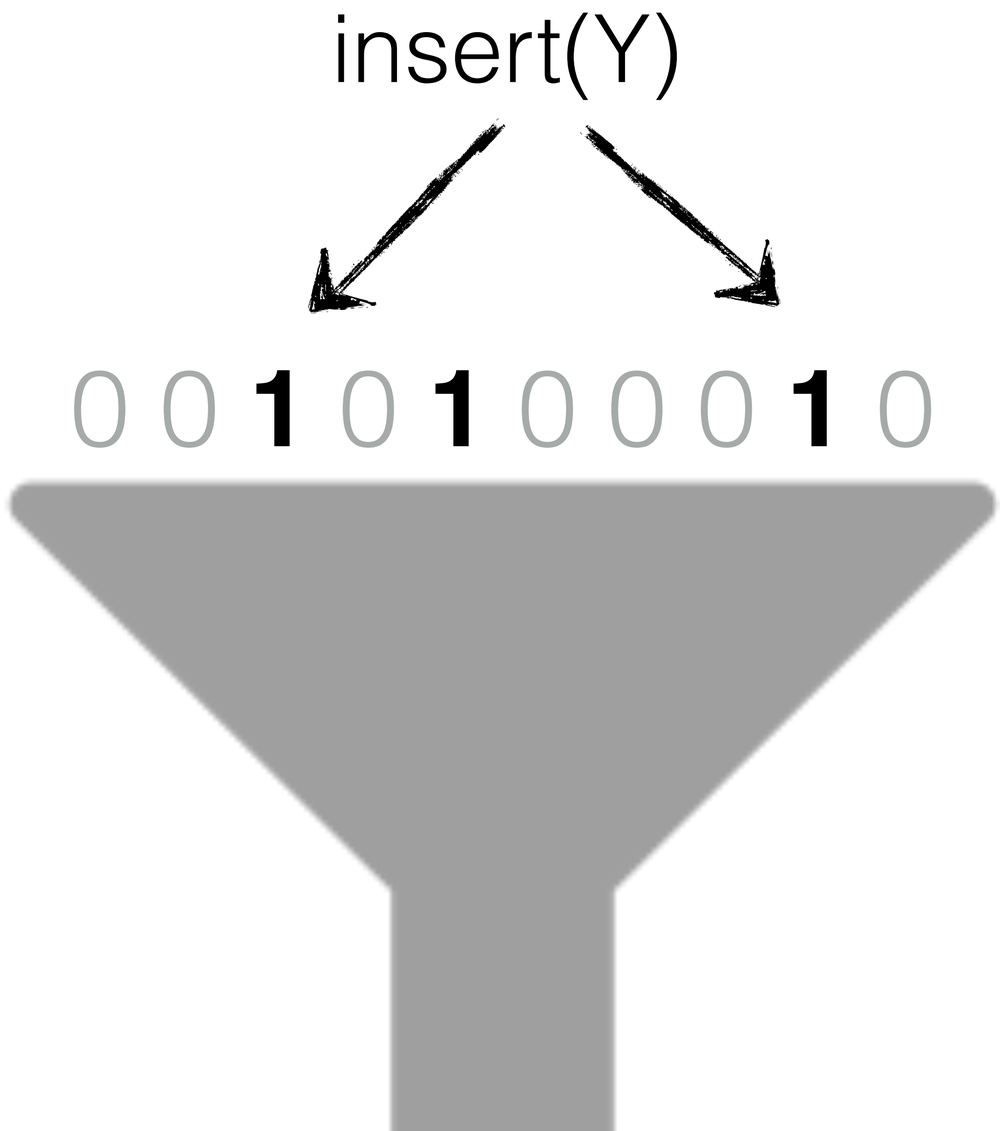
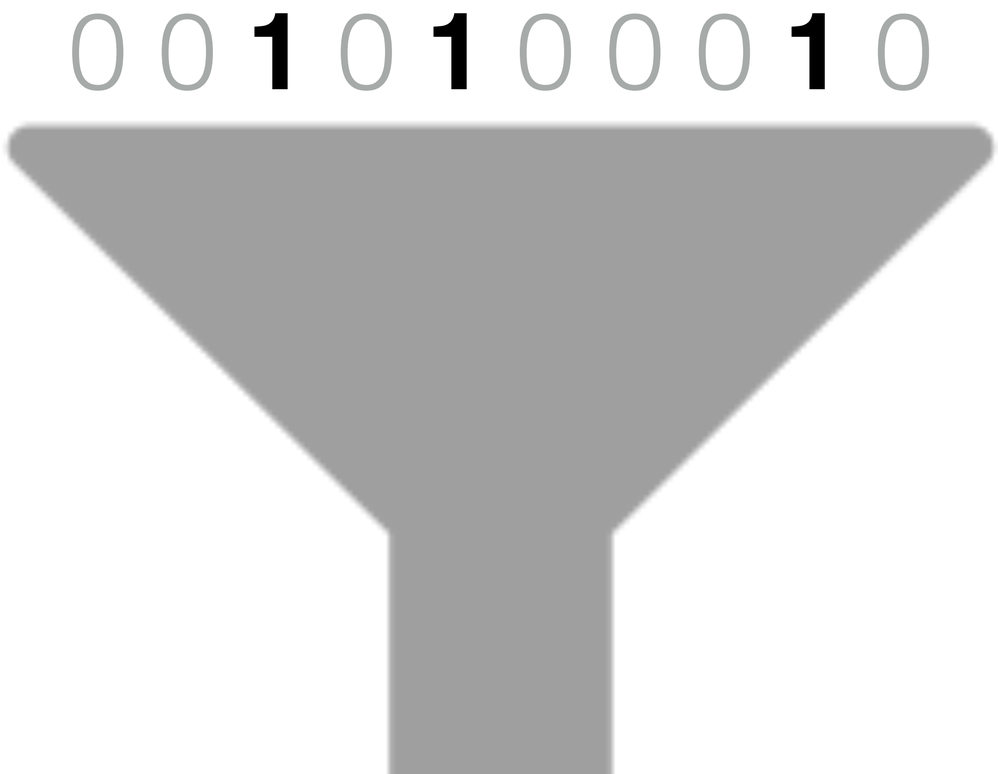


Queries: return positive if all hashed bits are 1s



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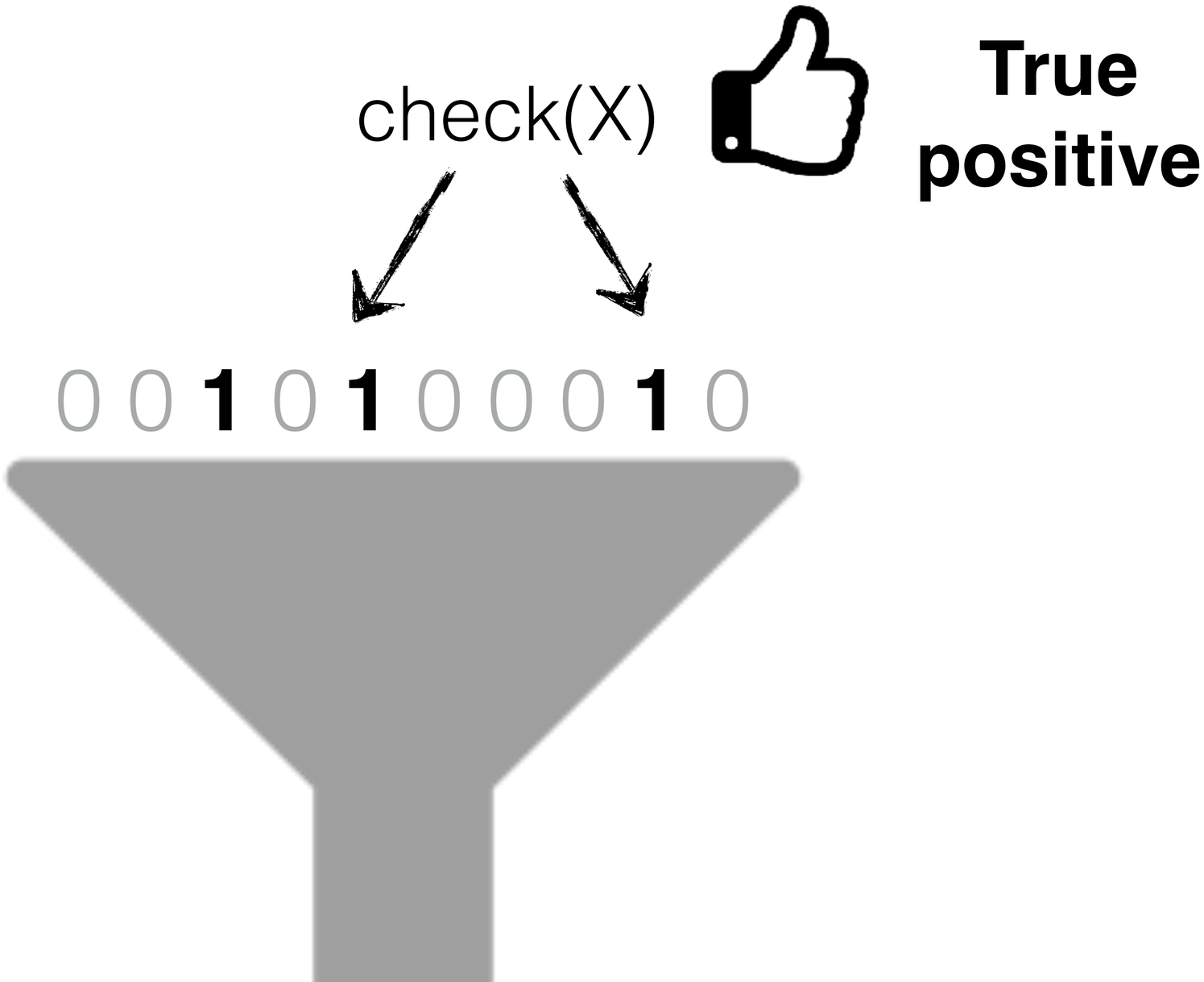

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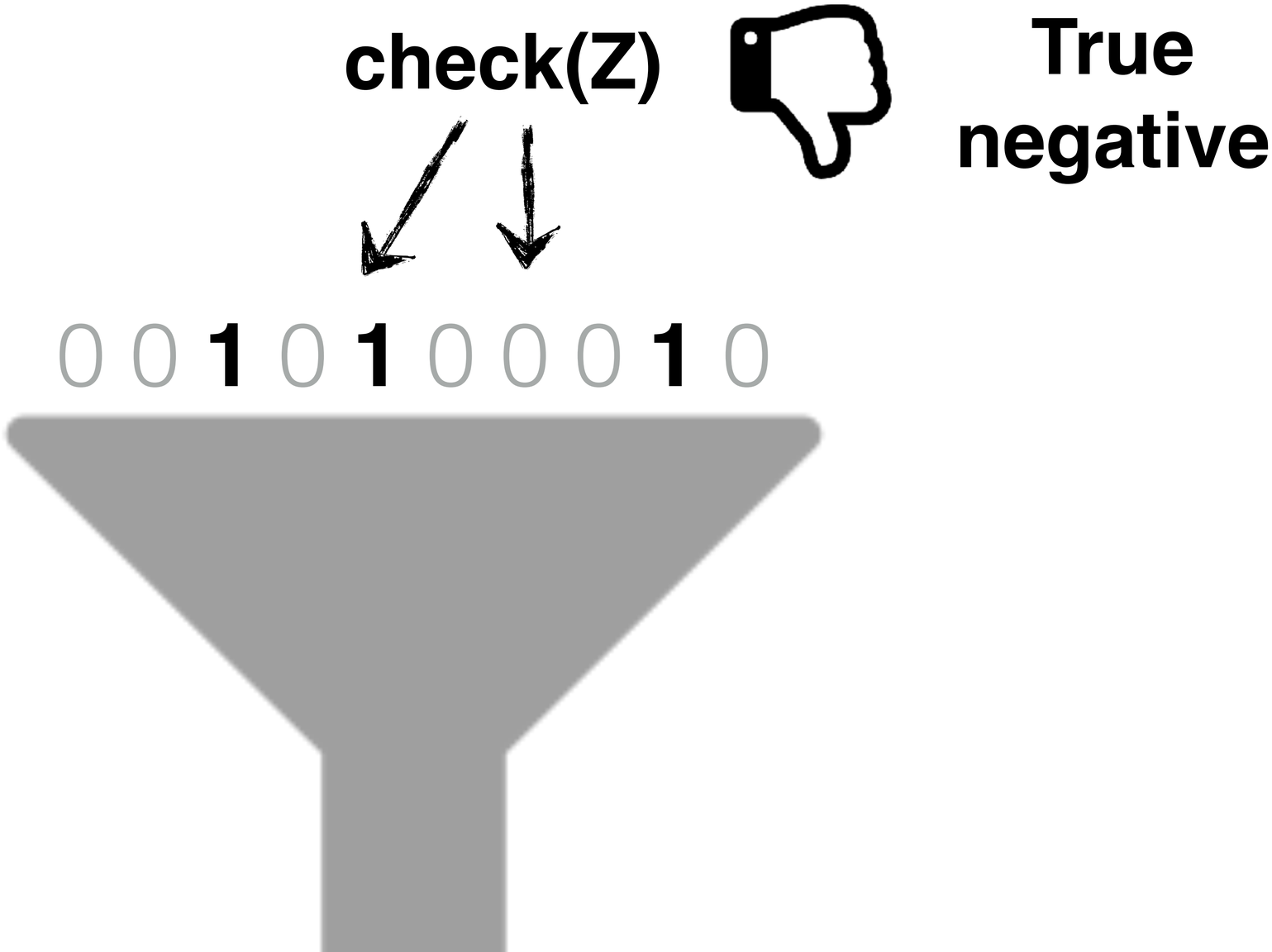

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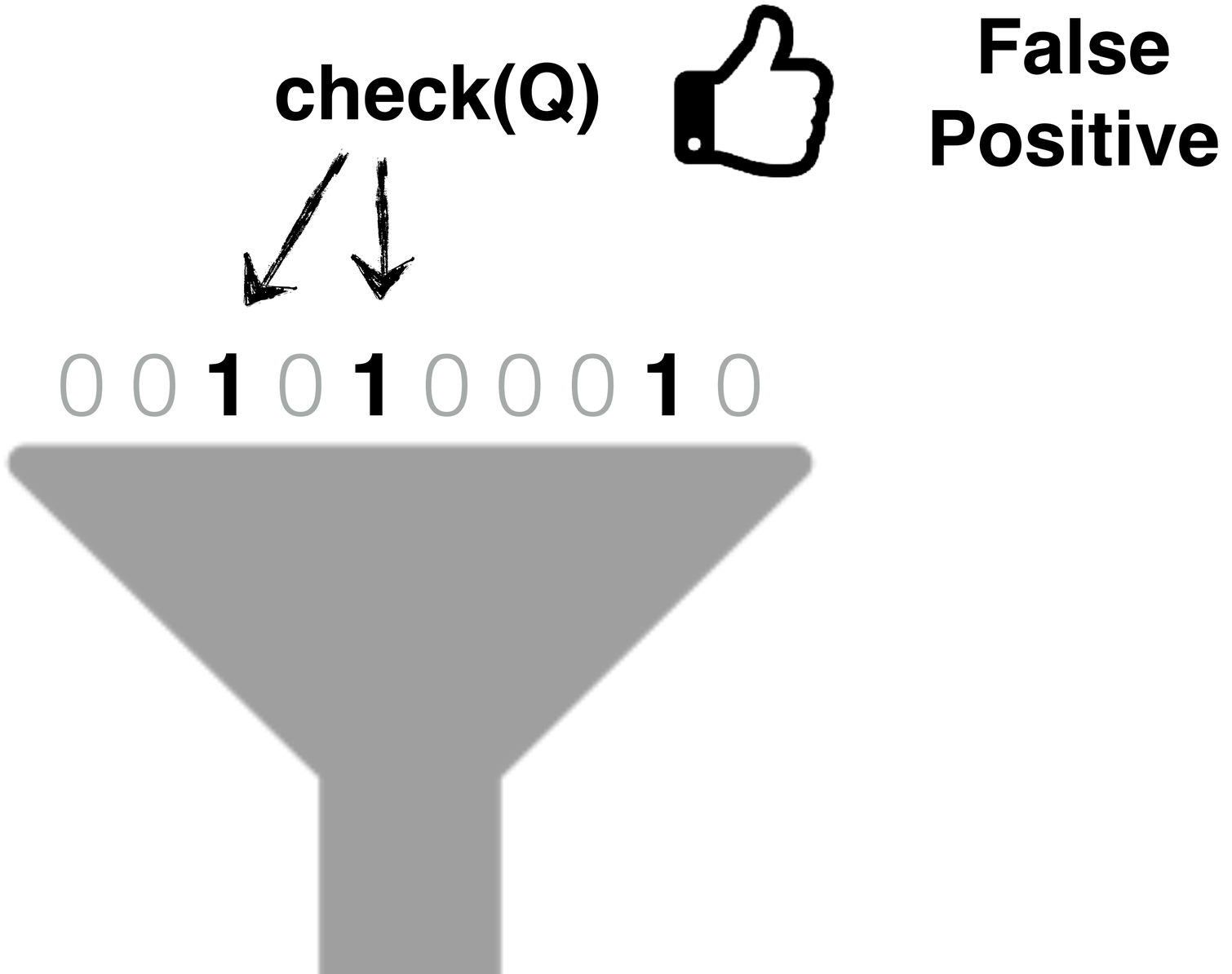
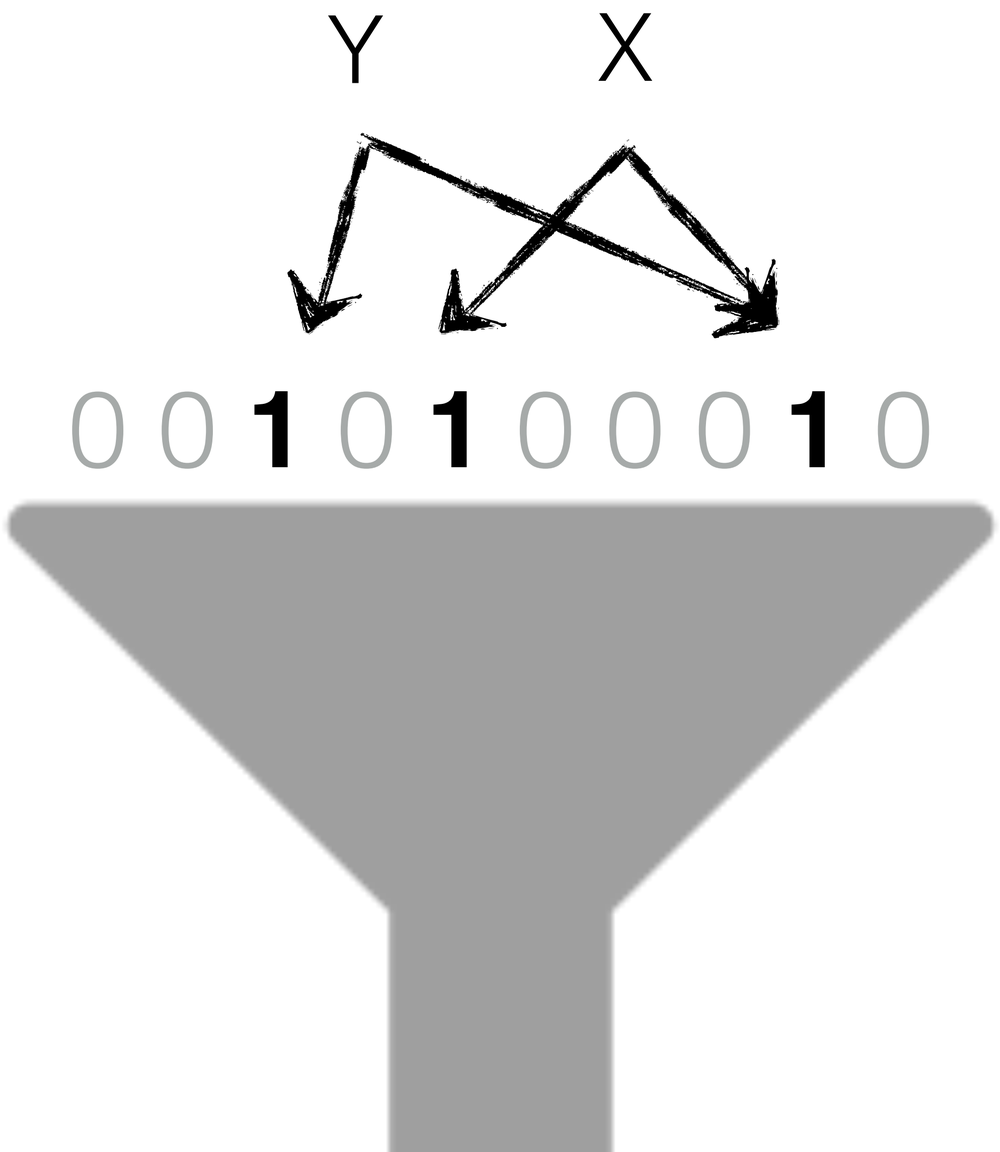
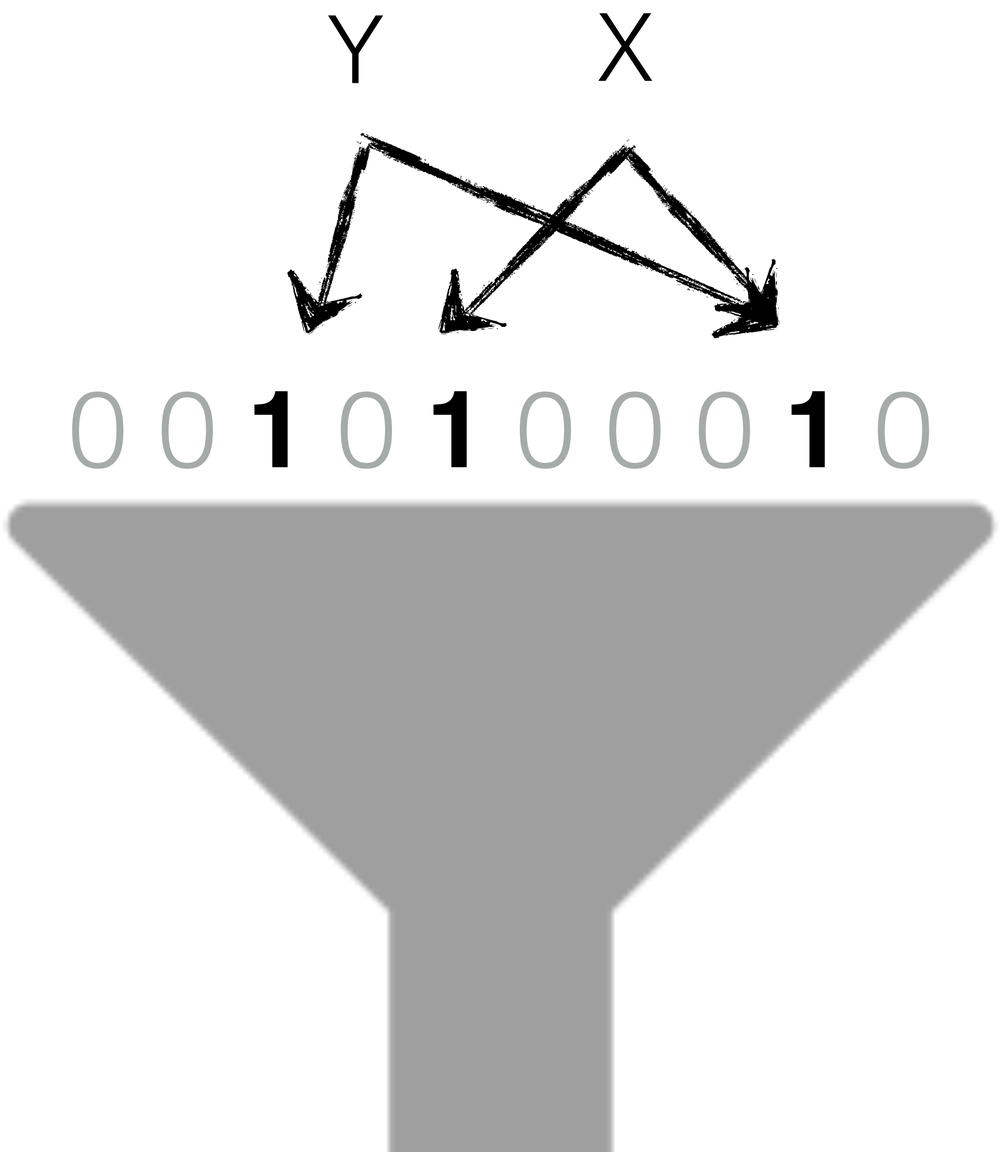


No deletes - can lead to false negatives



Thus, we consider it static



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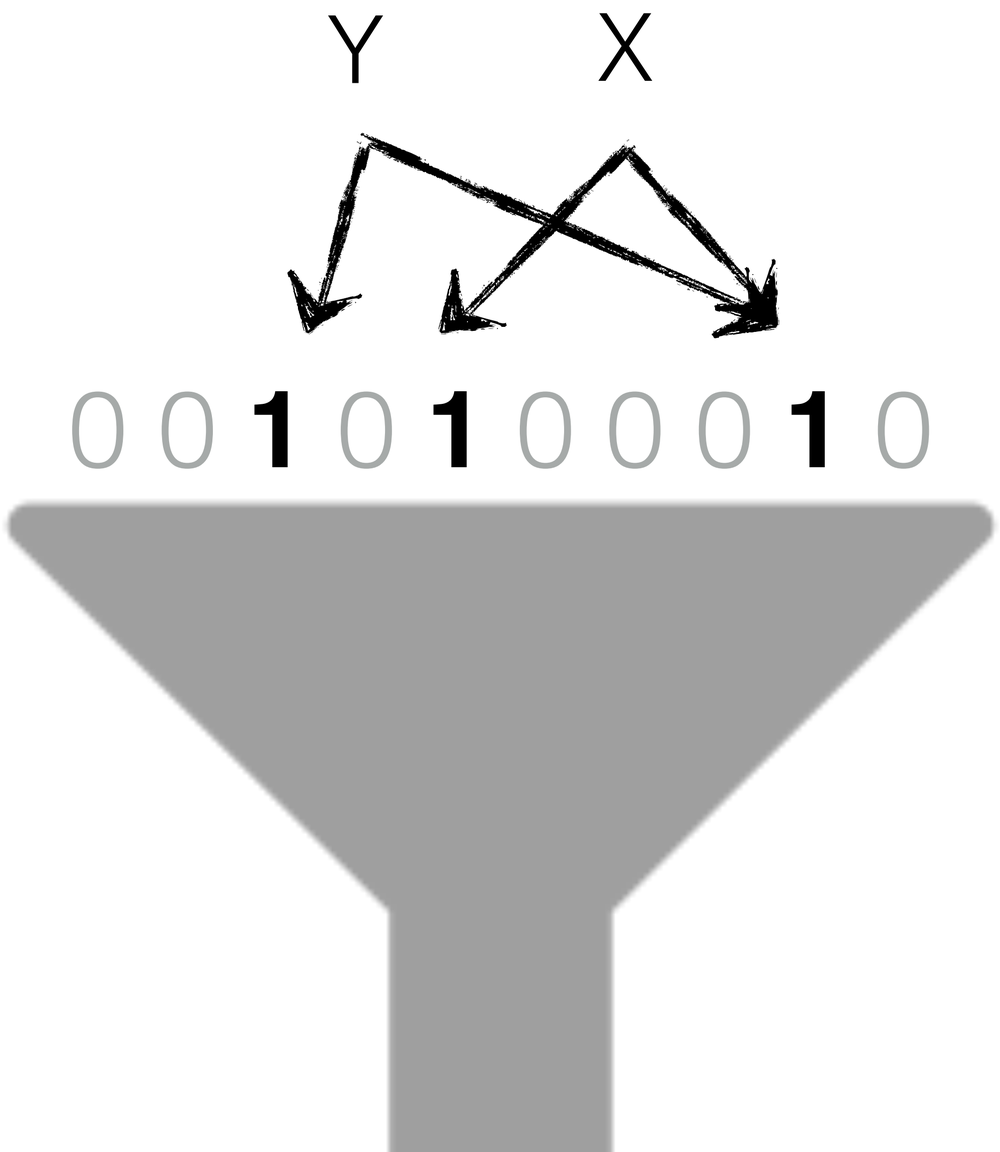

Construction contract

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Know specs in advance:

N - # entries to insert

ε - desired FPR

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Allocate filter with: $N \cdot \ln(2) \cdot \log_2(1/\varepsilon)$ bits

Construction contract

Know specs in advance:

N - # entries to insert

ε - desired FPR

Allocate filter with: $N \cdot \ln(2) \cdot \log_2(1/\varepsilon)$ bits

Insert N elements

Construction contract

Know specs in advance:

N - # entries to insert

ε - desired FPR

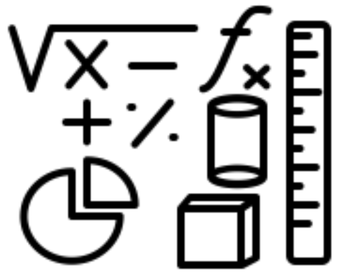
Allocate filter with: $N \cdot \ln(2) \cdot \log_2(1/\varepsilon)$ bits

Insert N elements

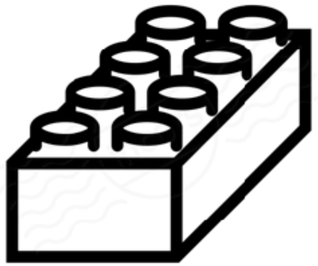
Guarantee FPR of ε

Bloom Filters

Analysis



Blocking



Sectorization

Analysis

In CSC443

Now: ground up

FPR Analysis

Network Applications of Bloom Filters: A Survey

Andrei Broder and Michael Mitzenmacher.
Allerton Conference, 2002

FPR Analysis

M: Total number of bits

N: Total number of keys

K: # hash functions

FPR Analysis

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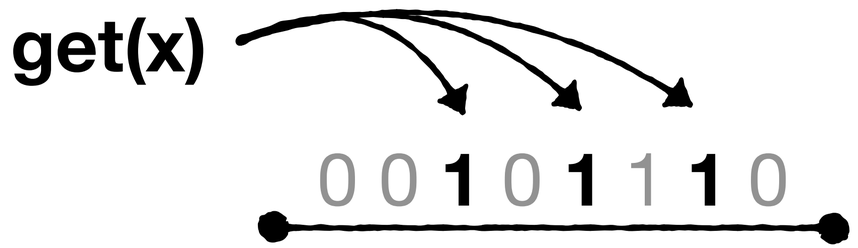
Probability that all k bits for a non-existing key are set?



FPR Analysis

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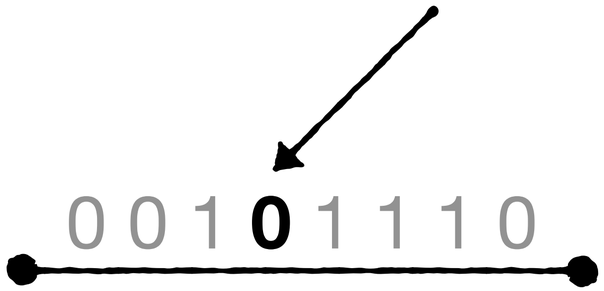
Probability that all k bits for a non-existing key are set?

↓

Probability that some random bit is still not set after N insertions?



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Probability that some random bit is still not set after 1 insertion?

FPR Analysis

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↓

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↓

Probability that some random bit is set after 1 hash function?

1/M

FPR Analysis

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↓

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↓

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↓

Probability that some random bit is **not** set after 1 hash function?

1-1/M

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↓

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$$\left(1-1/M \right)^{K}$$

FPR Analysis

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$$(1-1/M)^{KN}$$

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$$(1-1/M)^{KN}$$

Known identity: $\mathbf{(1-1/M)^{M} = e^{-1}}$ For any M

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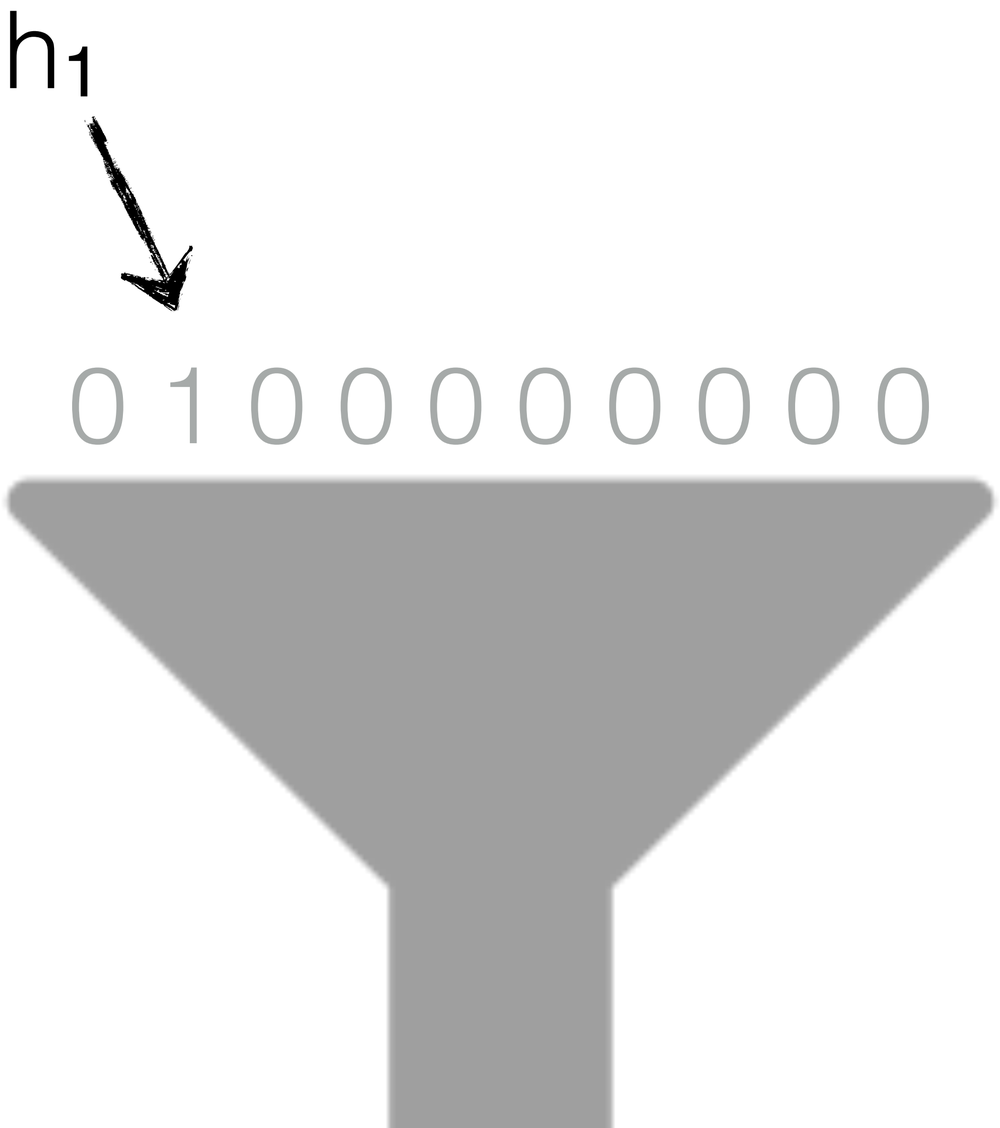
Probability that all k bits for a non-existing key are set?

$$(1-e^{-KN/M})^K$$

How many hash functions should we use?



One is too few: false positive occurs whenever we hit a 1

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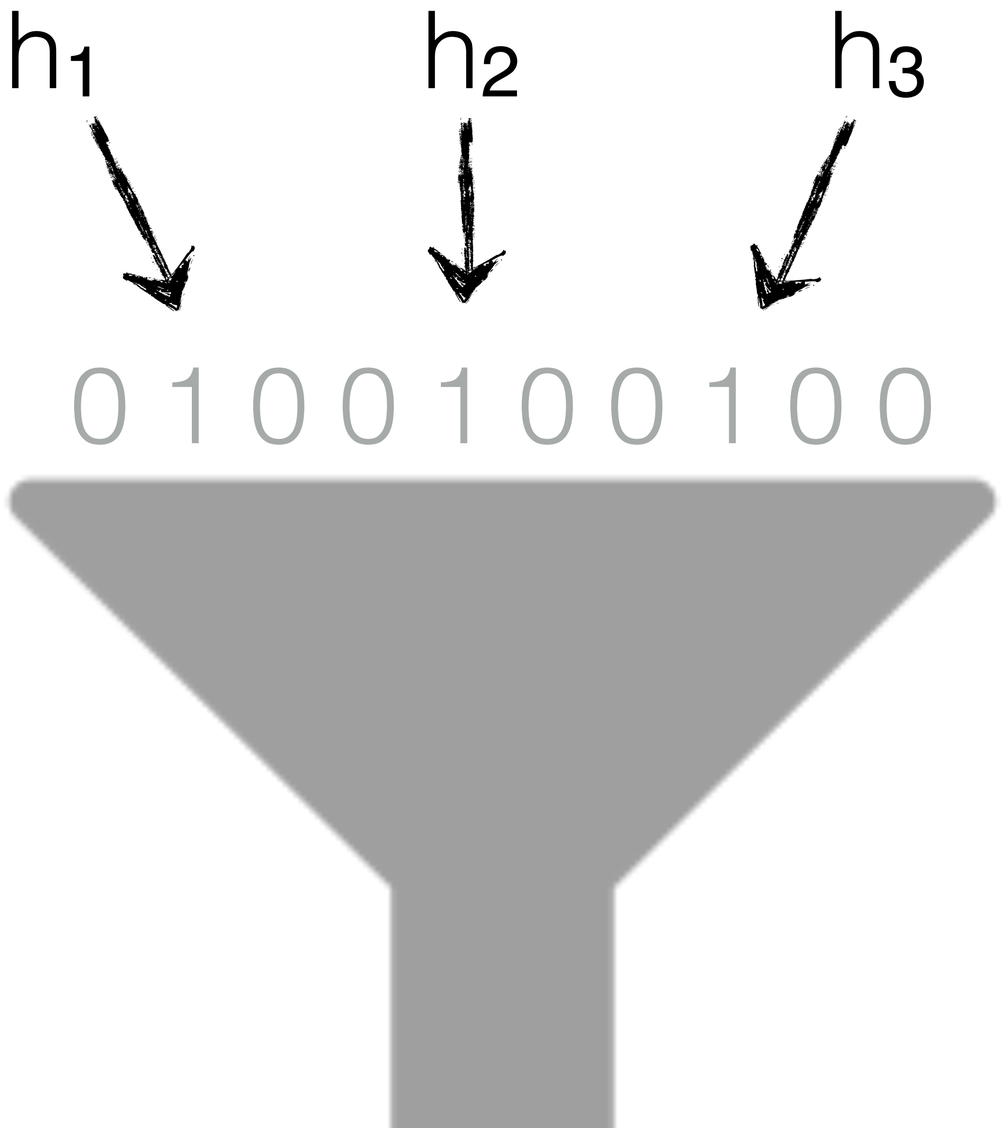

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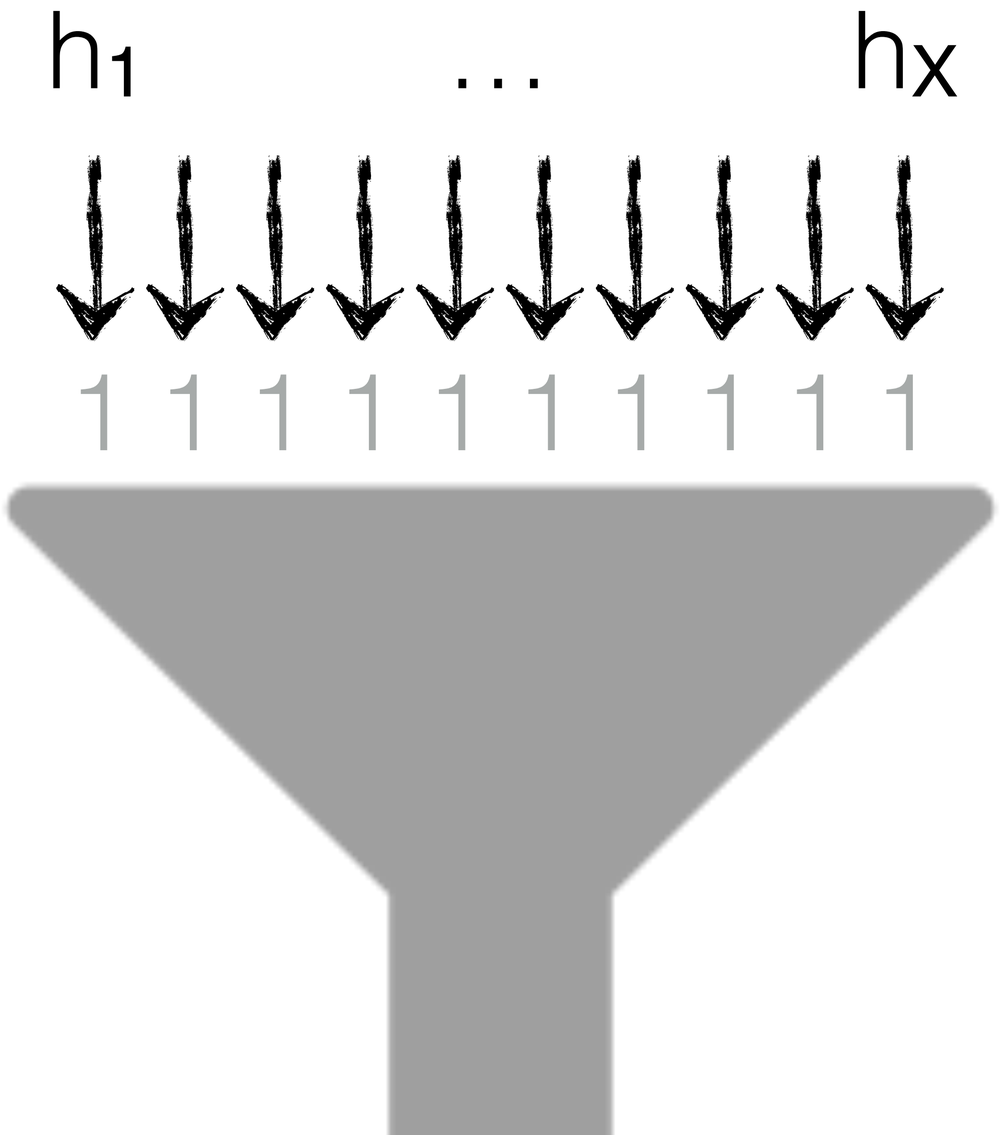
By adding hash functions, we initially decrease the false positive rate (FPR).

How many hash functions should we use?

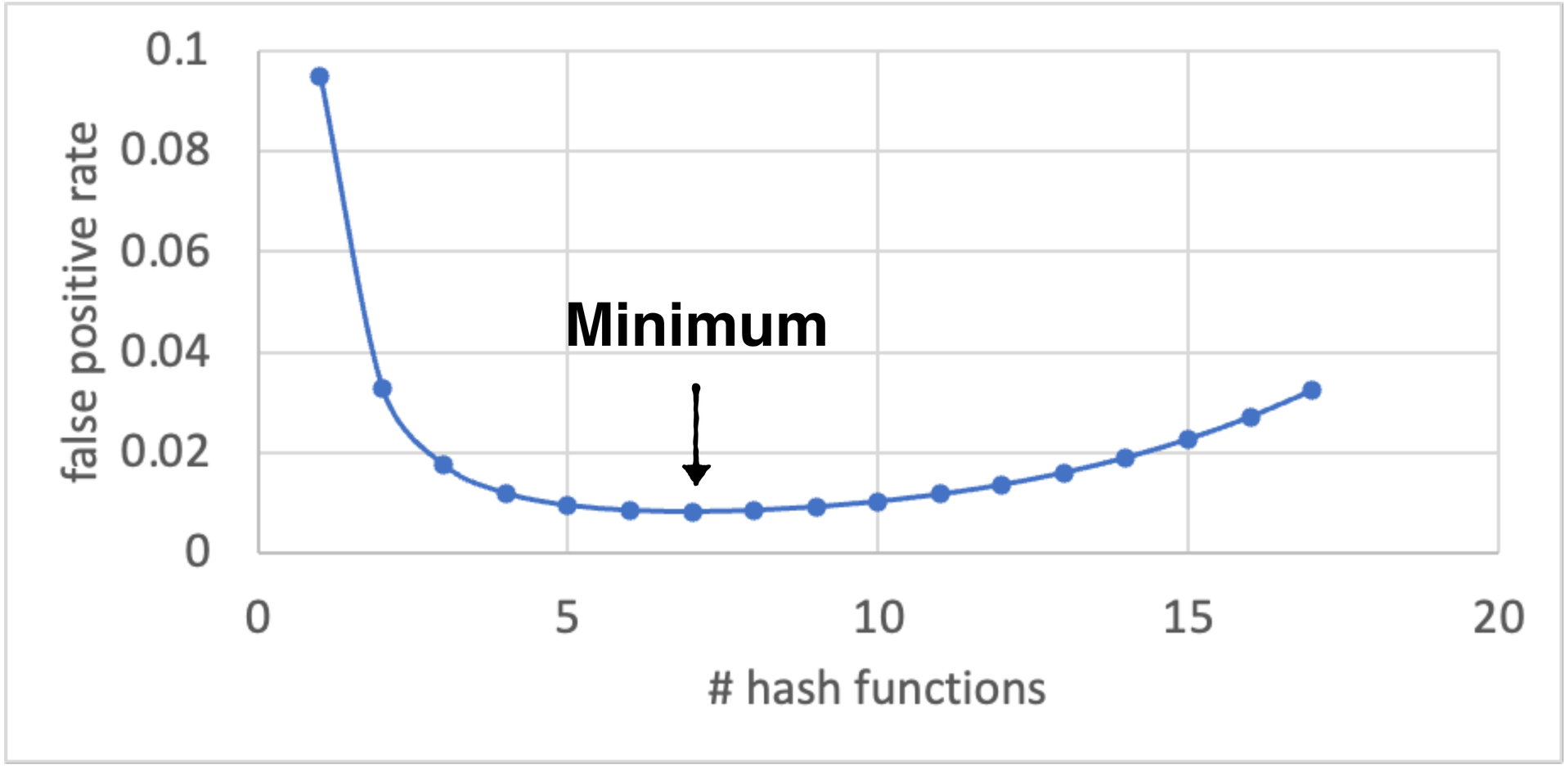


One is too few: false positive occurs whenever we hit a 1

By adding hash functions, we initially decrease the false positive rate (FPR).

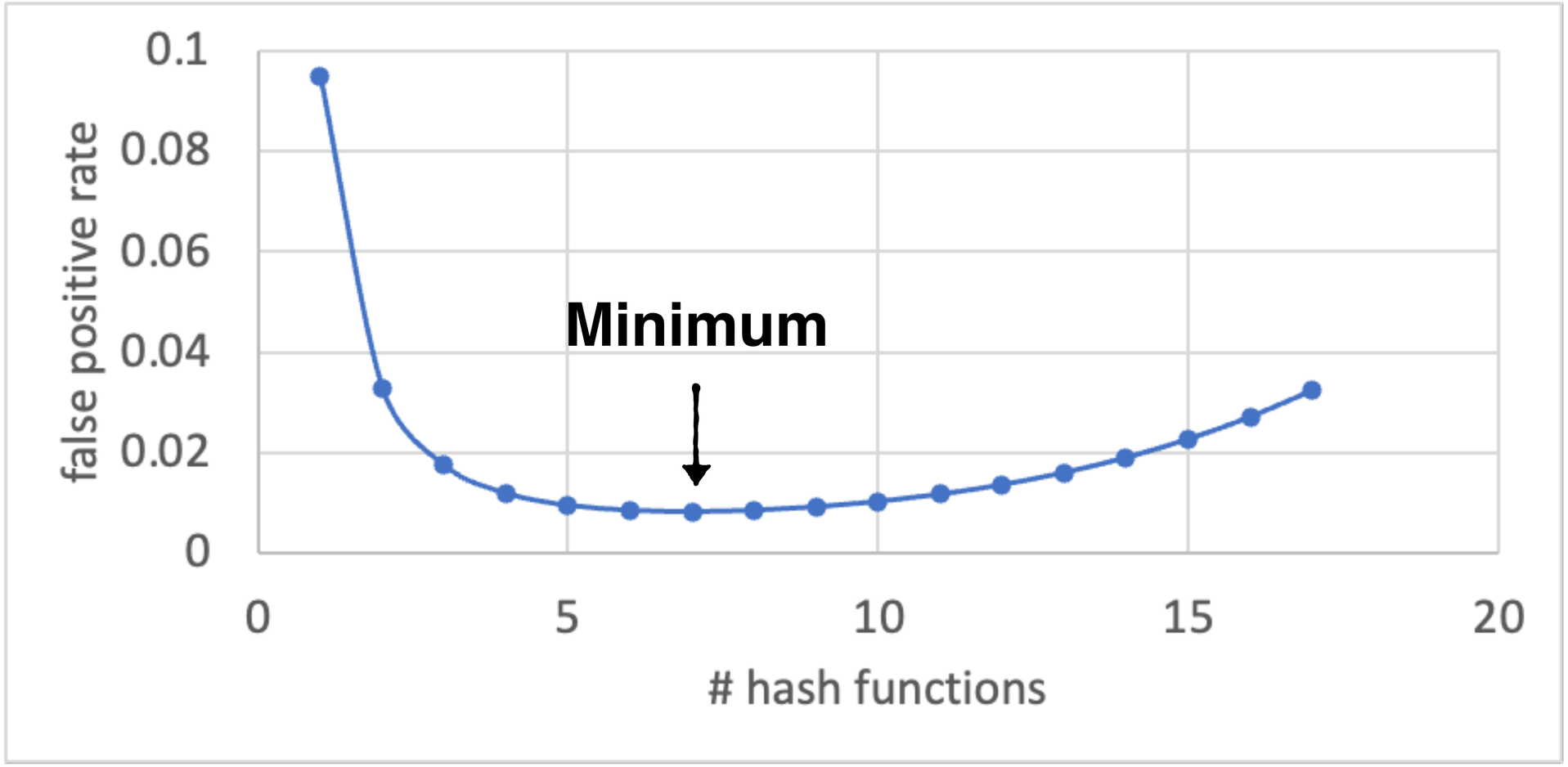
But too many hash functions wind up increasing the FPR.

How many hash functions should we use?



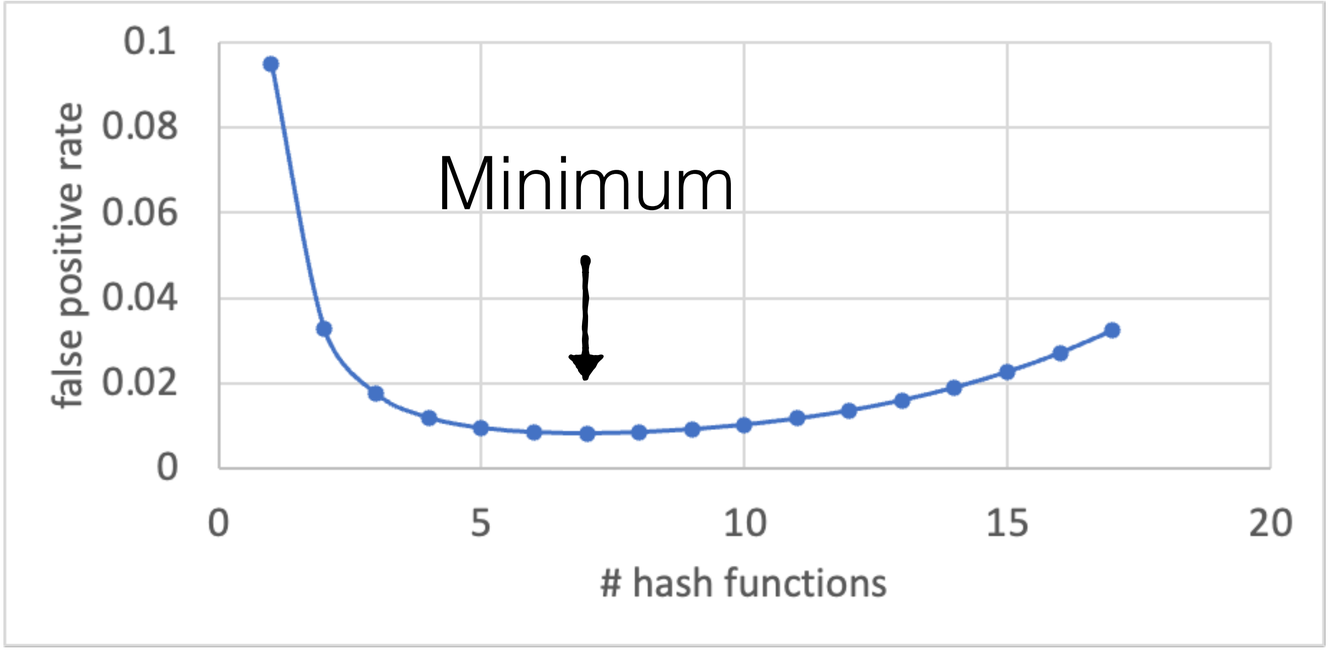
(Drawn for a filter using 10 bits per entry)

How many hash functions should we use?



Differentiate $(1-e^{-KN/M})^K$ with respect to K

How many hash functions should we use?



Differentiate $(1-e^{-KN/M})^K$ with respect to K

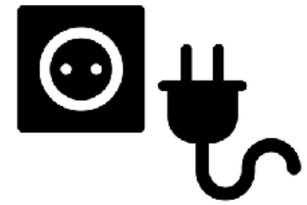
Optimal # hash functions k = ln(2) · *M/N*

(e.g. with Wolfram Alpha)

Optimal # hash functions $\mathbf{k = \ln(2) \cdot M/N}$

False positives rate

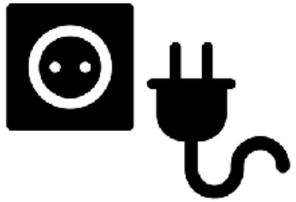
$\mathbf{(1-e^{-KN/M})^K}$



Optimal # hash functions $\mathbf{k = \ln(2) \cdot M/N}$

False positives rate

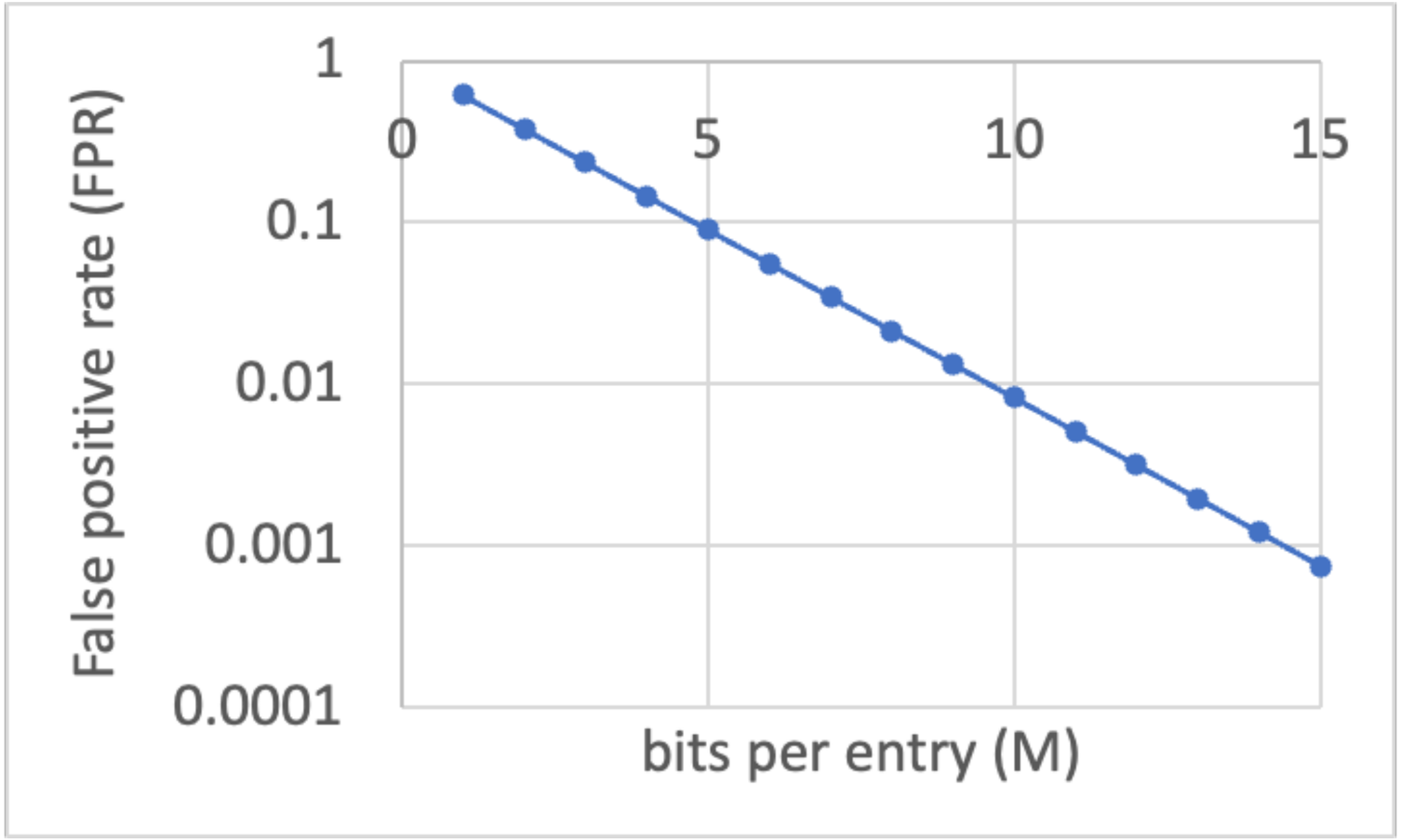
$\mathbf{(1-e^{-KN/M})^K}$



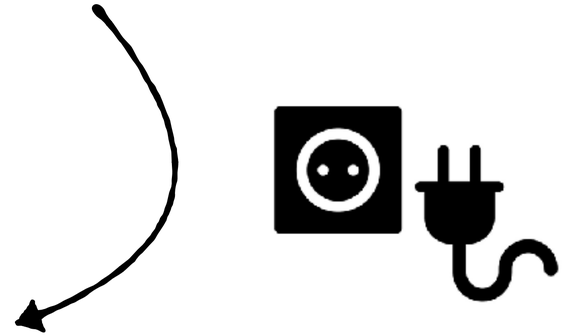
$\mathbf{2^{-M/N \cdot \ln(2)}}$

assuming the optimal # hash functions,

false positive rate = $2^{-M/N \cdot \ln(2)}$



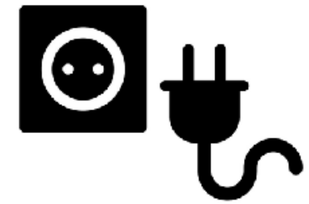
Optimal # hash functions **k = ln(2) · *M/N***



Some bit is not set

$e^{-KN/M}$

Optimal # hash functions k = ln(2) · *M/N*

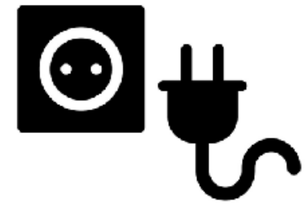


Some bit is not set

e-KN/M

0.5

Optimal # hash functions k = ln(2) · *M/N*



Some bit is not set

$e^{-KN/M}$

0.5

50% of all bits are zero once the filter is full

Operation Costs (in hash functions computed)

Insertion =

Positive Query =

Negative Query =

Operation Costs (in hash functions computed)

Insertion = $\mathbf{M/N \cdot \ln(2)}$

Positive Query =

Negative Query =

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

Positive Query = **$M/N \cdot \ln(2)$**

Negative Query =

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

Positive Query = $M/N \cdot \ln(2)$

Negative Query =

(50% of bits are zeros)

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

Positive Query = $M/N \cdot \ln(2)$

Avg. Negative Query = $1 + 1/2\,(1 + 1/2 \cdot (\ \ldots\ ))$

(50% of bits are zeros)

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

Positive Query = $M/N \cdot \ln(2)$

Avg. Negative Query = $1 + 1/2 + 1/4 + \ldots$ **= 2**

(50% of bits are zeros)

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

Positive Query = $M/N \cdot \ln(2)$

Avg. Negative Query = 2

Full analysis from ground up :)

Operation Costs (in hash functions computed)

Insertion = $M/N \cdot \ln(2)$

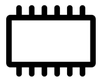
Positive Query = $M/N \cdot \ln(2)$

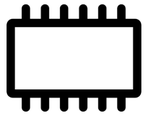
Avg. Negative Query = 2

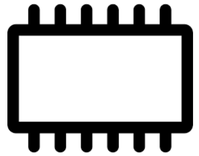
Is this ok for modern hardware?

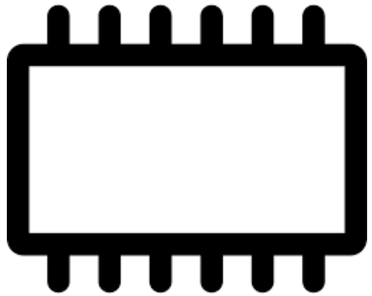
Recall the memory hierarchy

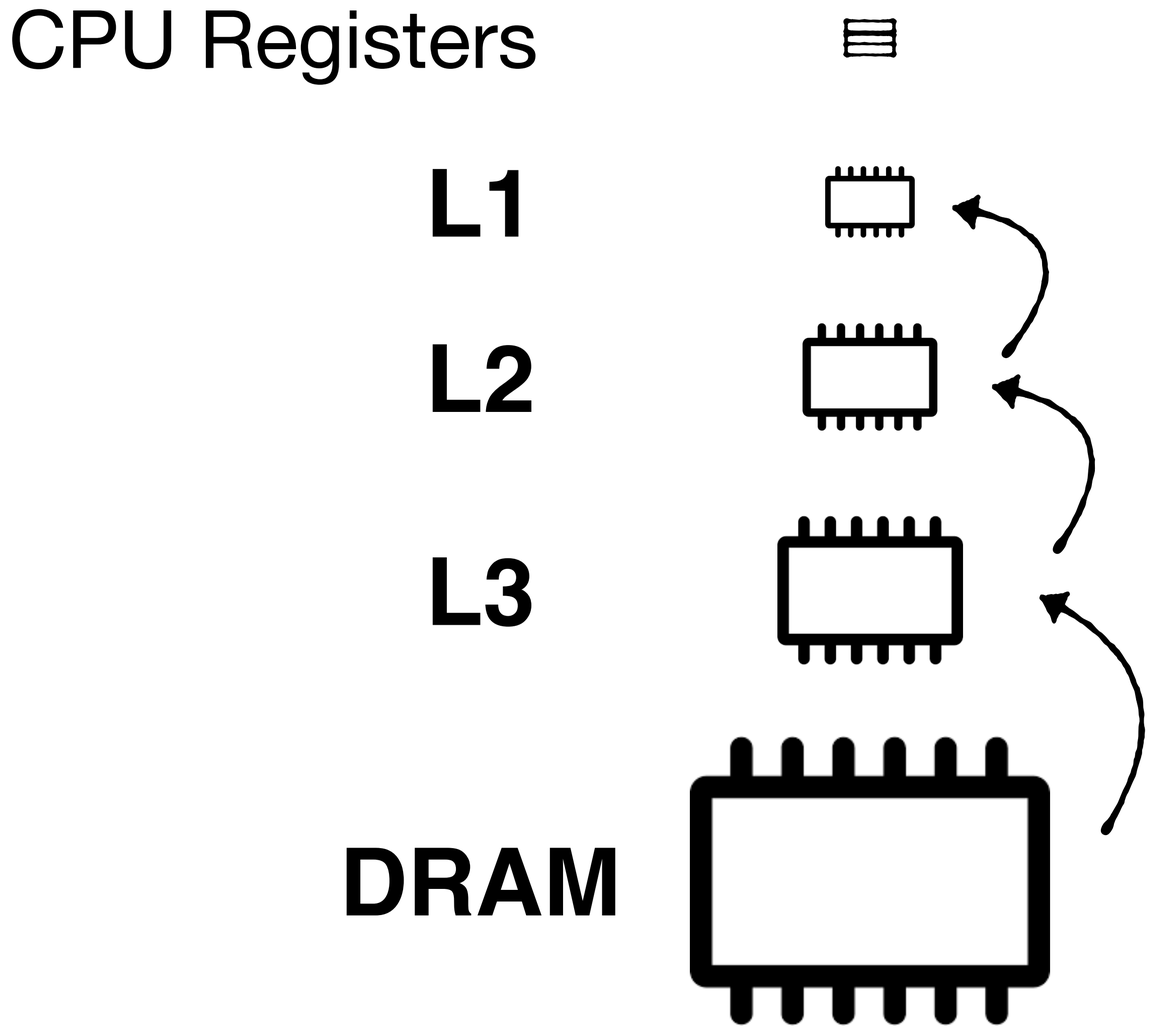
CPU Registers 

L1 

L2 

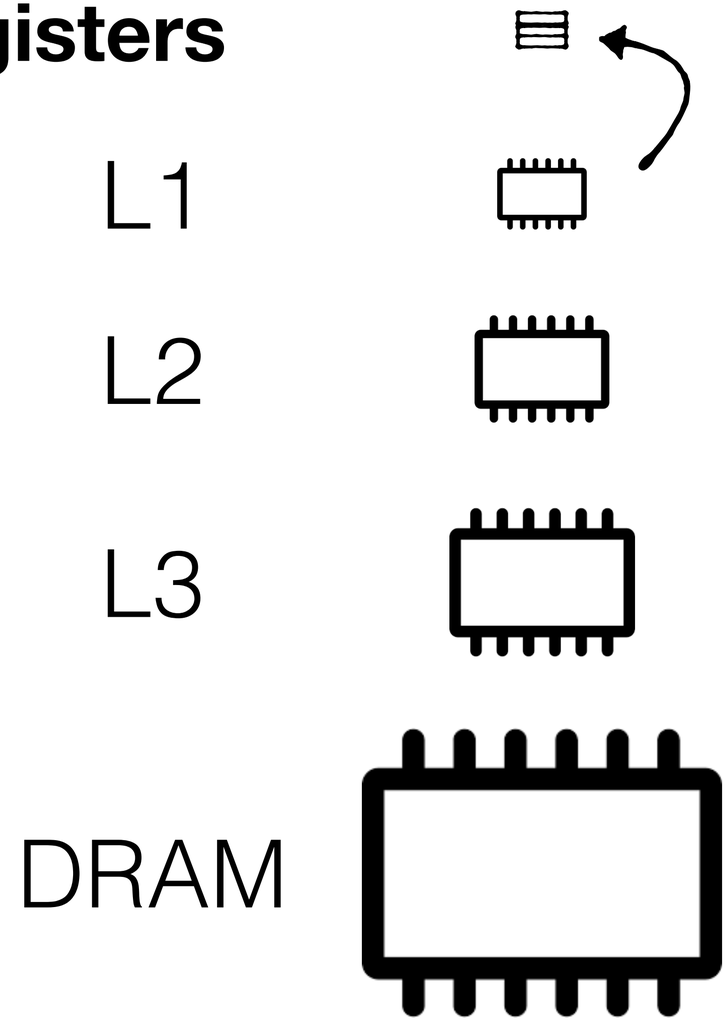
L3 

DRAM 

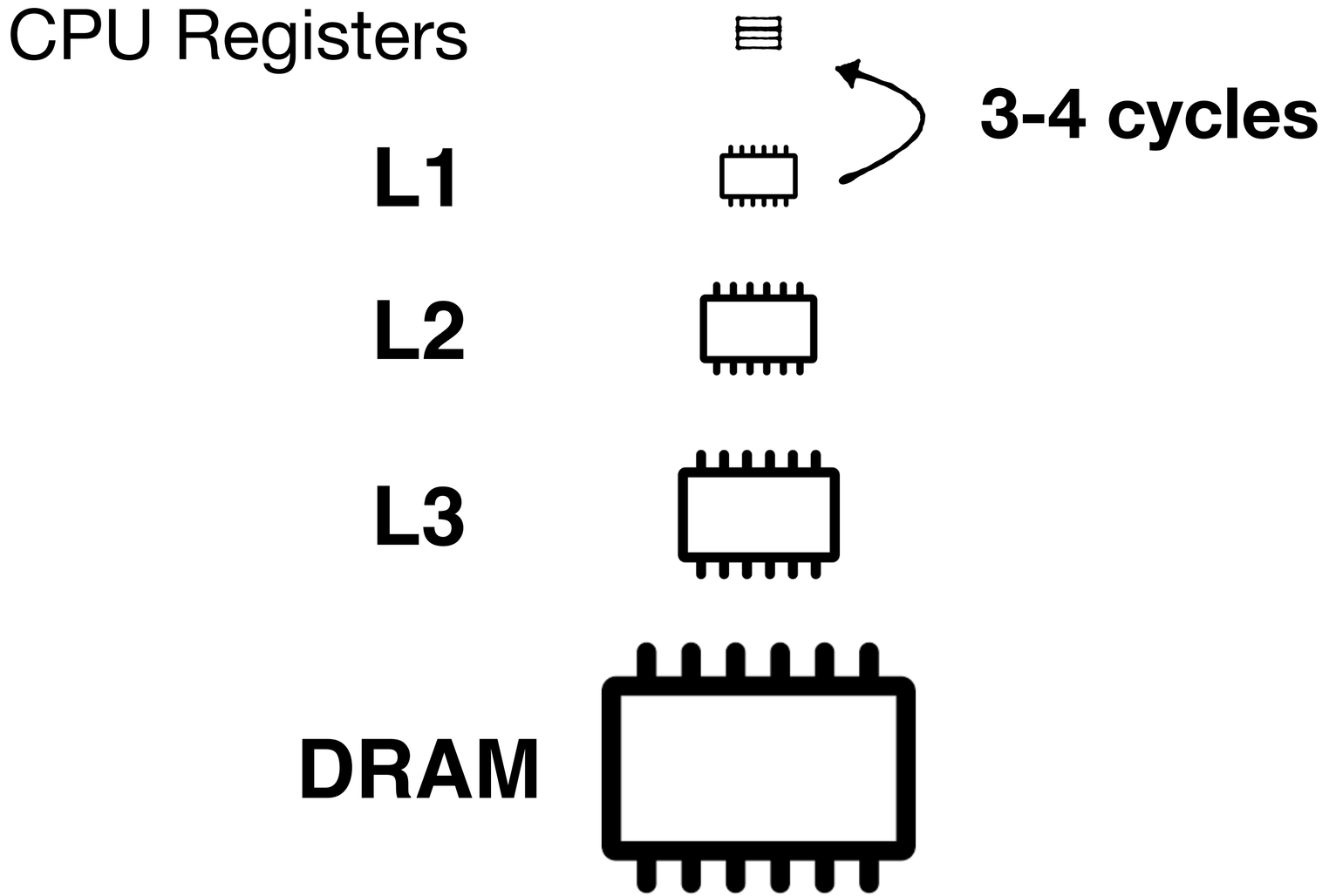


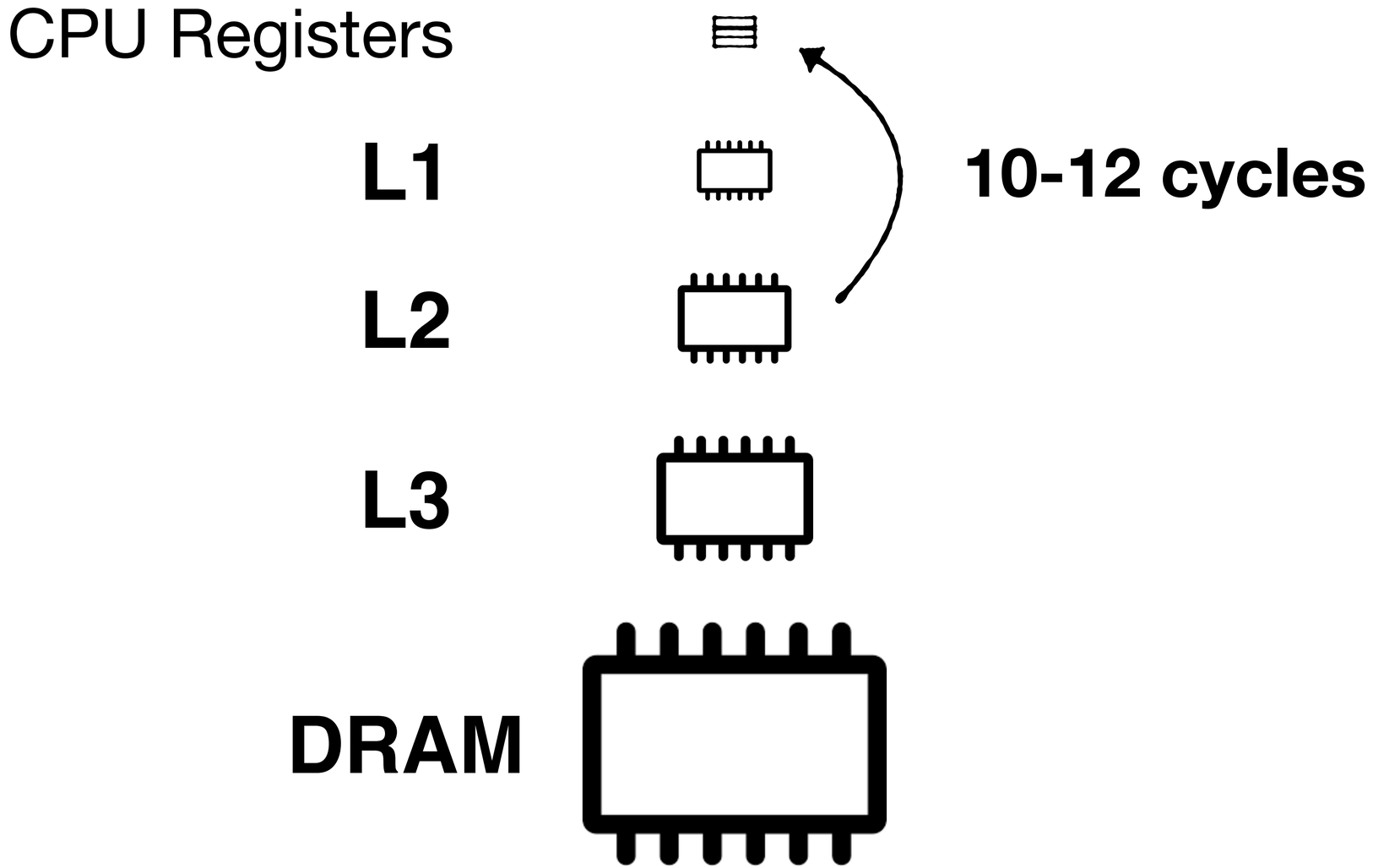
Move data at “cache line” granularity (e.g., 64B)

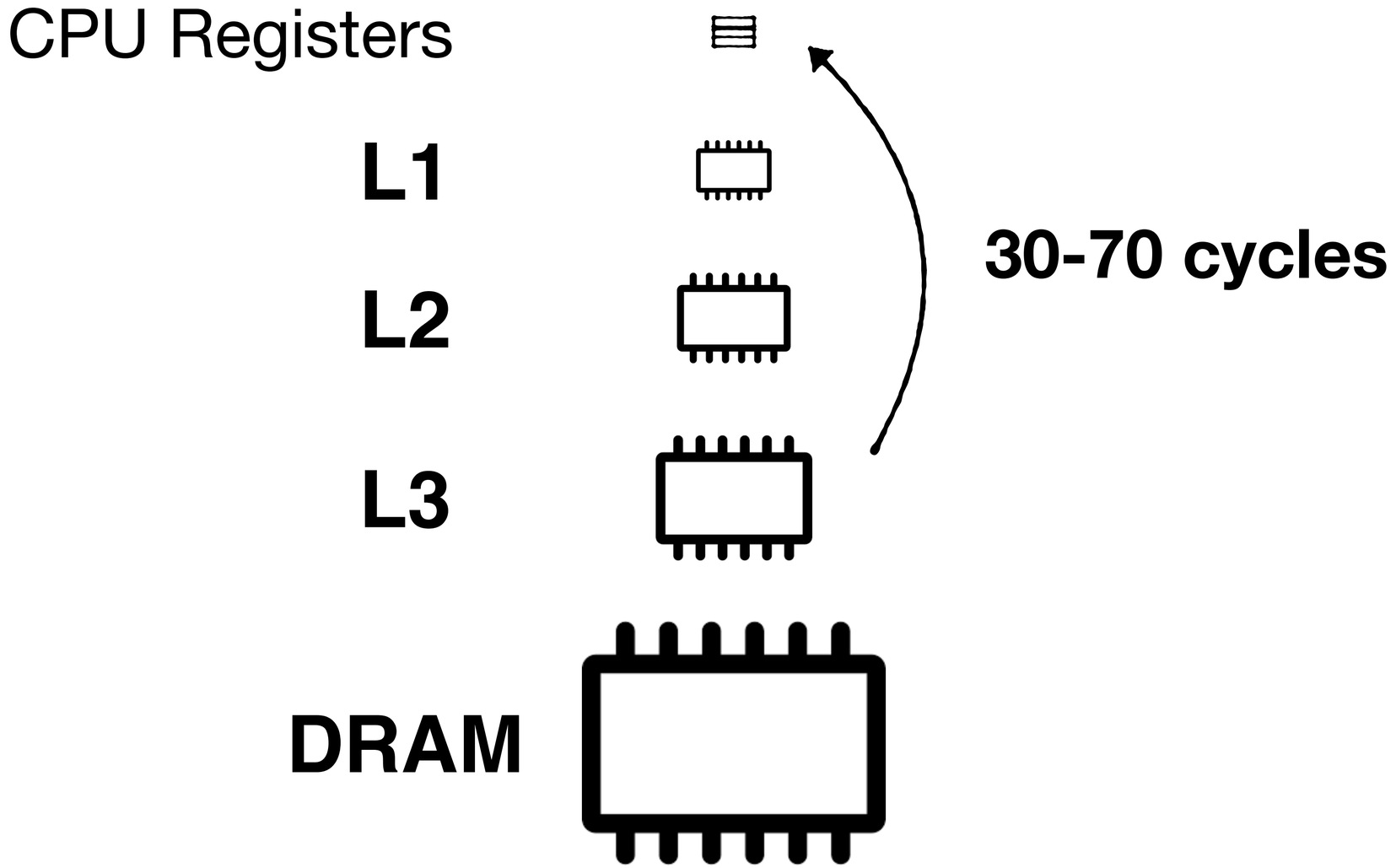
CPU Registers

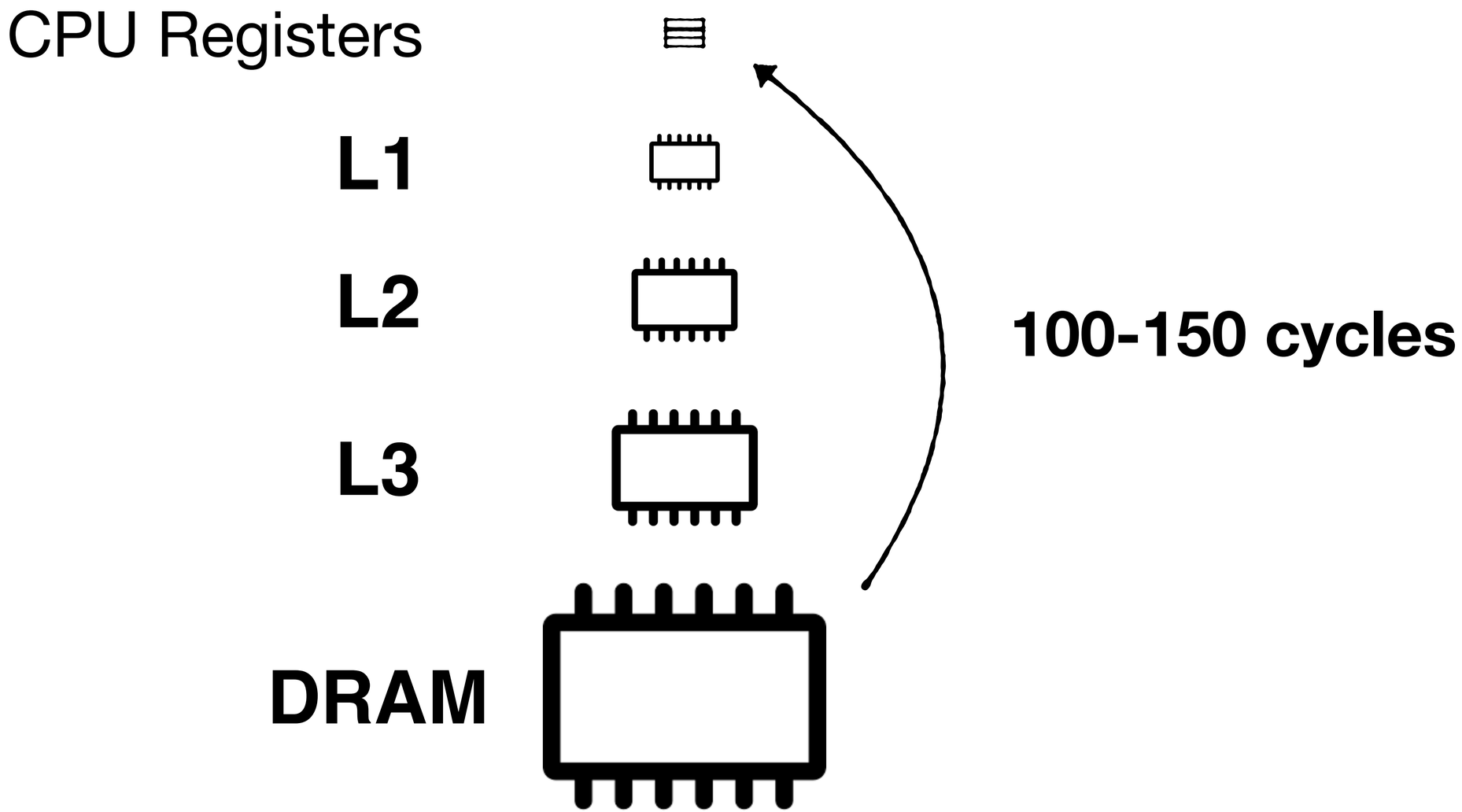


Move data at “word” granularity (e.g., 8B)


CPU Registers
L1
3-4 cycles
L2
L3
DRAM


CPU Registers
L1
L2
L3
DRAM
10-12 cycles

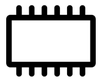

CPU Registers
L1
L2
L3
DRAM
30-70 cycles


CPU Registers
L1
L2
L3
DRAM
100-150 cycles

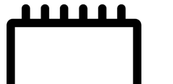
Source: http://ithare.com/infographics-operation-costs-in-cpu-clock-cycles/
(Numbers from **2016)**

CPU Registers

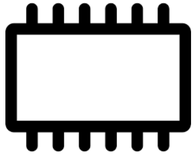
L1



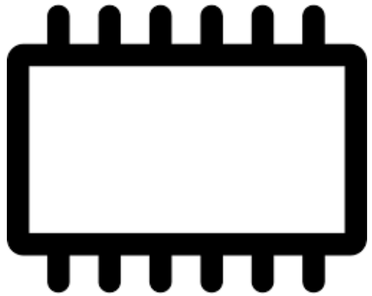
L2



L3



DRAM



Each hash function can lead to a cache miss

Insertion = $M/N \cdot \ln(2)$

Positive Query = $M/N \cdot \ln(2)$

Avg. Negative Query = 2

Each hash function can lead to a cache miss

Insertion = $\boldsymbol{M/N \cdot \ln(2) \cdot 100\ \text{ns}}$

Positive Query = $\boldsymbol{M/N \cdot \ln(2) \cdot 100\ \text{ns}}$

Avg. Negative Query = $\boldsymbol{2 \cdot 100\ \text{ns}}$

Observation

Basic Bloom filter is slowest filter

Observation

Basic Bloom filter is slowest filter

With hardware optimizations, it is the fastest

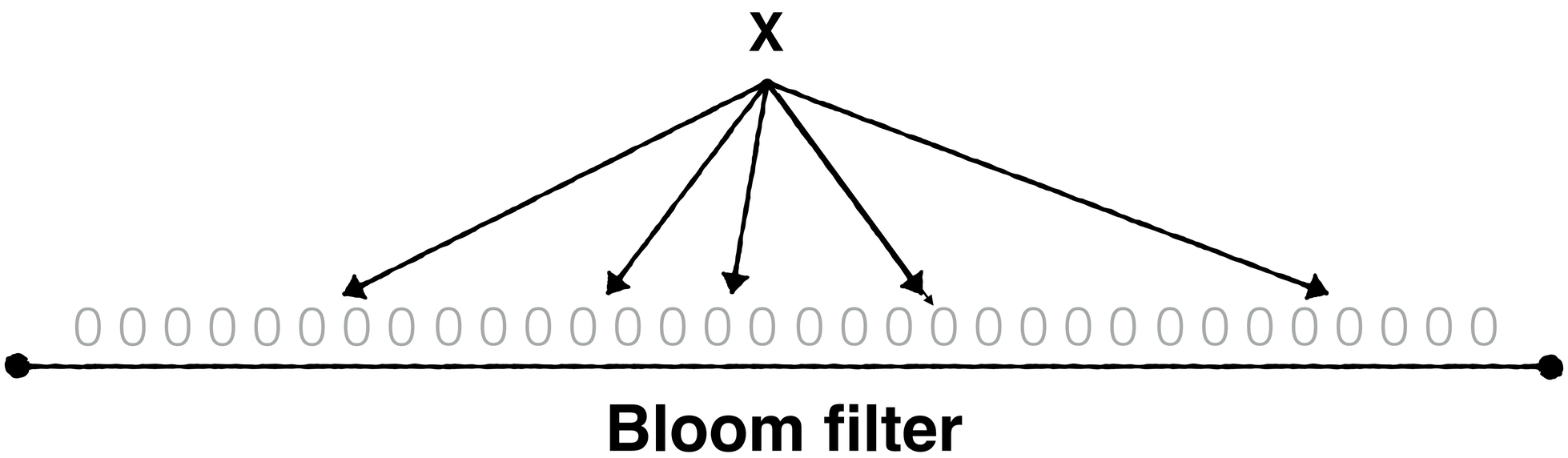
Observation

Basic Bloom filter
is slowest filter

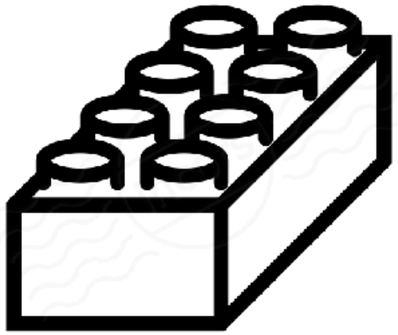
With hardware
optimizations, it is the
fastest

lends itself to hardware optimization

Alleviate random accesses?



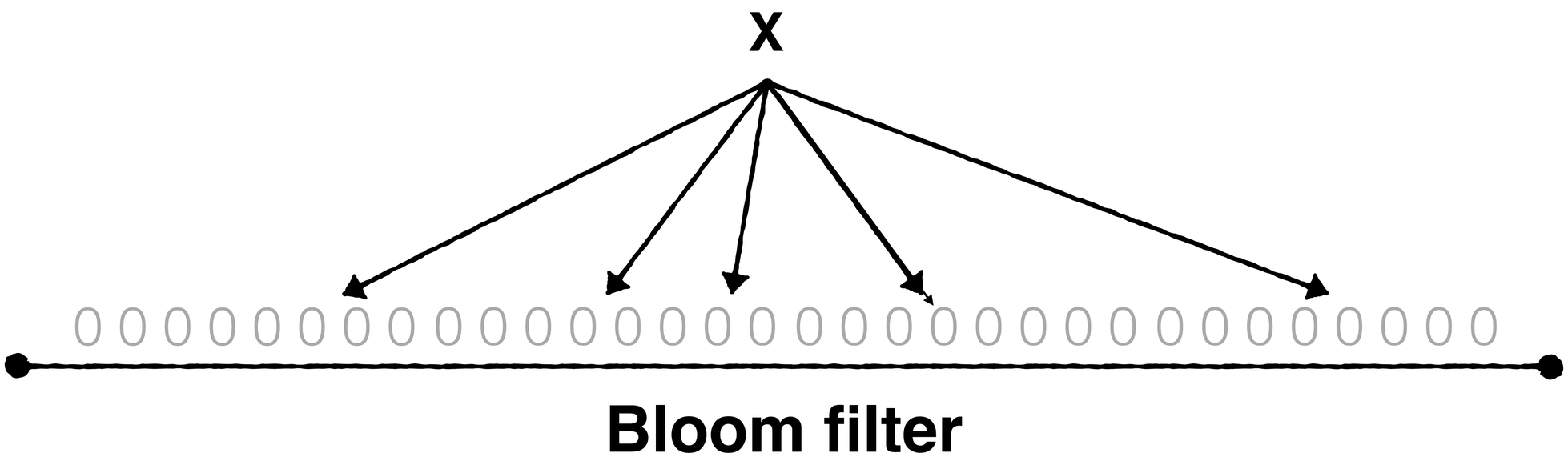
Blocked Bloom Filters



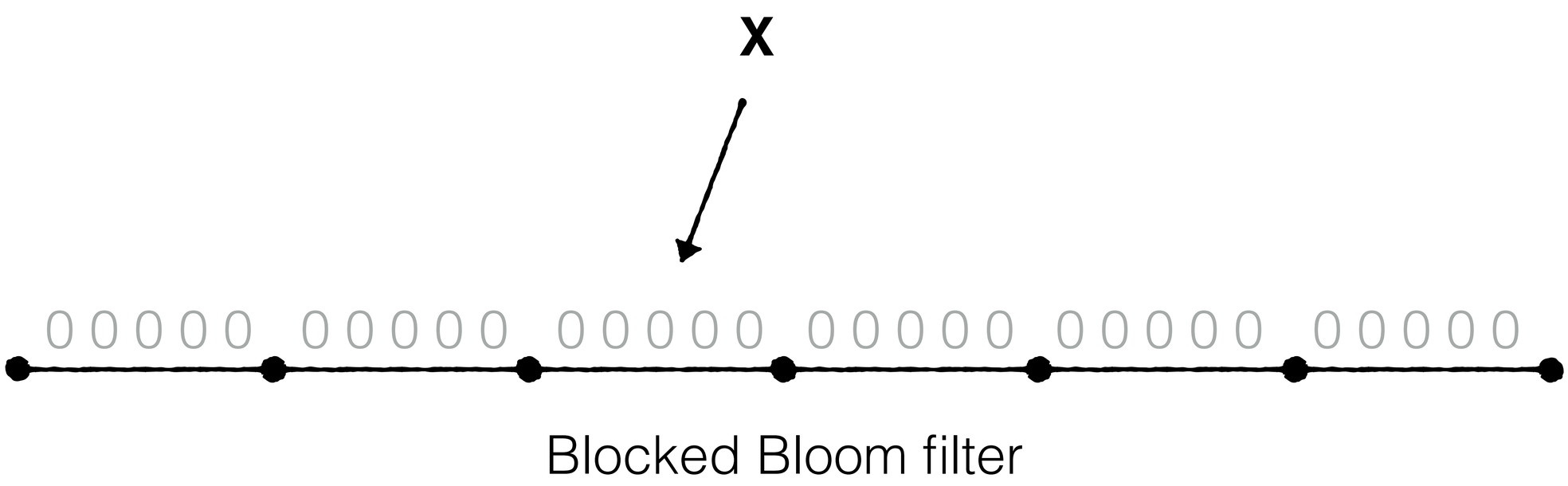
Cache-, Hash- and Space-Efficient Bloom Filters

Journal of Experimental Algorithms, 2010

Felix Putze, Peter Sanders, Johannes Singler

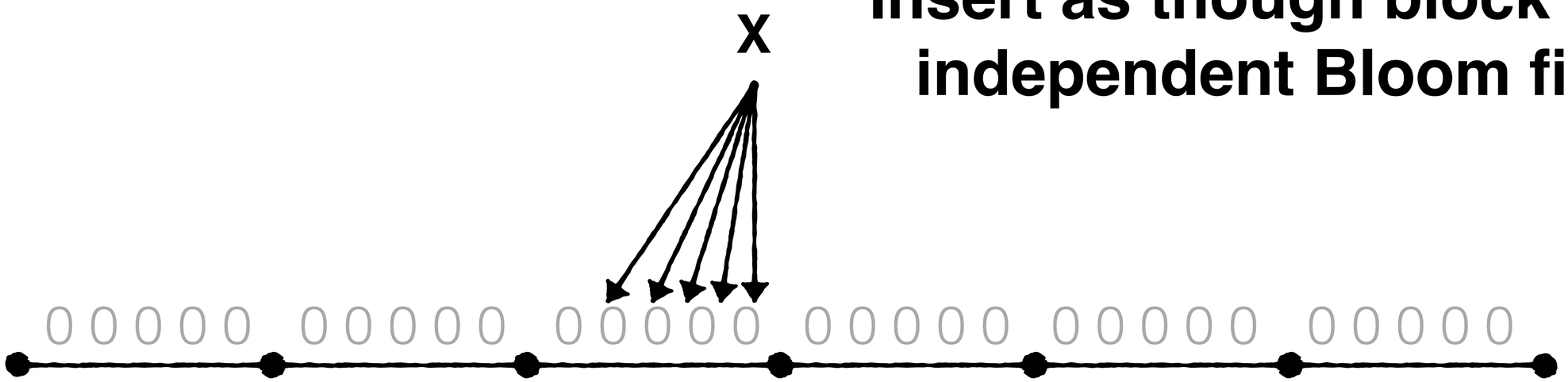

x
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Bloom filter

Hash to one block, sized as a cache line



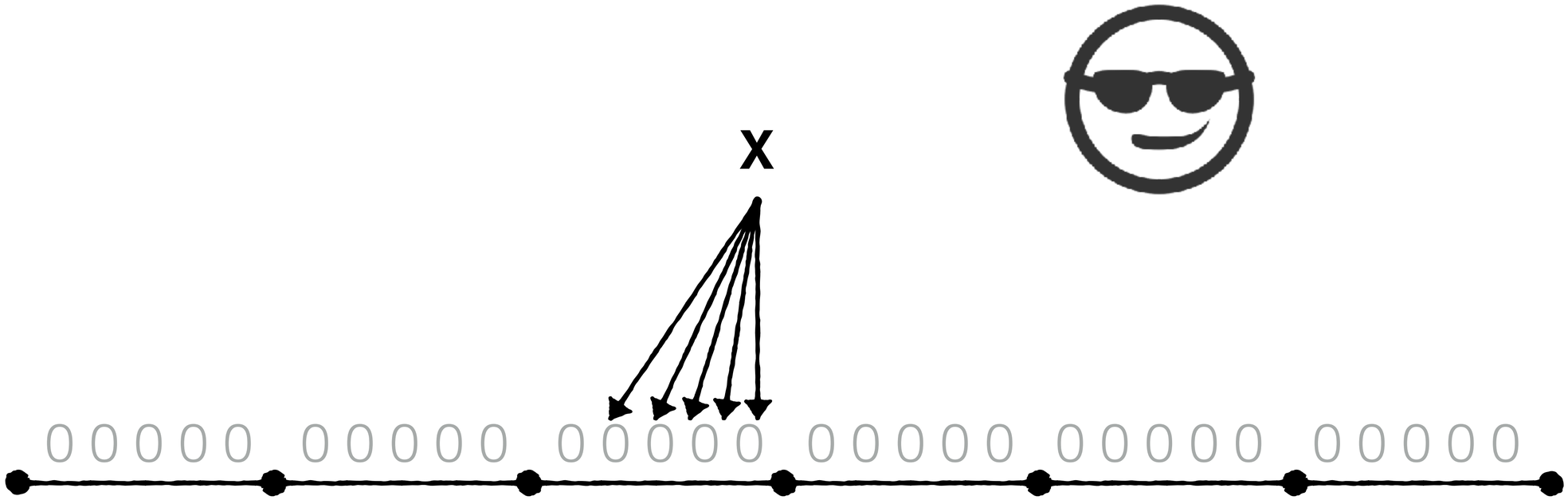
Blocked Bloom filter

Insert as though block is an independent Bloom filter



Blocked Bloom filter

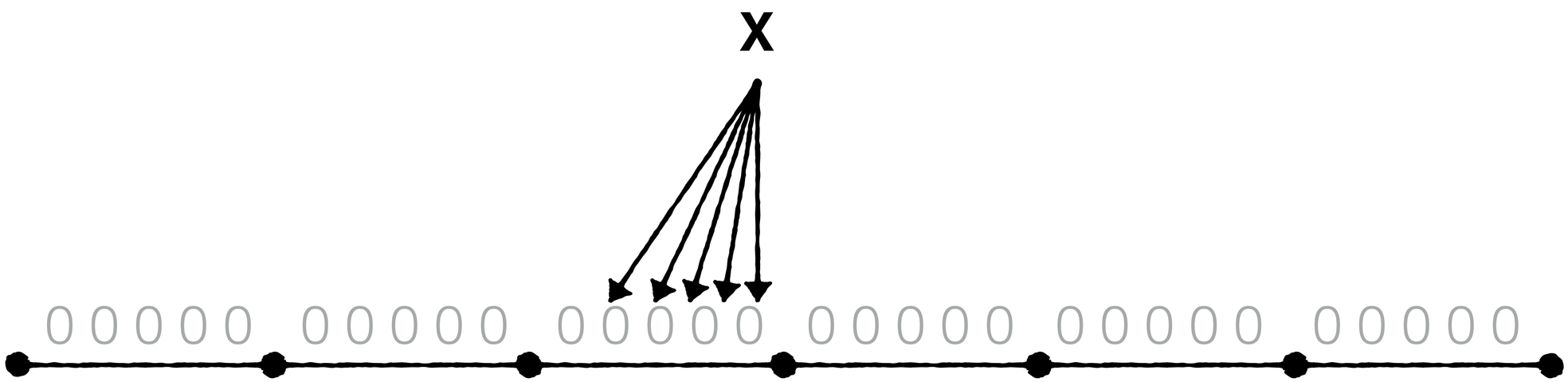
1 cache miss per query/insertion



Blocked Bloom filter

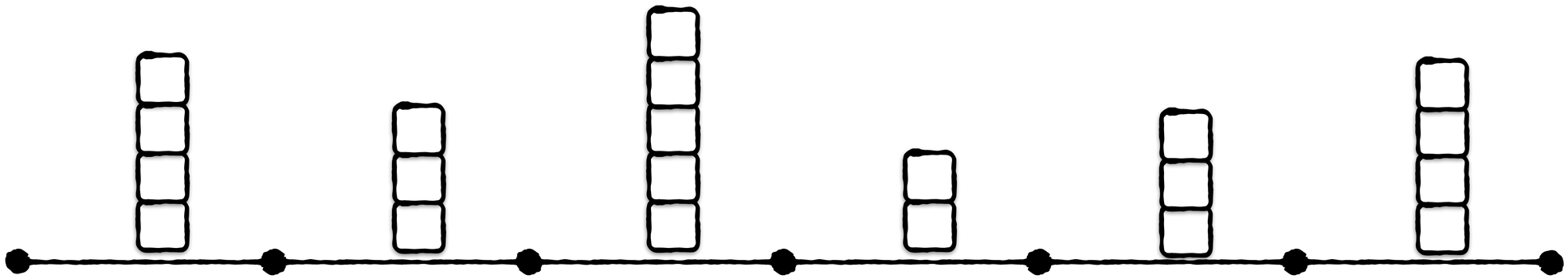
1 cache miss per query/insertion

Anything bad?



Blocked Bloom filter

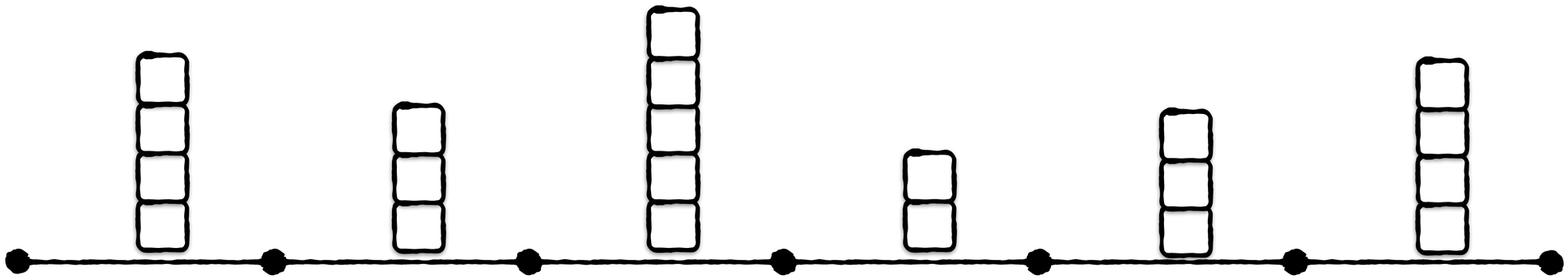
uneven distribution of entries across blocks



Blocked Bloom filter

uneven distribution of entries across blocks

impact on FPR?

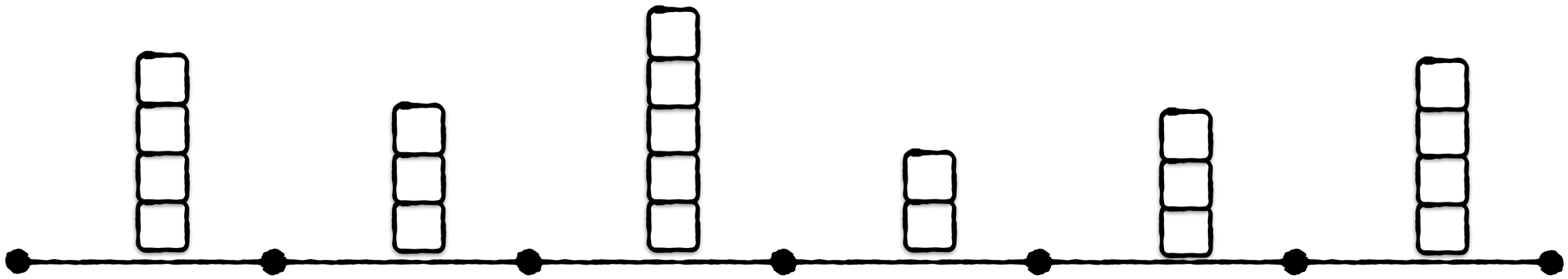


Blocked Bloom filter

uneven distribution of entries across blocks

impact on FPR?

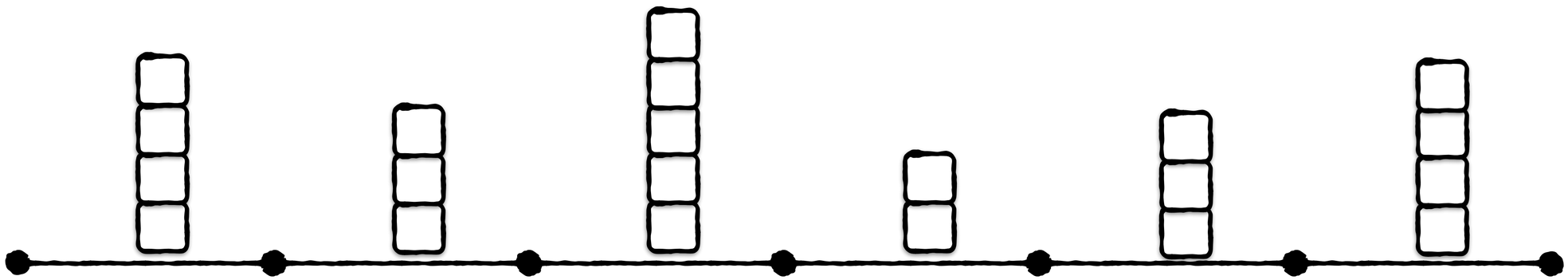
General analysis technique for hash tables



Blocked Bloom filter

entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

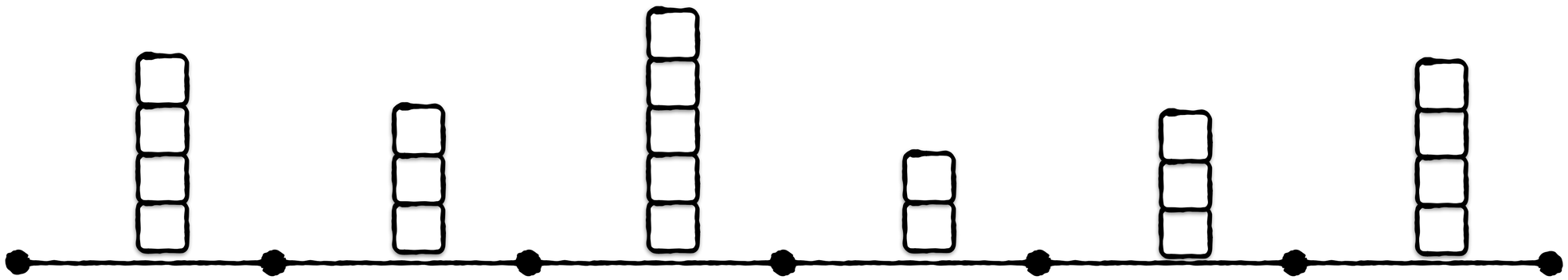


Blocked Bloom filter

entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

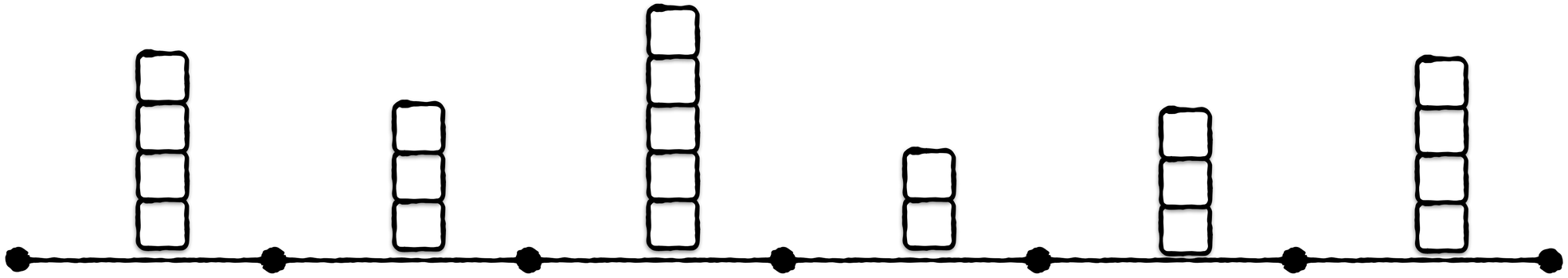
 # entries



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

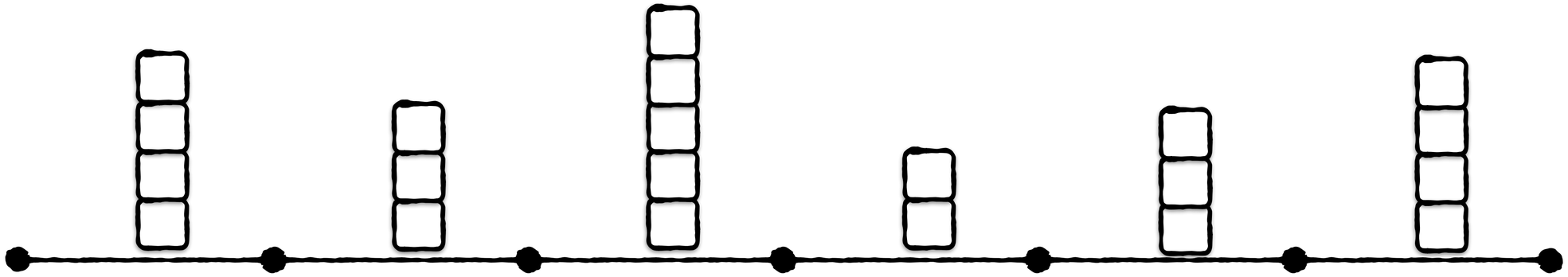
Prob of 1 entry falling into a given block, i.e., 1/n



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

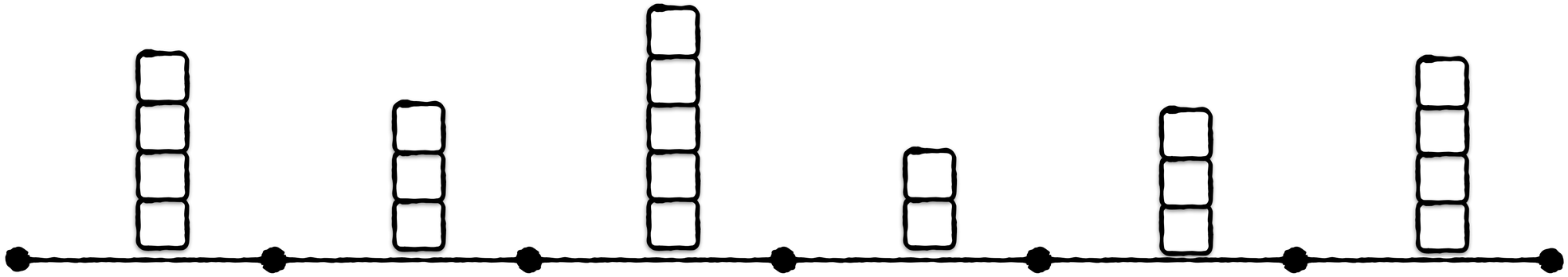
i entries falling into our bucket



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

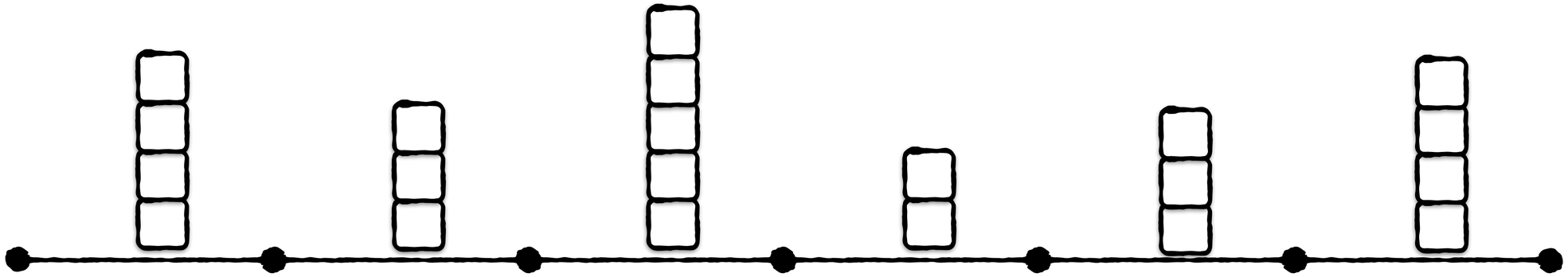
Ways of choosing k out of n entries



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

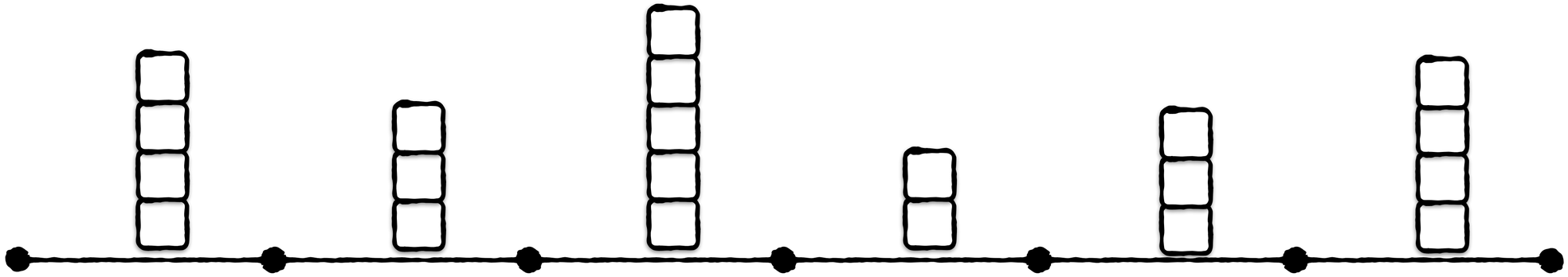
k entries falling into our block



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

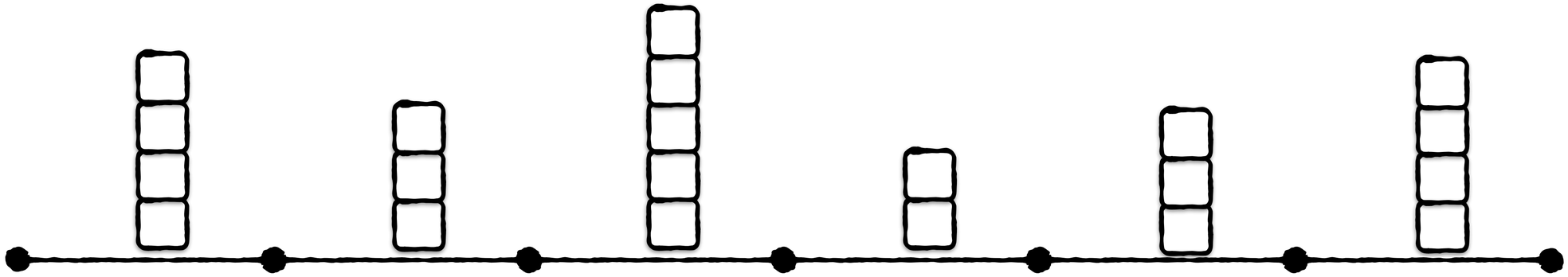
All other entries falling into other blocks



entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

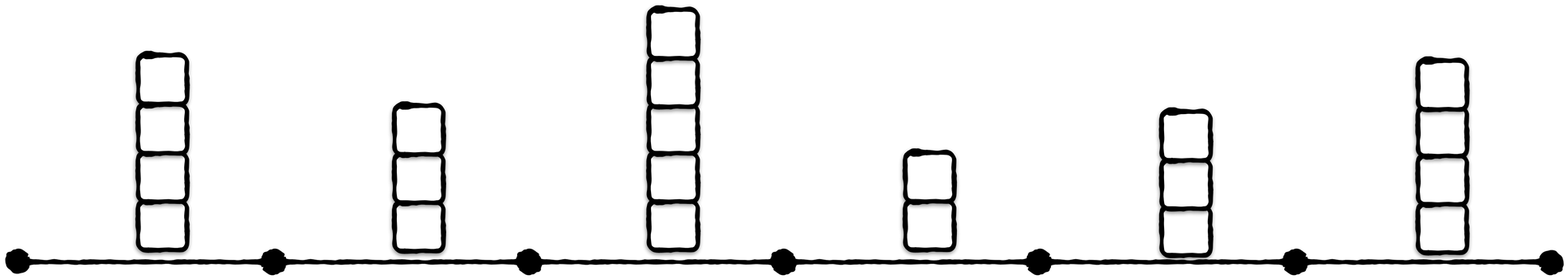
Cumbersome



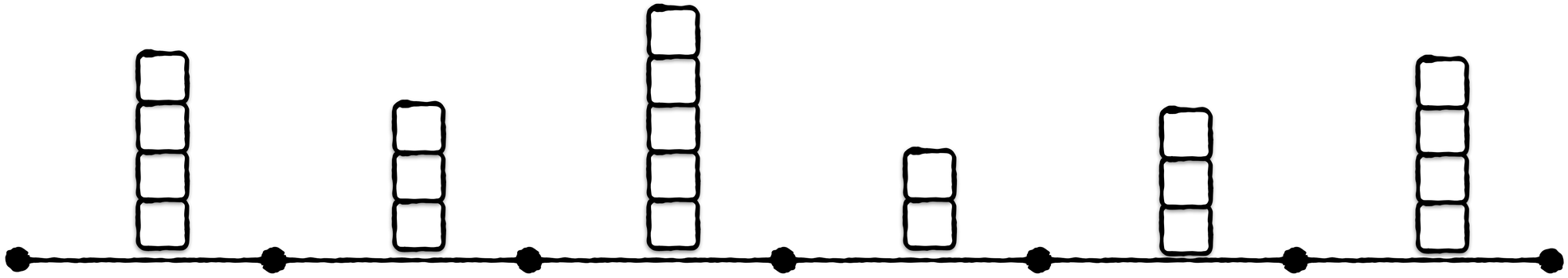
entries per block follows binomial distribution

$$f(n, p, i) = \binom{n}{i} \cdot p^i \cdot (1-p)^{n-i}$$

For n → ∞, binomial converges to Poisson

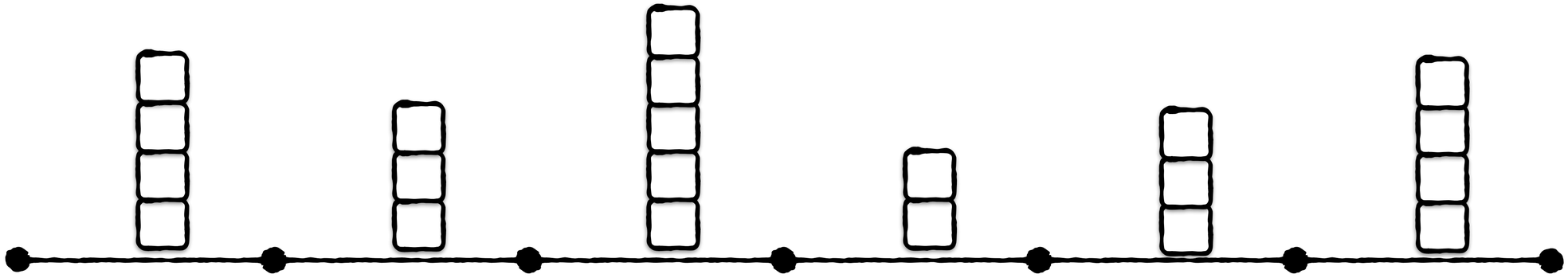


P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$



P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$

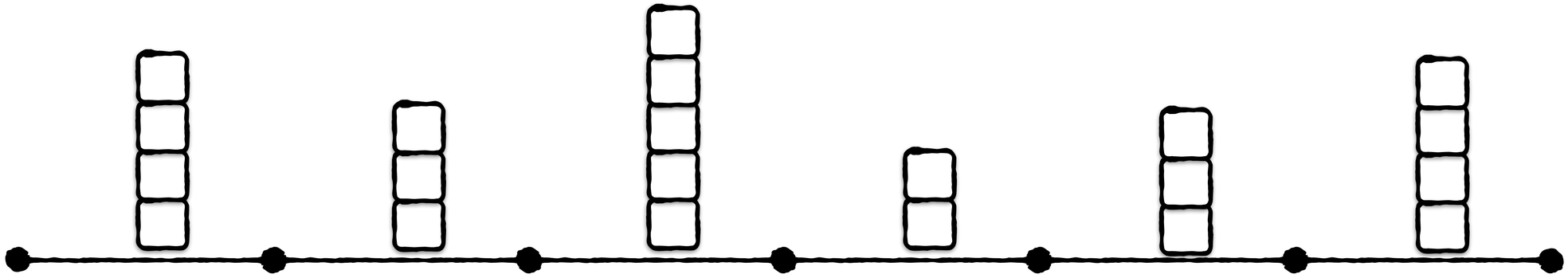
λ = avg. entries per block



P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$

λ = avg. entries per block **= B**/(M/N)

Bits per cache line (e.g., 256)

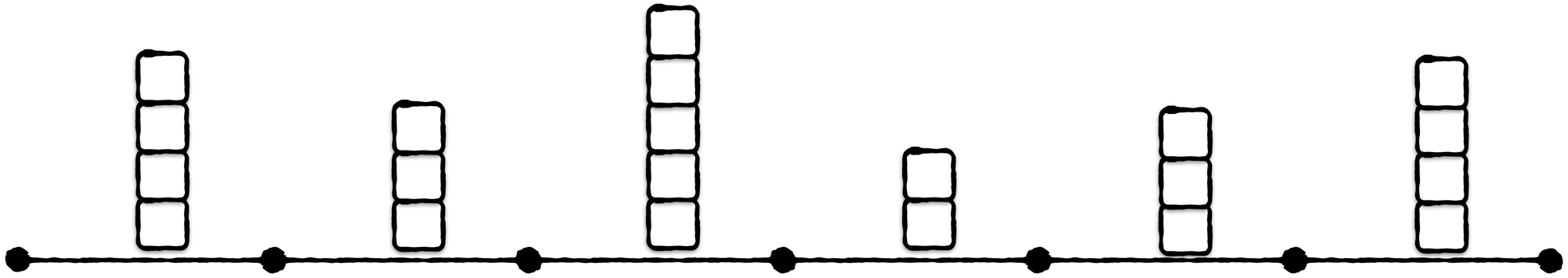


P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$

λ = avg. entries per block **= B/(M/N)**

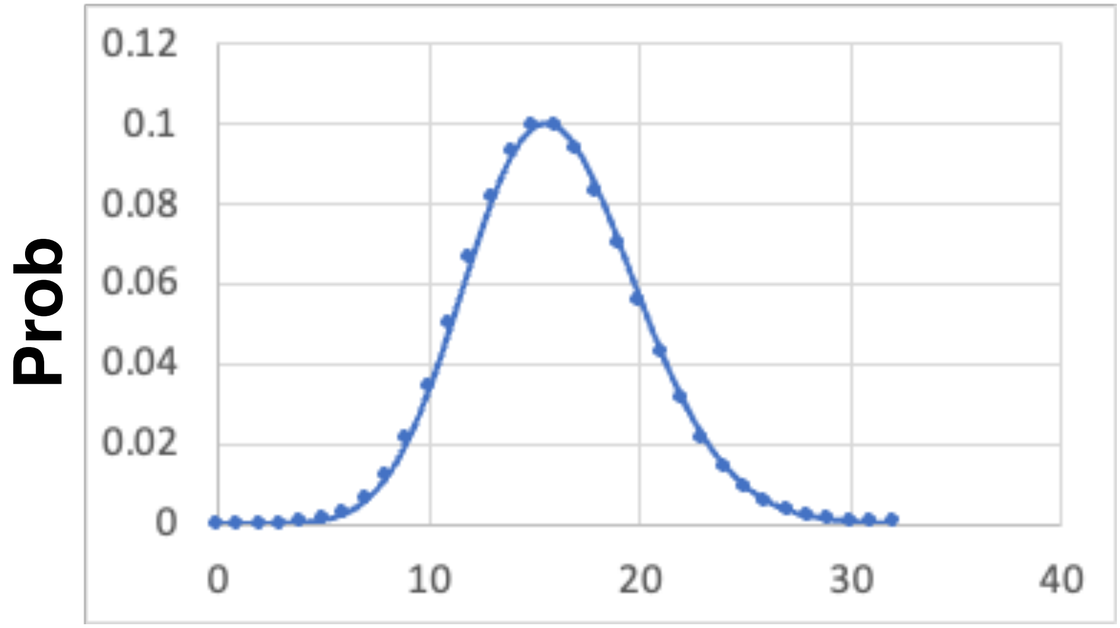
Bits per cache line (e.g., 256)

Bits per entry (e.g., 8)



P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$

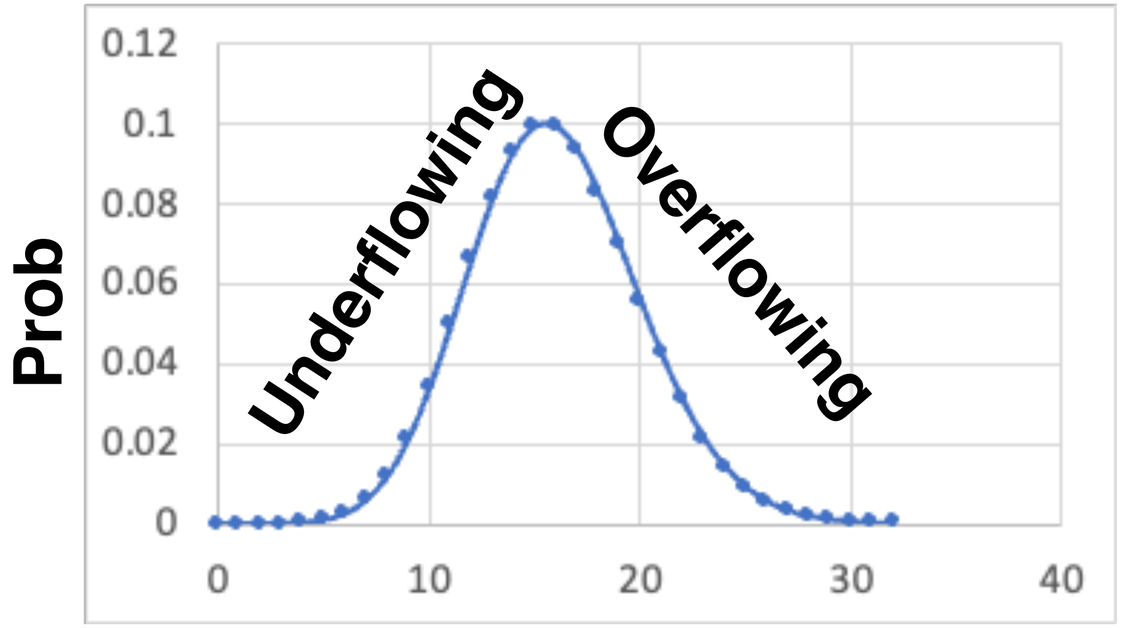
λ = avg. entries per block



Entries i per block with λ = 16

P[i entries fall into given block] ~ Poisson(i, λ) = $\frac{\lambda^i \cdot e^{-\lambda}}{i!}$

λ = avg. entries per block



Entries i per block with λ = 16

entries in a block ~ Poisson(i, B/(M/N))

entries in a block ~ Poisson(i, B/(M/N))

FPR for filter ~ $FPR(N, M, K) = (1-e^{-KN/M})^K$

entries in a block ~ Poisson(i, B/(M/N))

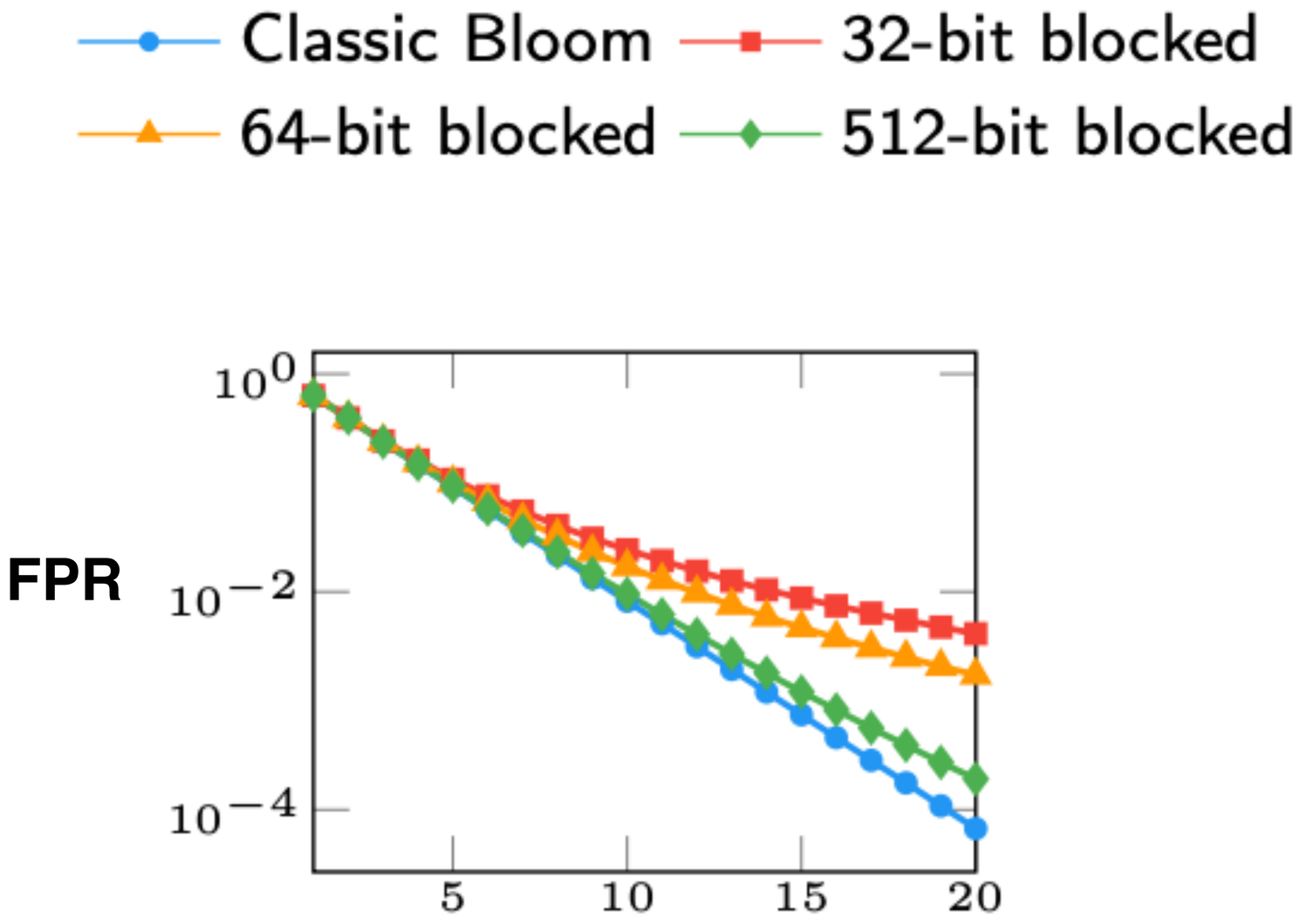
FPR for filter ~ FPR(**i**, **B, K**)

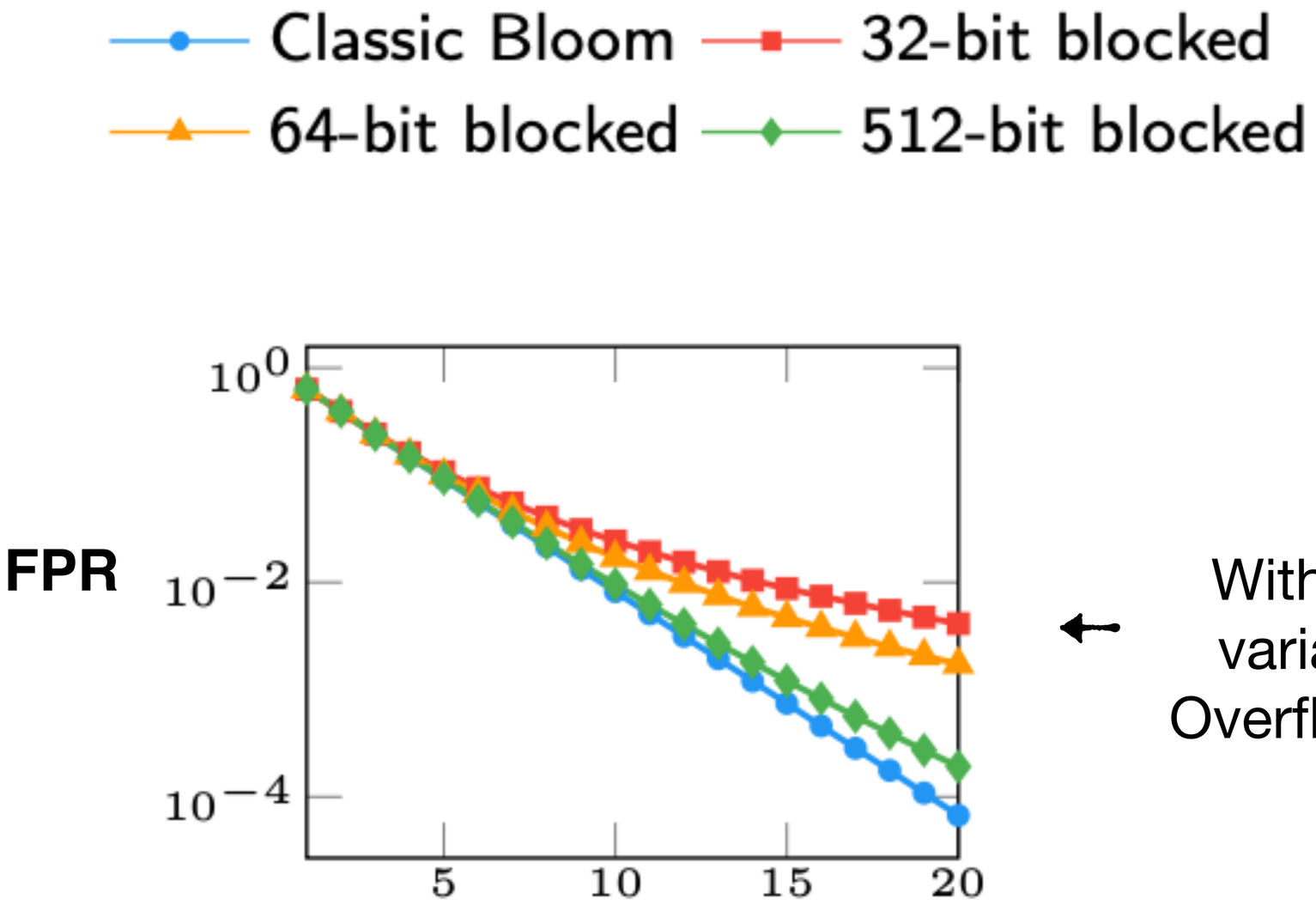
i entries in cache line

B bits in cache line

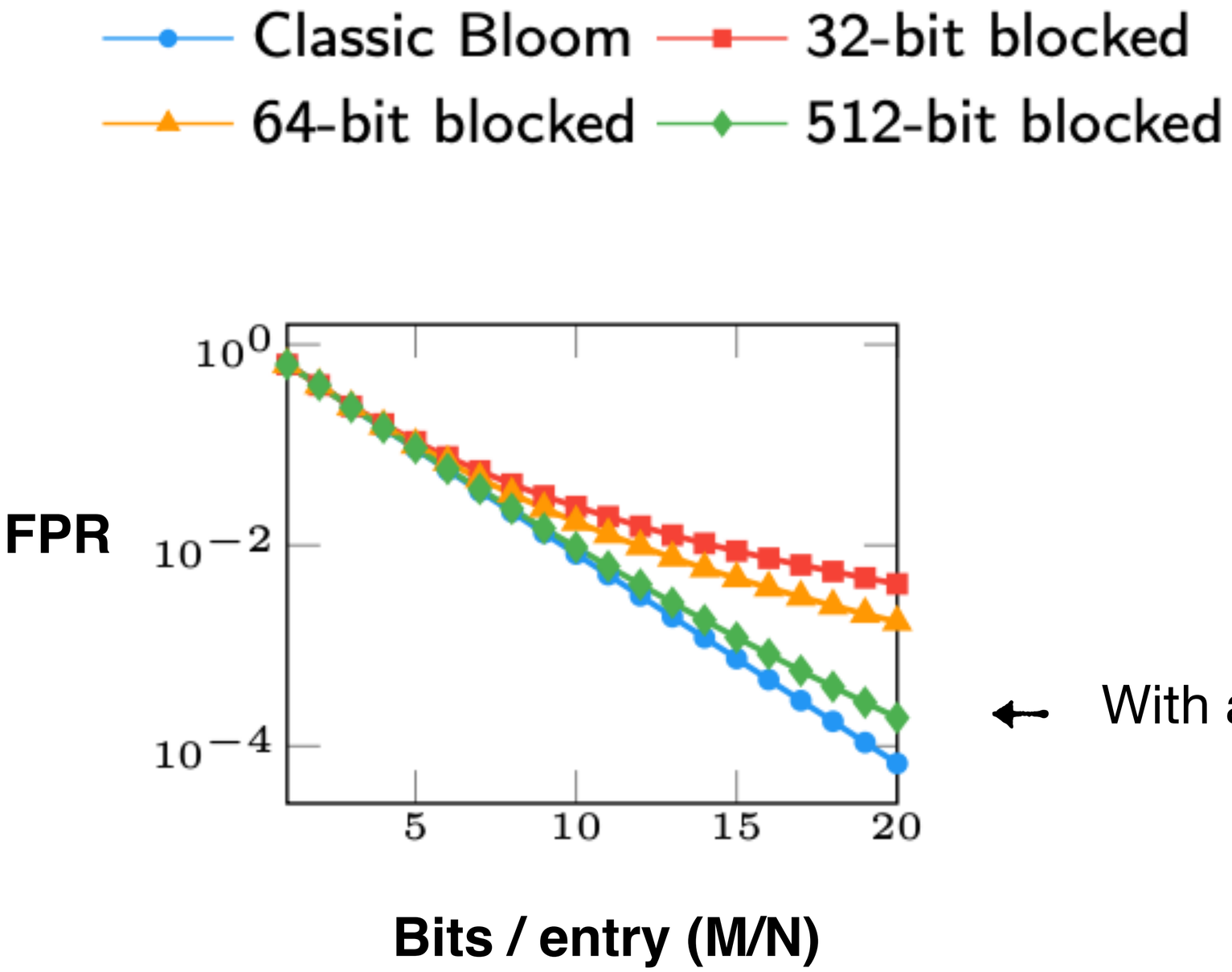
K hash functions

$$\textbf{Avg. FPR across all blocks} = \sum_{i=0}^{\infty} \text{Poisson}(i, B/(M/N)) \cdot \text{FPR}(i, B, K)$$


Classic Bloom
32-bit blocked
64-bit blocked
512-bit blocked
FPR
10^0
10^{-2}
10^{-4}
5
10
15
20
Bits / entry (M/N)

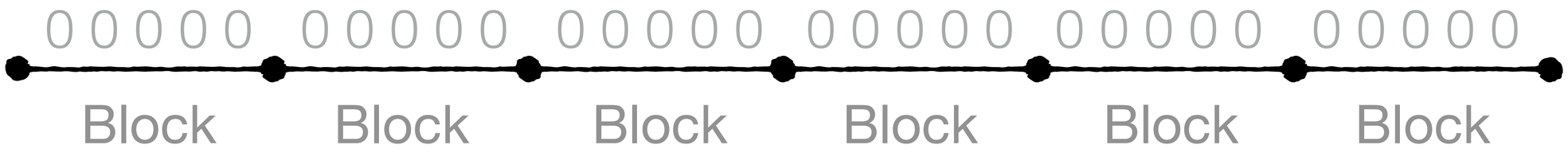


With smaller blocks, there is more variation in entries across blocks. Overflowing blocks blow up the FPR.

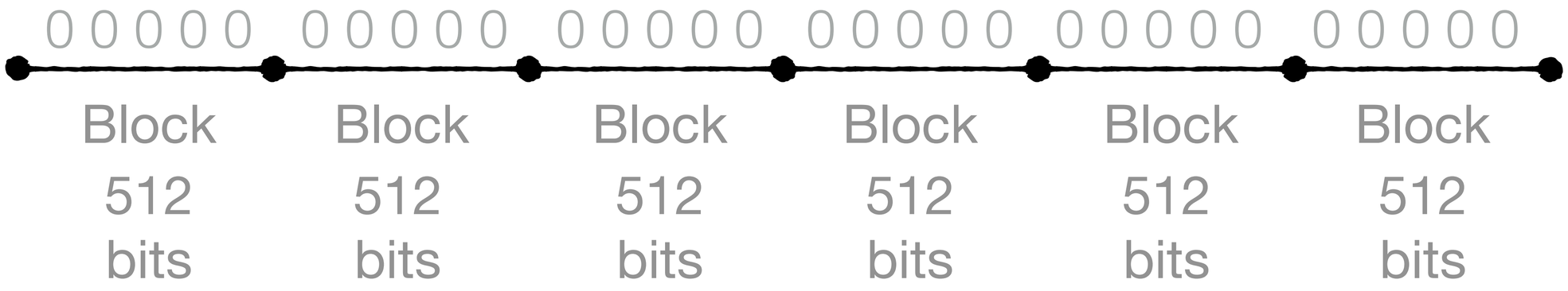


← With a block the size of a cache line, we don't lose much

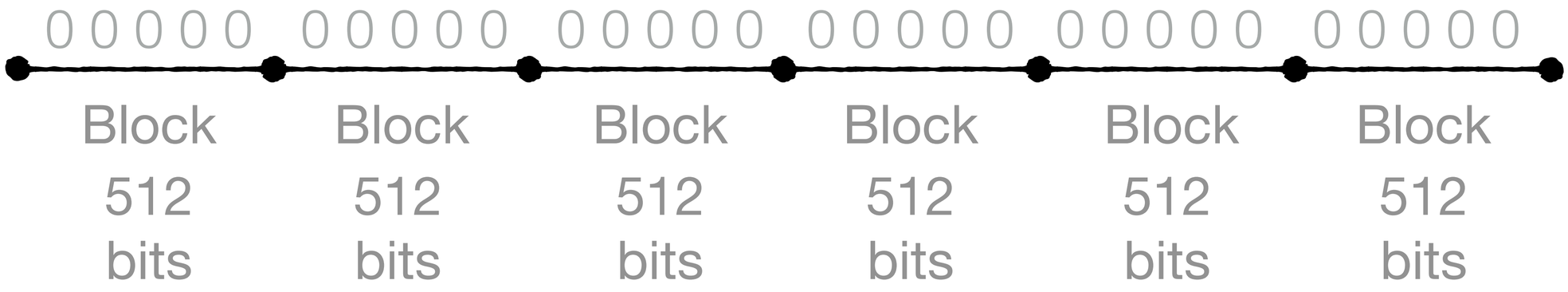
size blocks as cache lines



size blocks as cache lines

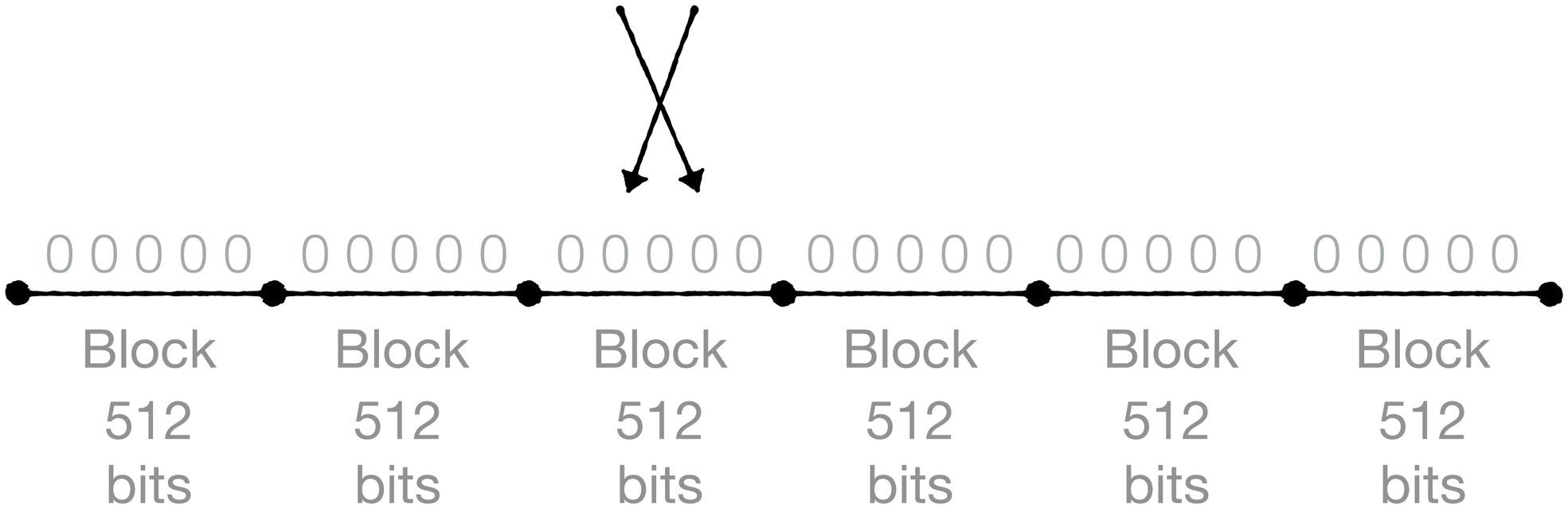


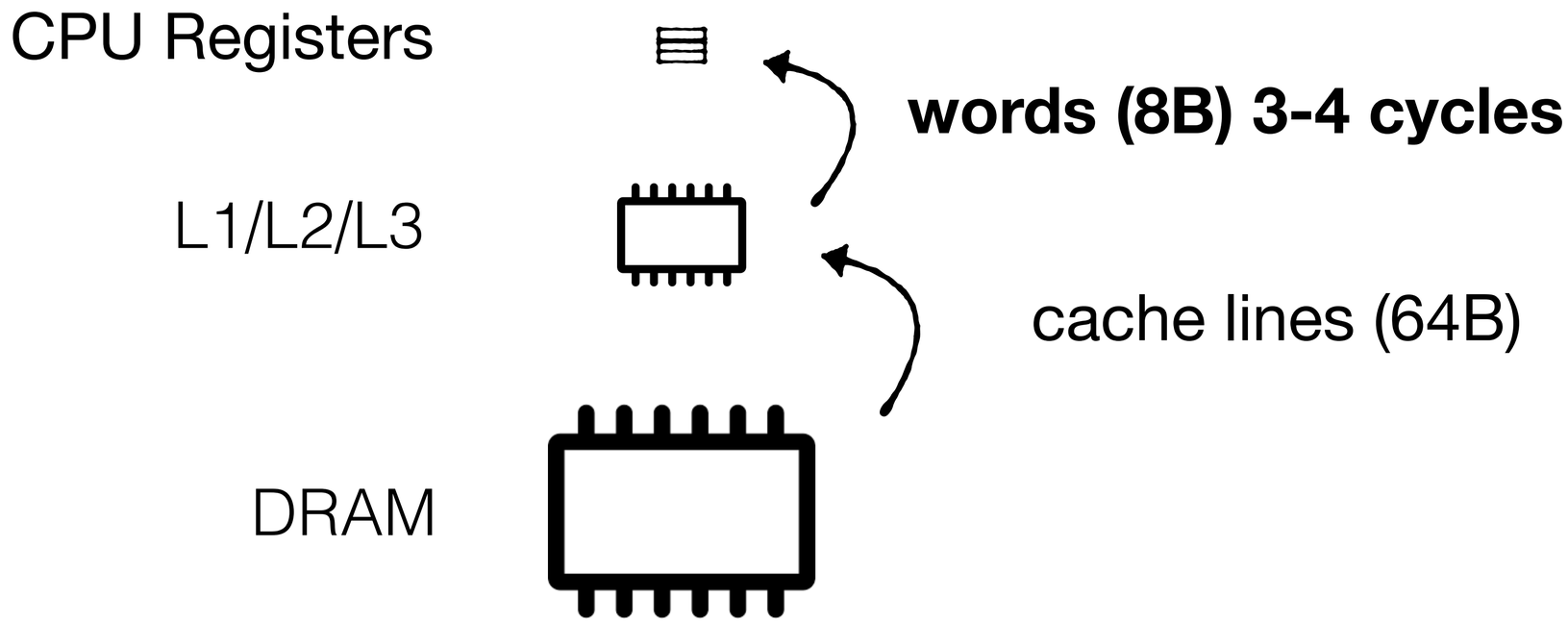
Any remaining issue?



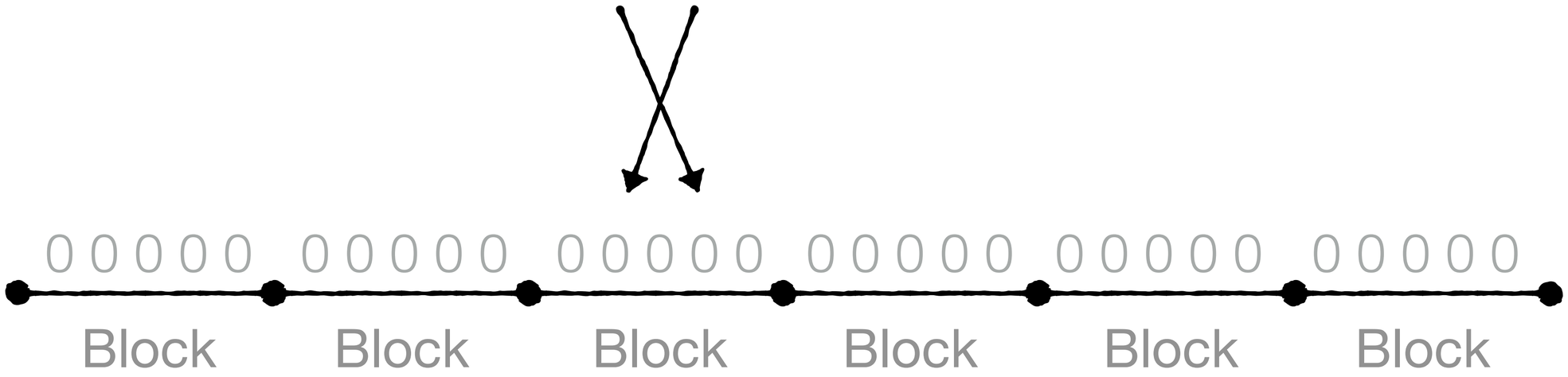
Any remaining issue?

Random access within a cache line

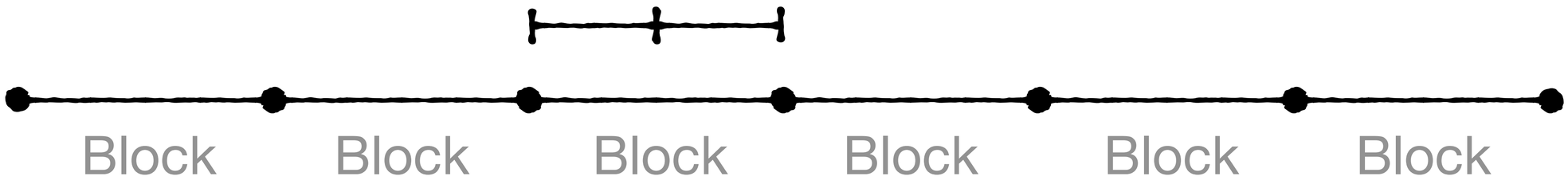



CPU Registers
L1/L2/L3
DRAM
words (8B) 3-4 cycles
cache lines (64B)

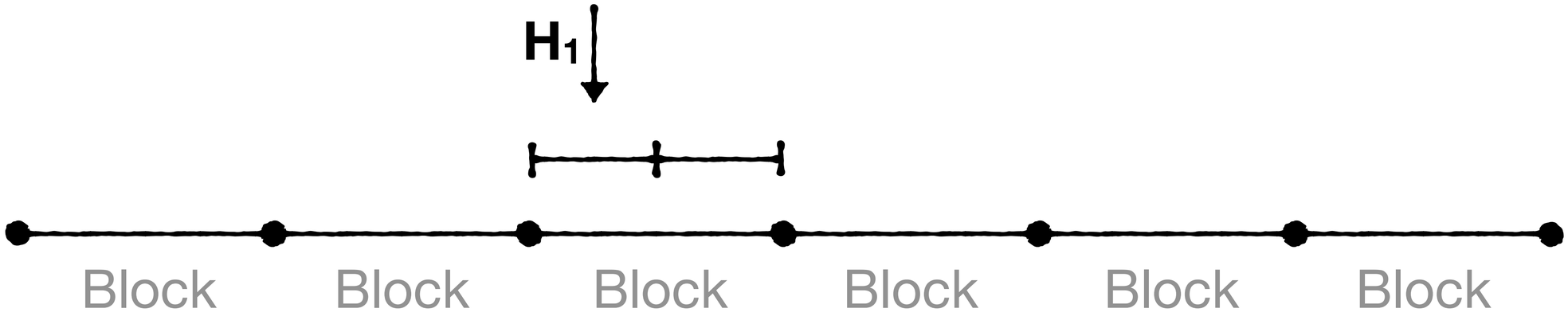
Each random access moves different word from L1 cache to register



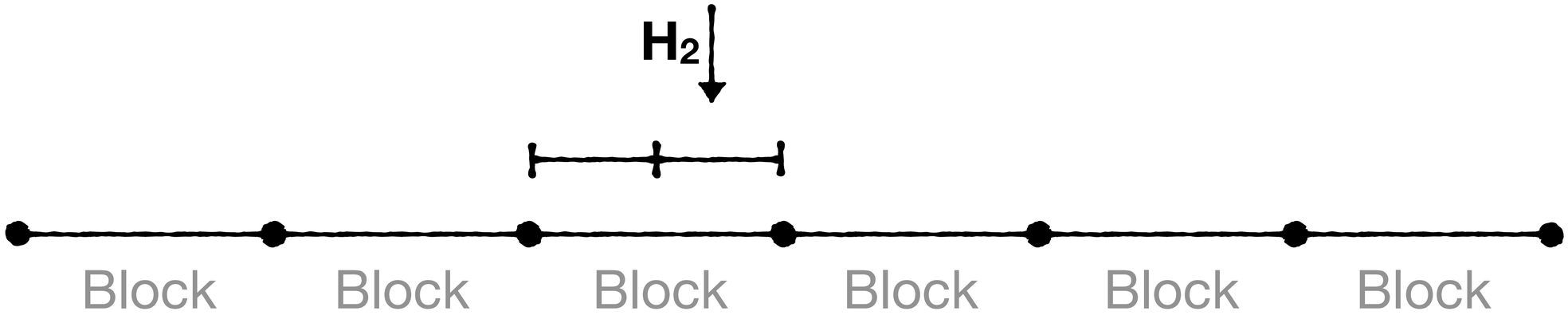
e.g., 4 hash functions, 2 words per block



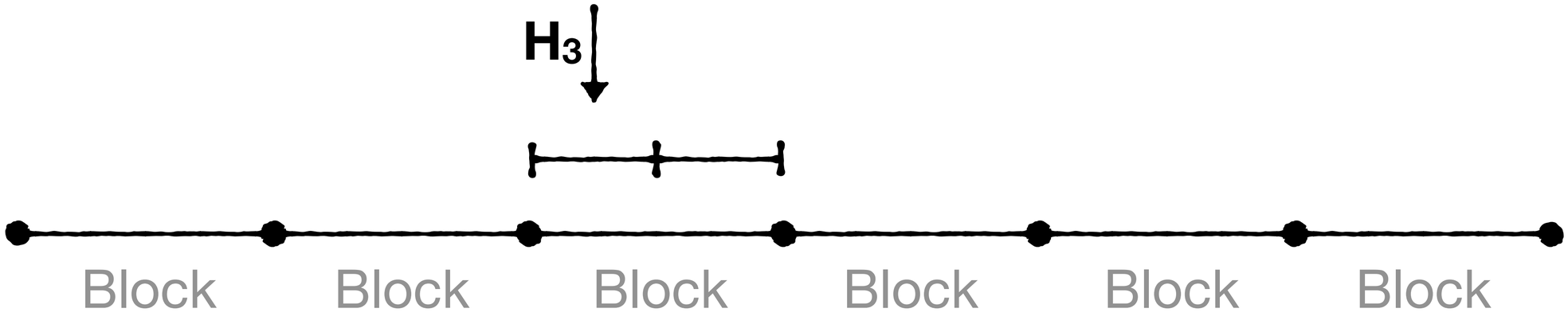
e.g., 4 hash functions, 2 words per block



e.g., 4 hash functions, 2 words per block

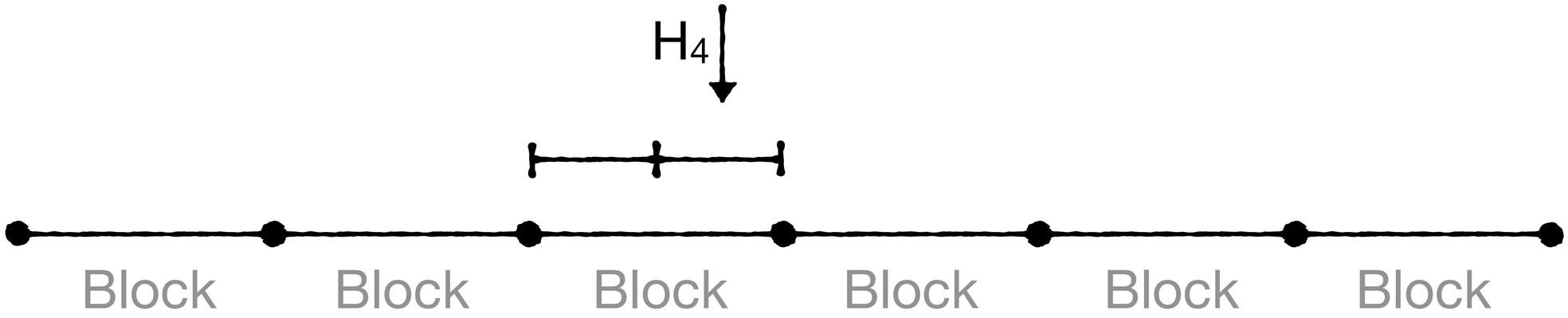


e.g., 4 hash functions, 2 words per block



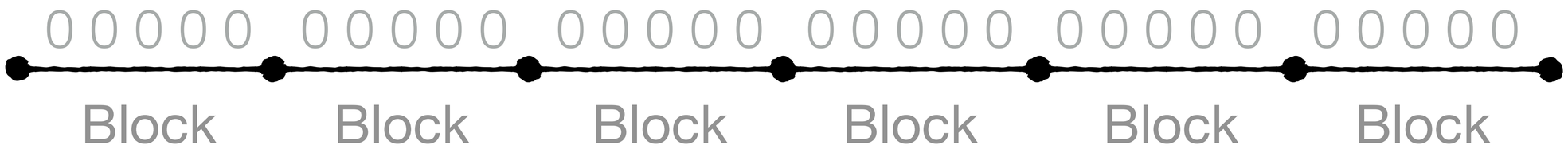
Solutions?

e.g., 4 hash functions, 2 words per block



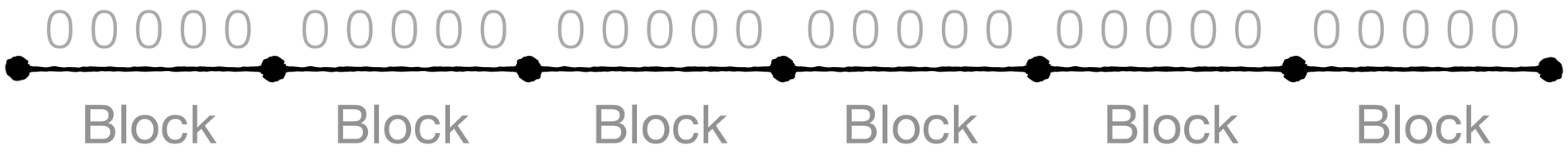
Split block Bloom filters. Jim Apple. Arxiv 2023.

Used in the Impala system as of 2016

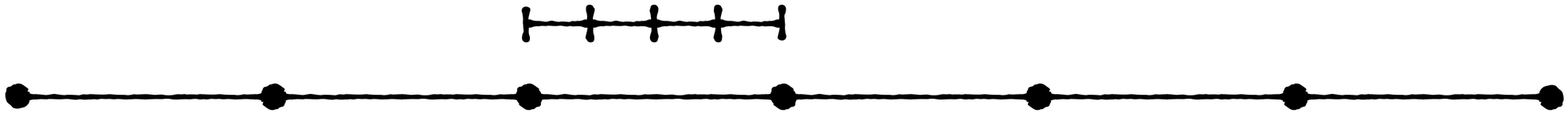


Split block Bloom filters. Jim Apple. Arxiv 2023.

Performance-Optimal Filtering: Bloom Overtakes Cuckoo at High Throughput. Harald Lang, Thomas Neumann, Alfons Kemper, Peter Boncz. **VLDB 2019.**

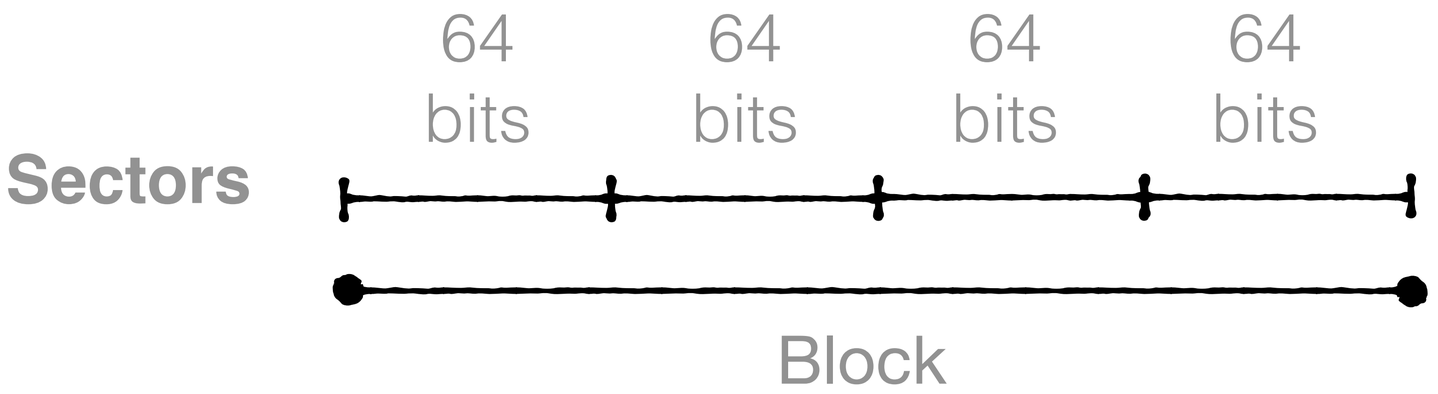


Partition into s sectors, each the size of a word (e.g., 64 bits)

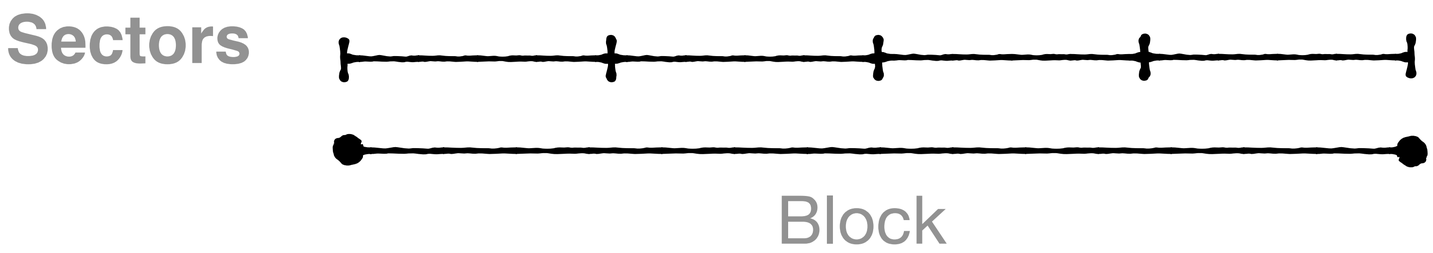


Block

Example: s = 4 sectors

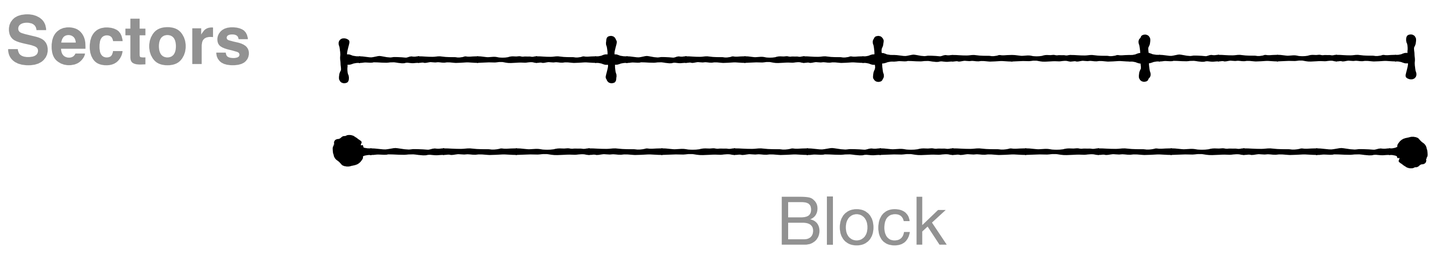


Insertion: hashes to k / s bits per sector sequentially



Insertion: hashes to k / s bits per sector sequentially

e.g., s=4 sectors and k=8 hashes



Insertion: hashes to k / s bits per sector sequentially

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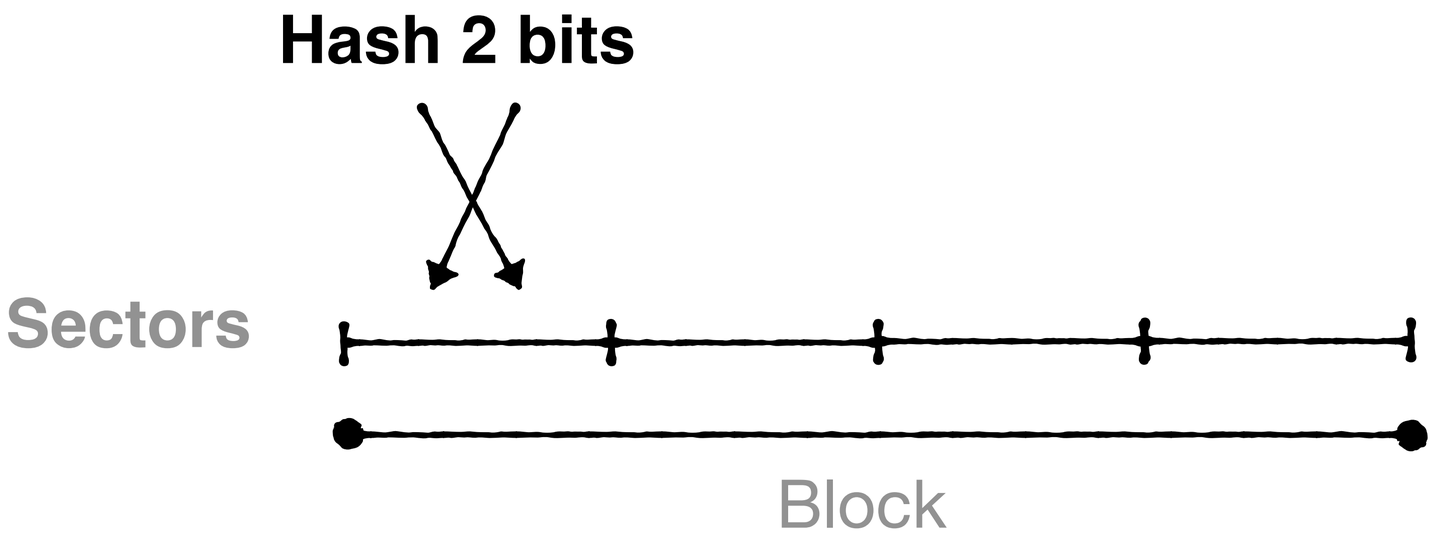

Insertion: hashes to k / s bits per sector sequentially

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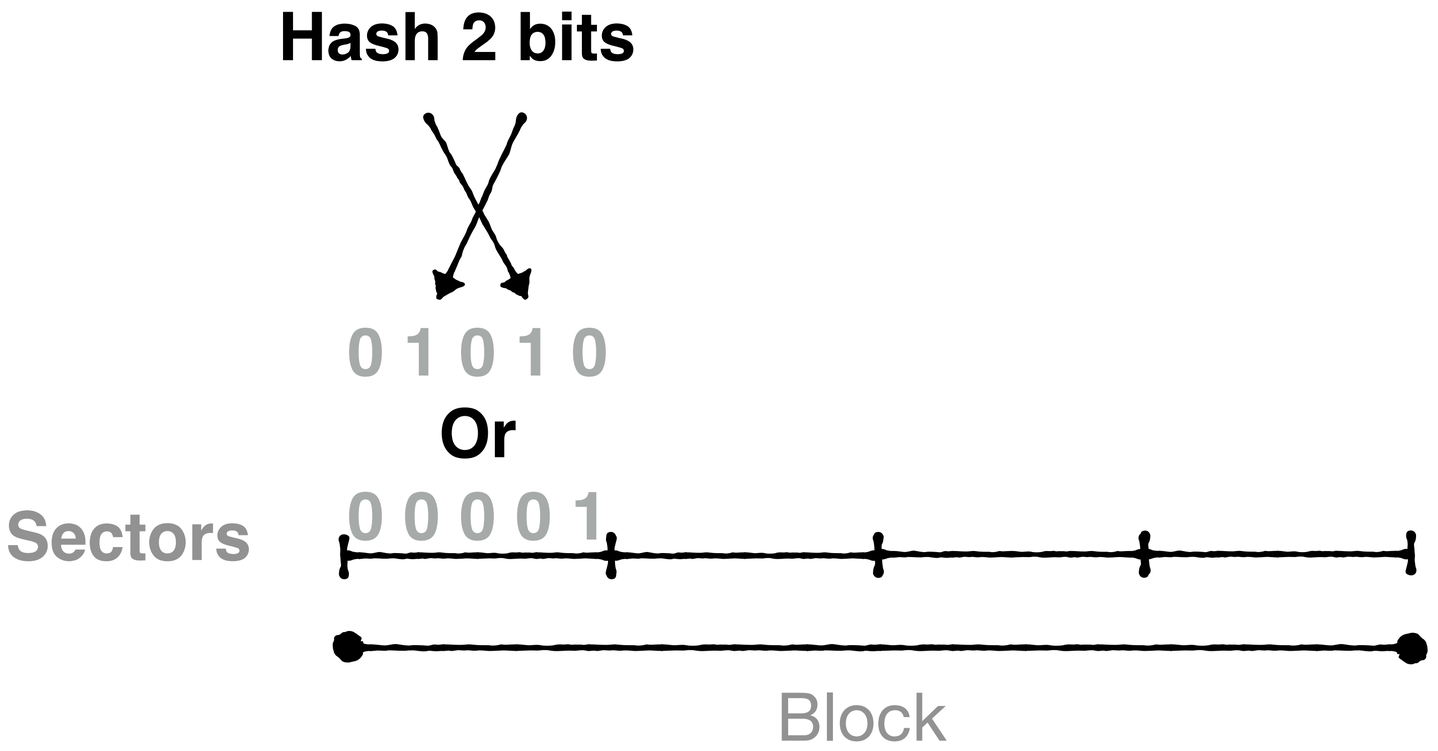

Insertion: hashes to k / s bits per sector sequentially

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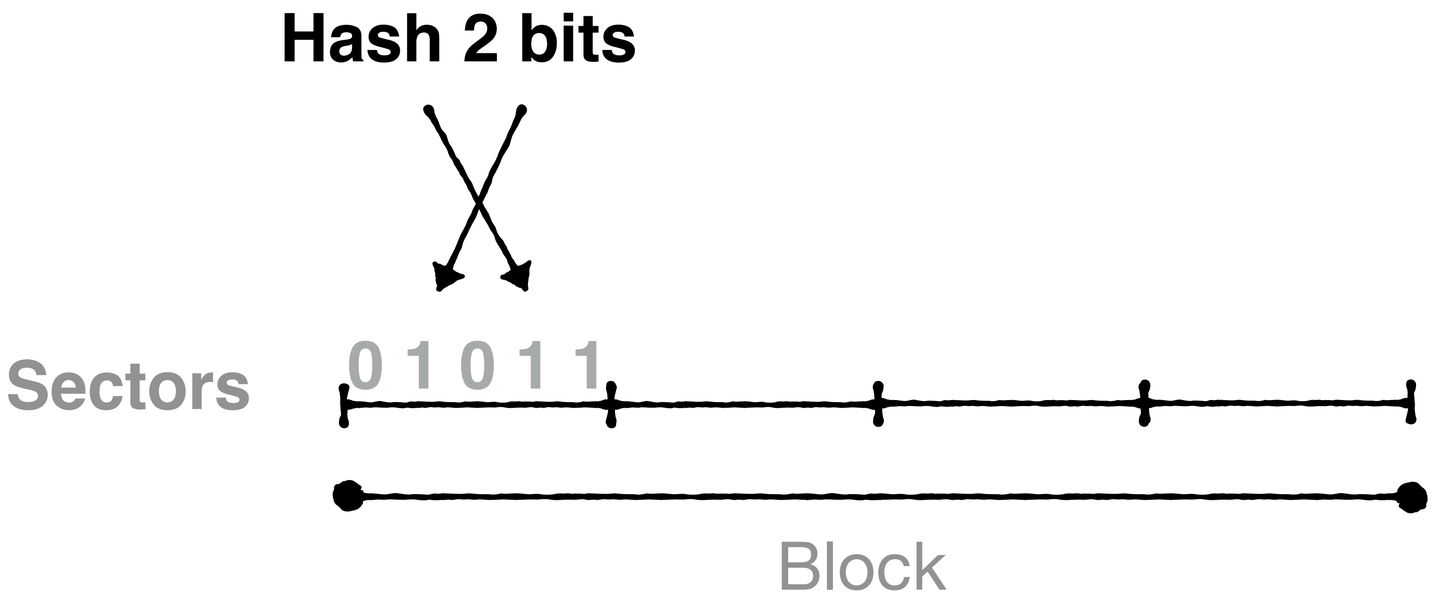
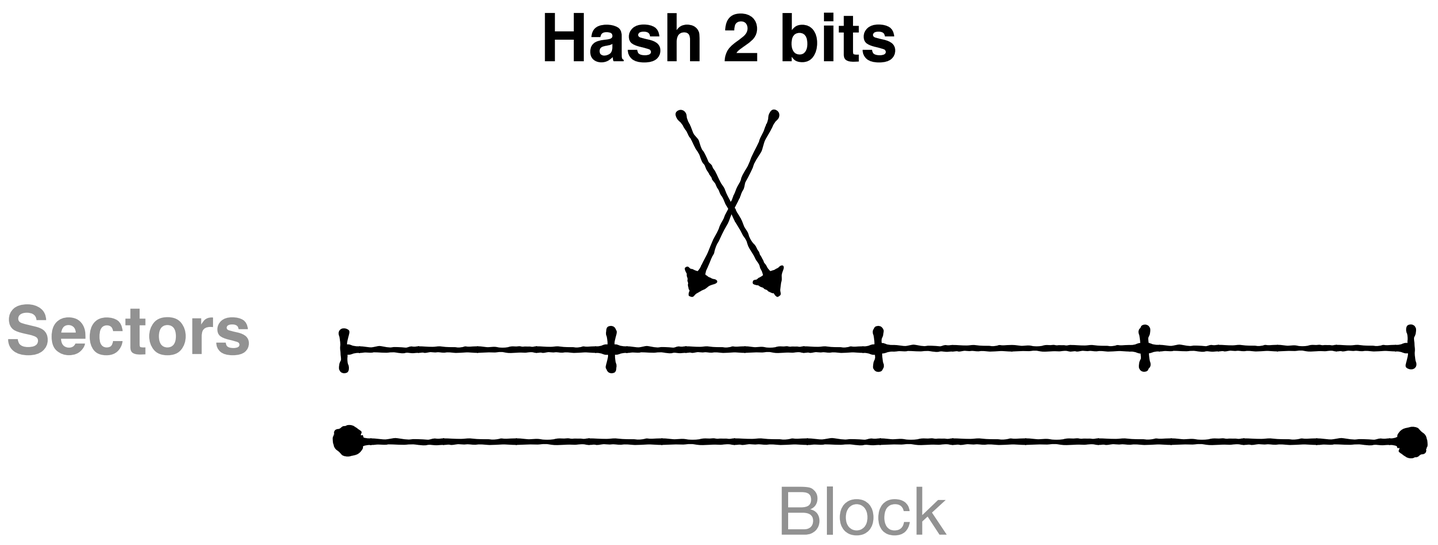


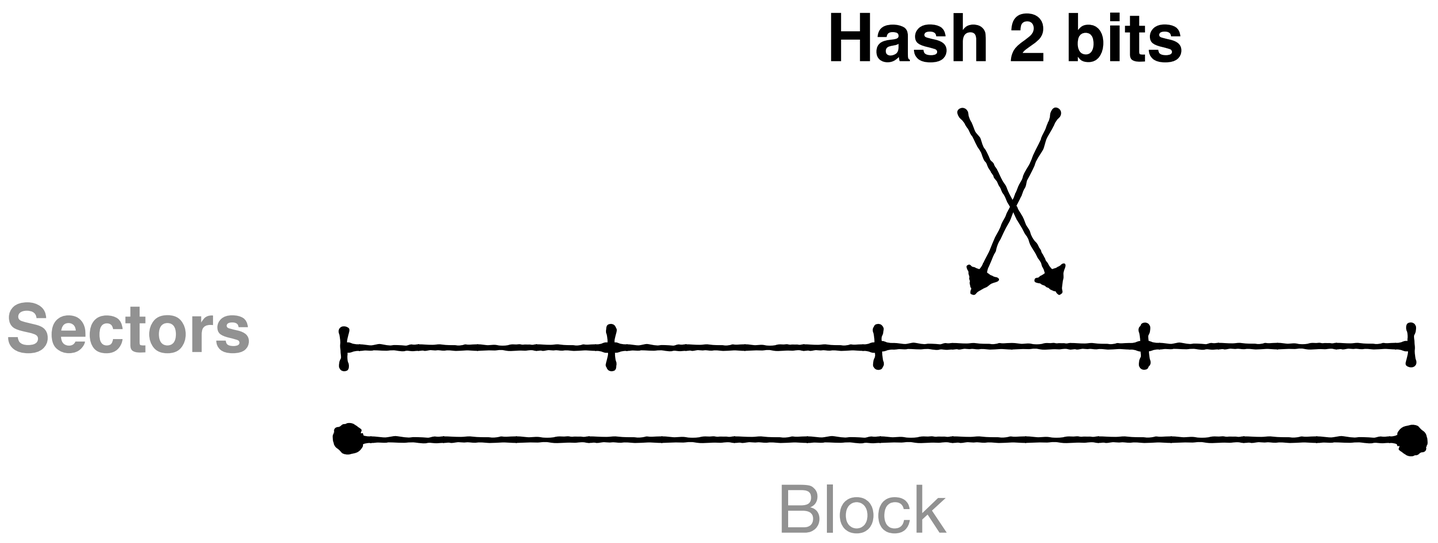
Insertion: hashes to k / s bits per sector sequentially

e.g., s=4 sectors and k=8 hashes



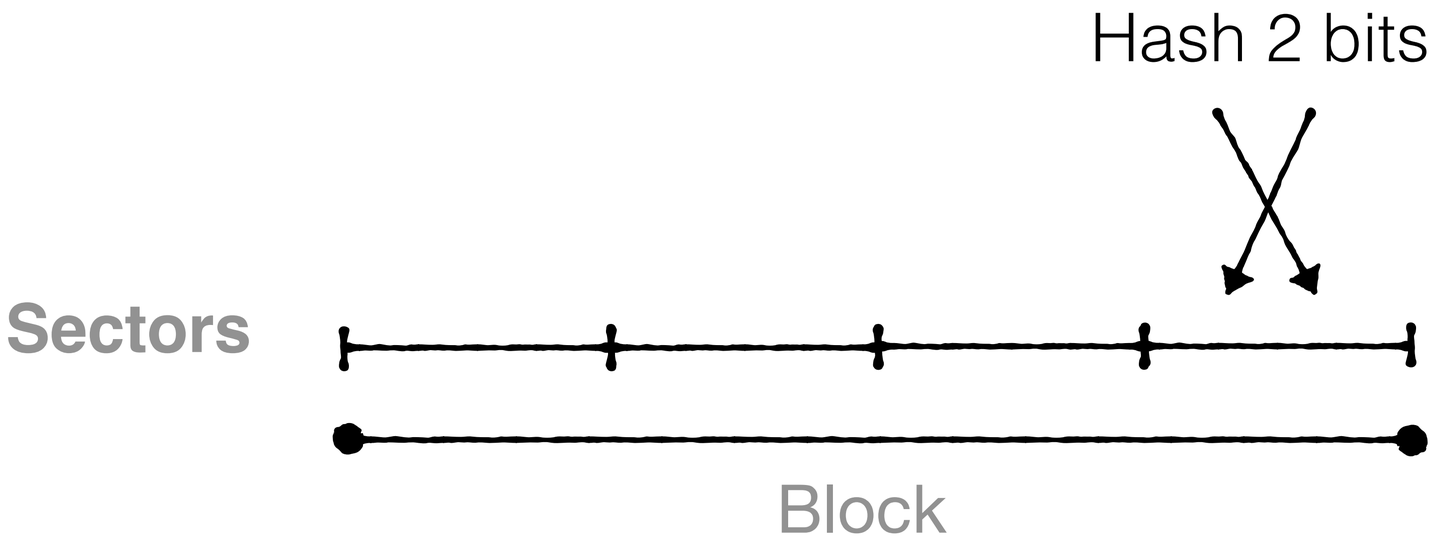
Insertion: hashes to k / s bits per sector sequentially

e.g., s=4 sectors and k=8 hashes

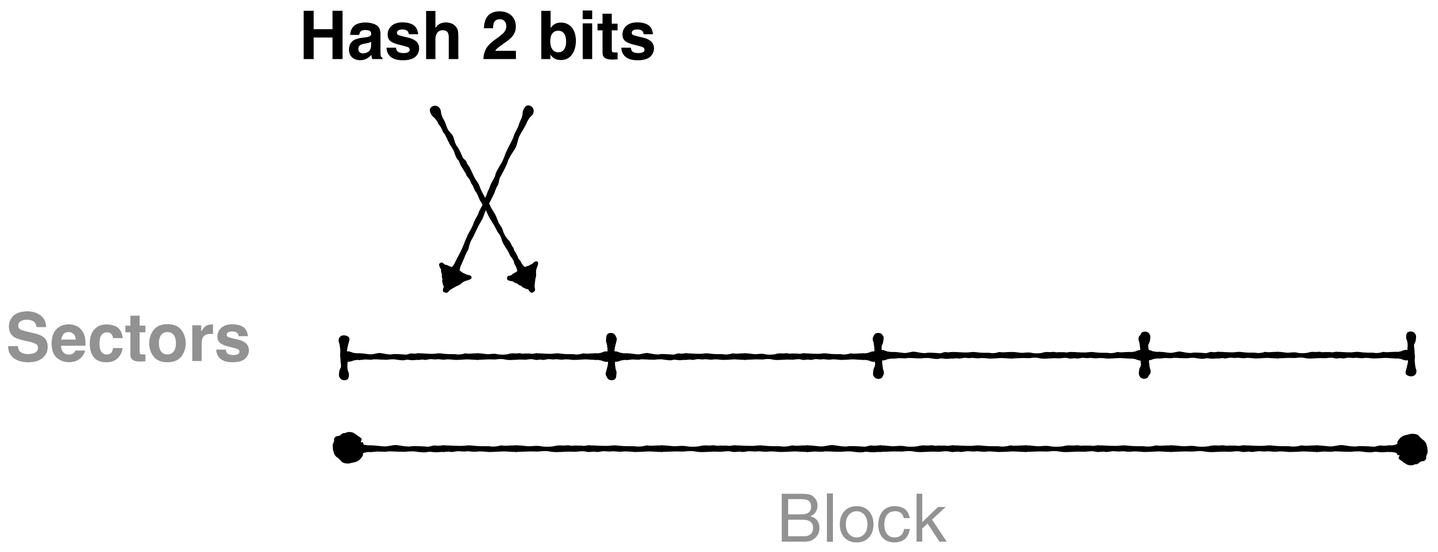


Insertion: hashes to k / s bits per sector sequentially

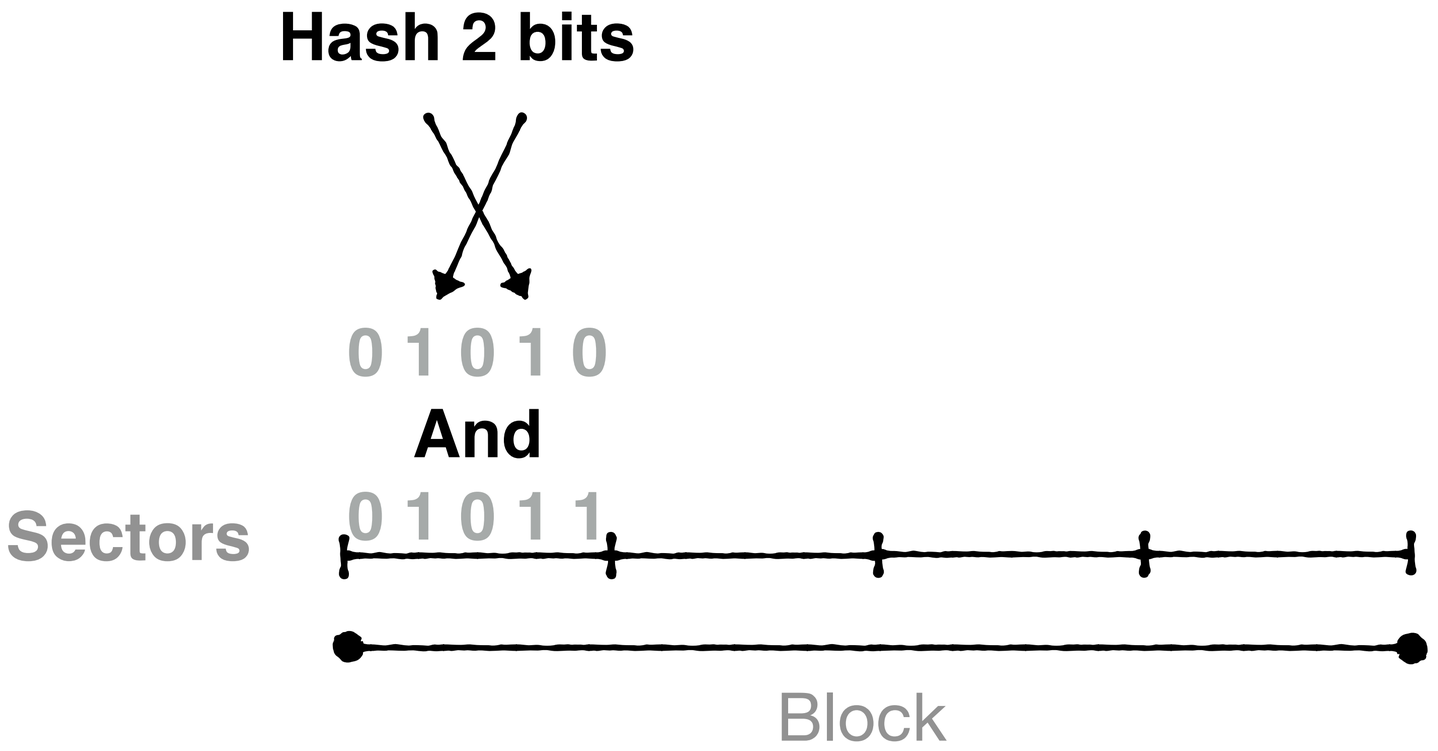
Read/written 4 rather than 8 registers



Query: check k / s hashes per sector sequentially



Query: check k / s hashes per sector sequentially

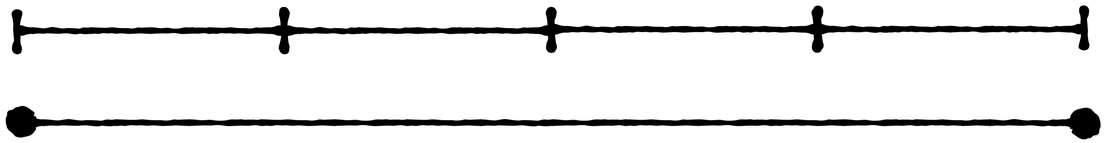


Query: check k / s hashes per sector sequentially

Hash 2 bits

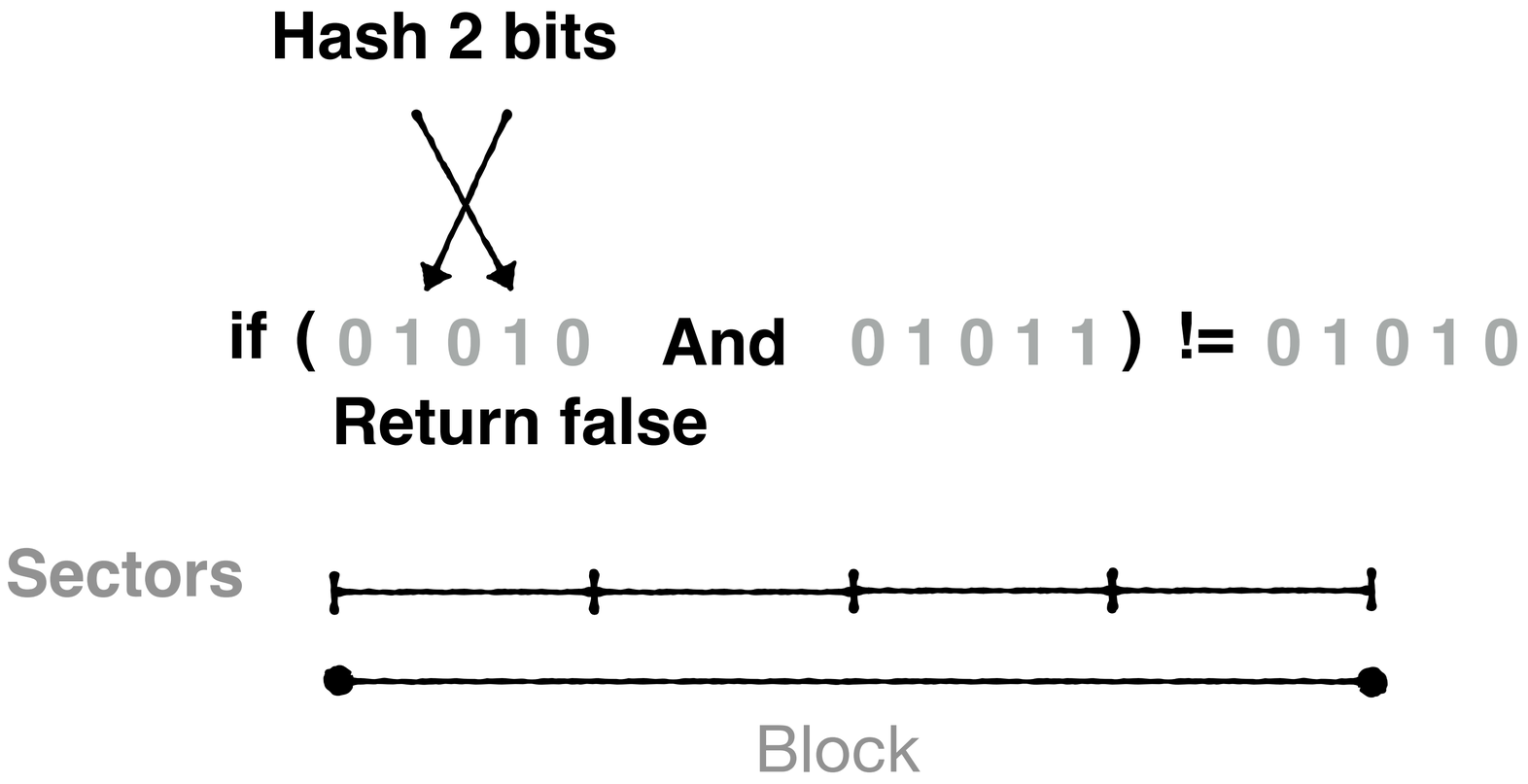
(0 1 0 1 0 **And** 0 1 0 1 1) **==** 0 1 0 1 0

Sectors

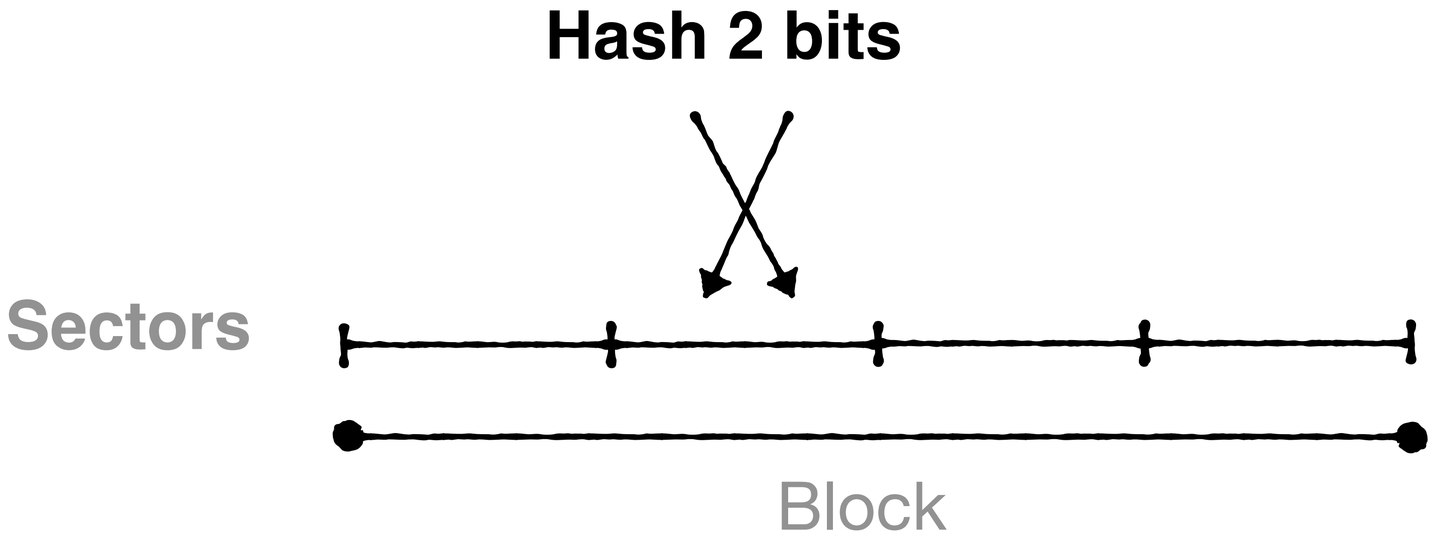


Block

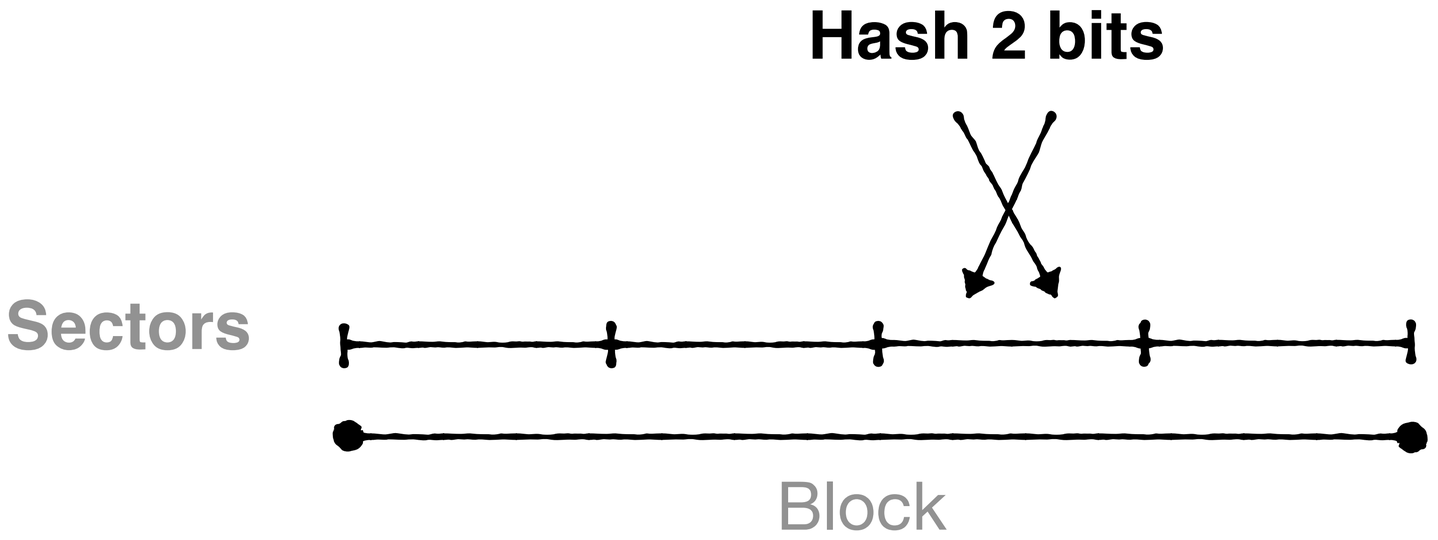
Query: check k / s hashes per sector sequentially



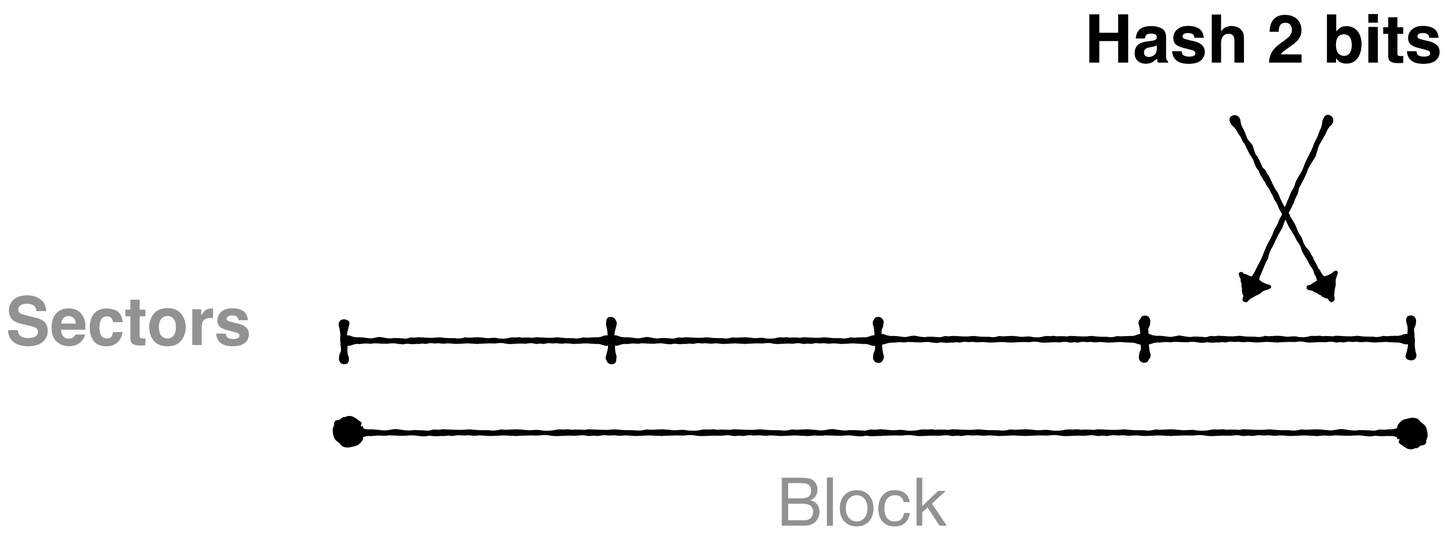
Query: check k / s hashes per sector sequentially



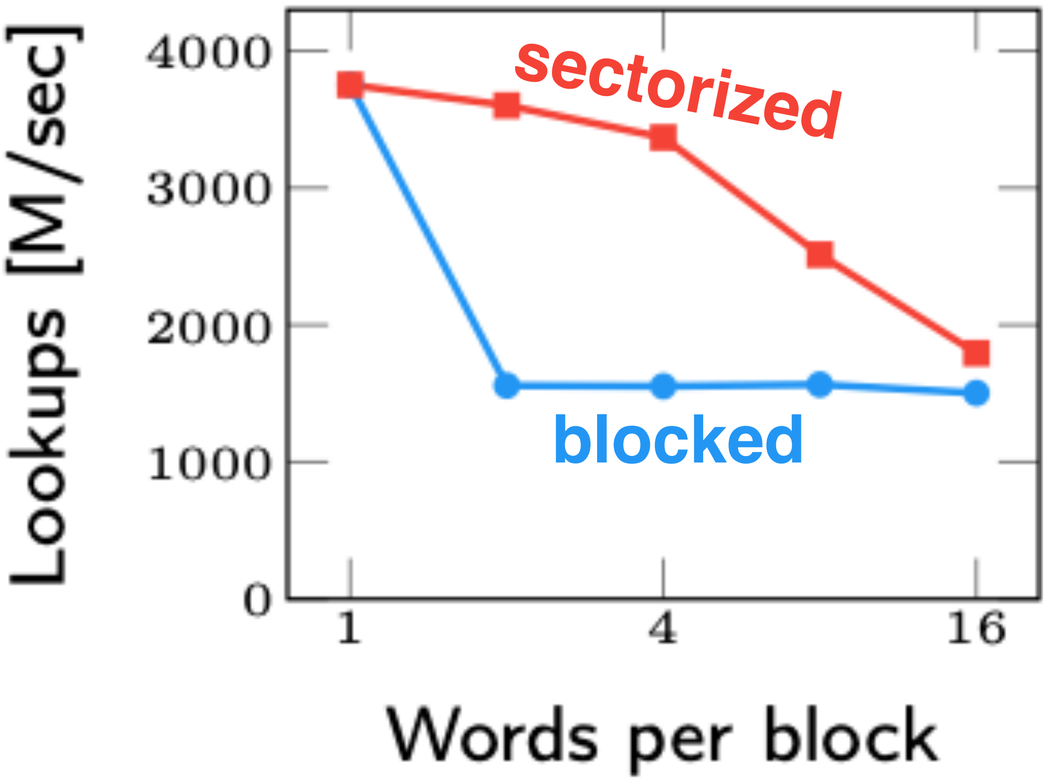
Query: check k / s hashes per sector sequentially



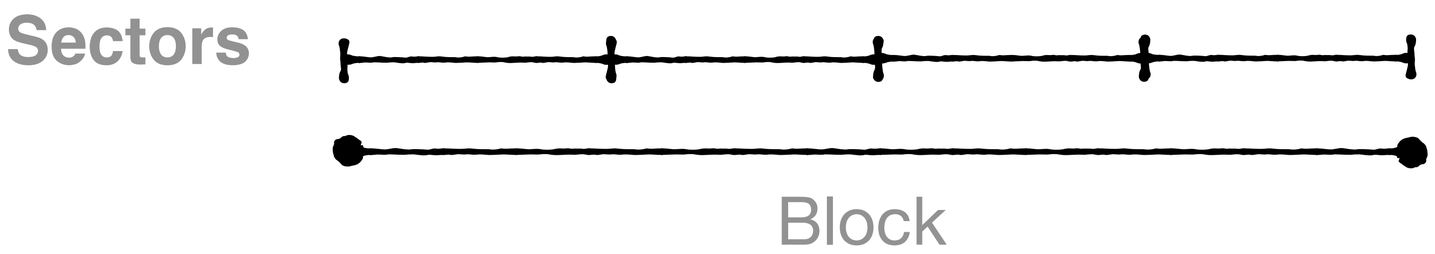
Query: check k / s hashes per sector sequentially



Query: check k / s hashes per sector sequentially

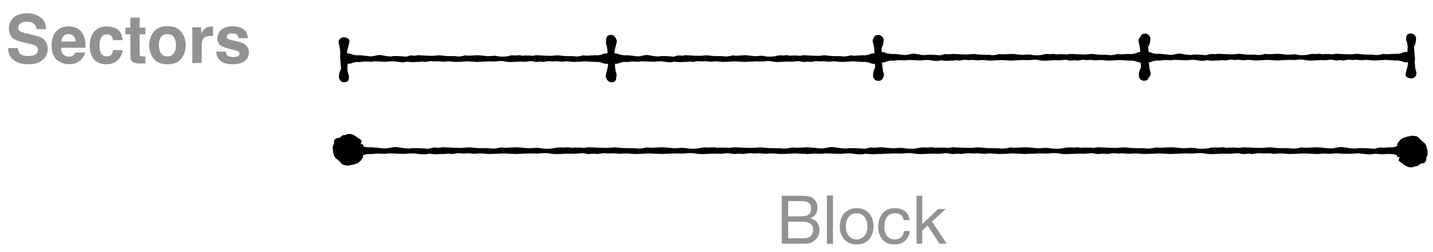


Further ways to optimize?



Further ways to optimize?

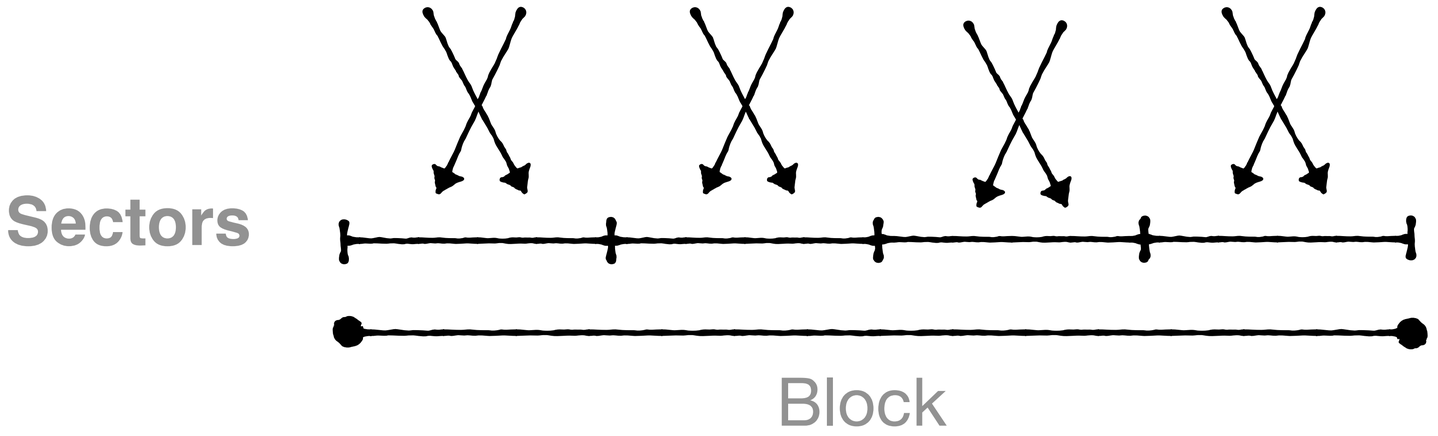
AVX - SIMD



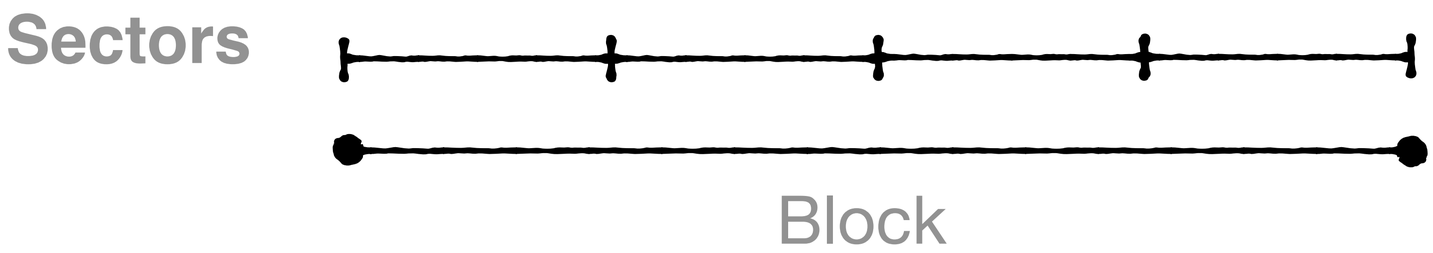
Further ways to optimize?

AVX - SIMD

Operate on each sector in parallel

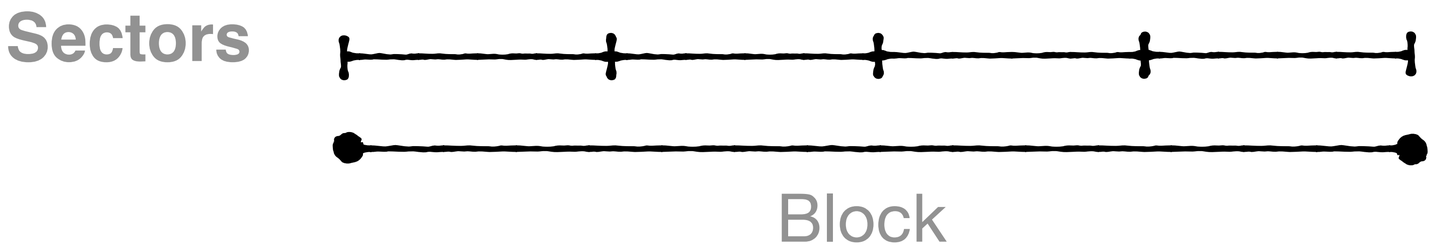


Problems with Sectorized Bloom filters?



Problems with Sectorized Bloom filters?

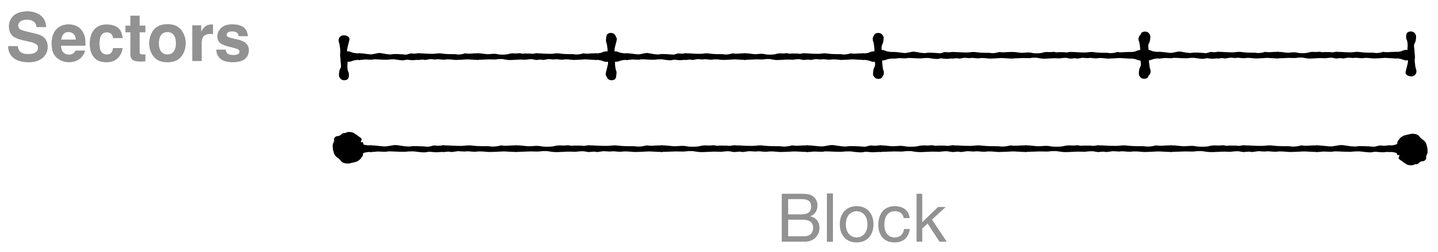
 # hashes must be multiple of # sectors



Problems with Sectorized Bloom filters?

hashes must be multiple of # sectors

Why is this bad?

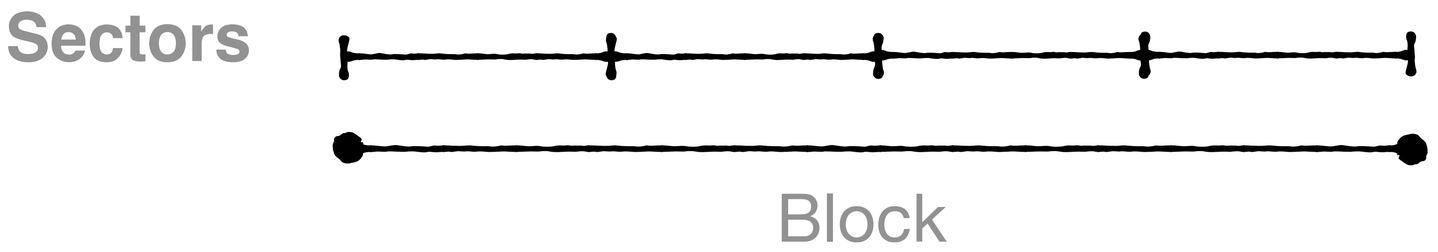


Problems with Sectorized Bloom filters?

hashes must be multiple of # sectors

Why is this bad?

Force using sub-optimal # hash functions



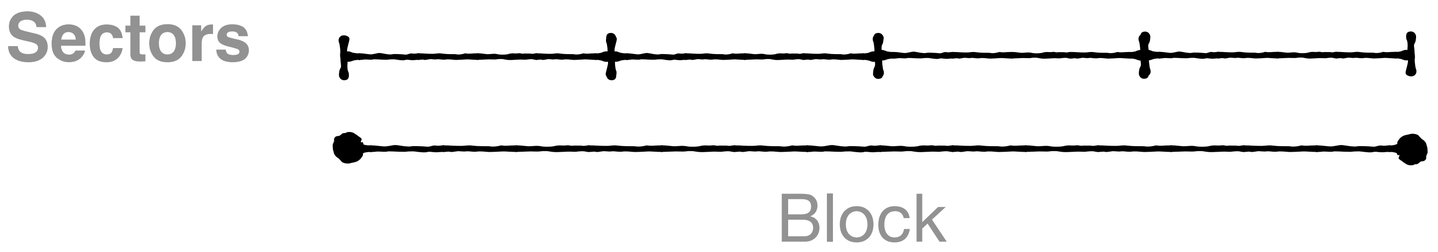
Problems with Sectorized Bloom filters?

hashes must be multiple of # sectors

Why is this bad?

Force using sub-optimal # hash functions

Harm FPR



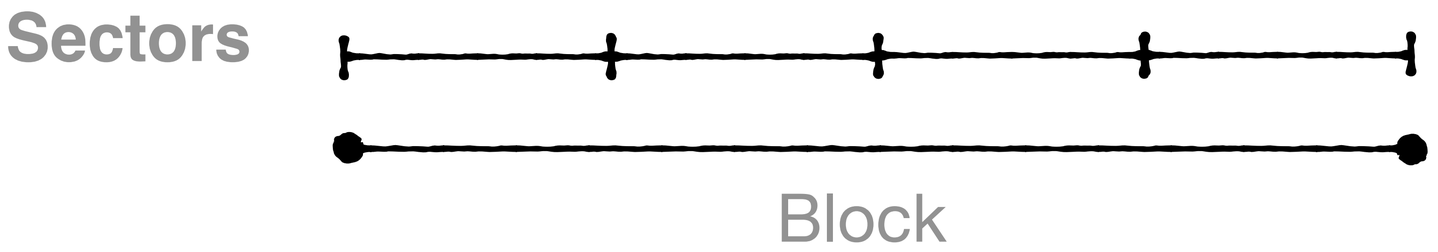
Problems with Sectorized Bloom filters?

hashes must be multiple of # sectors

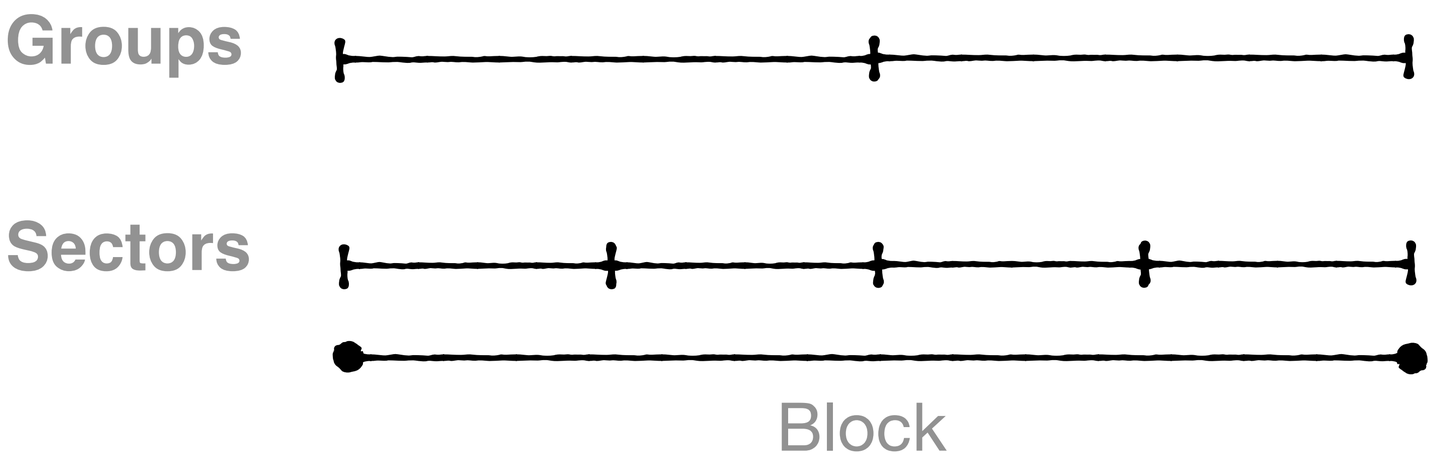
Why is this bad?

Force using sub-optimal # hash functions

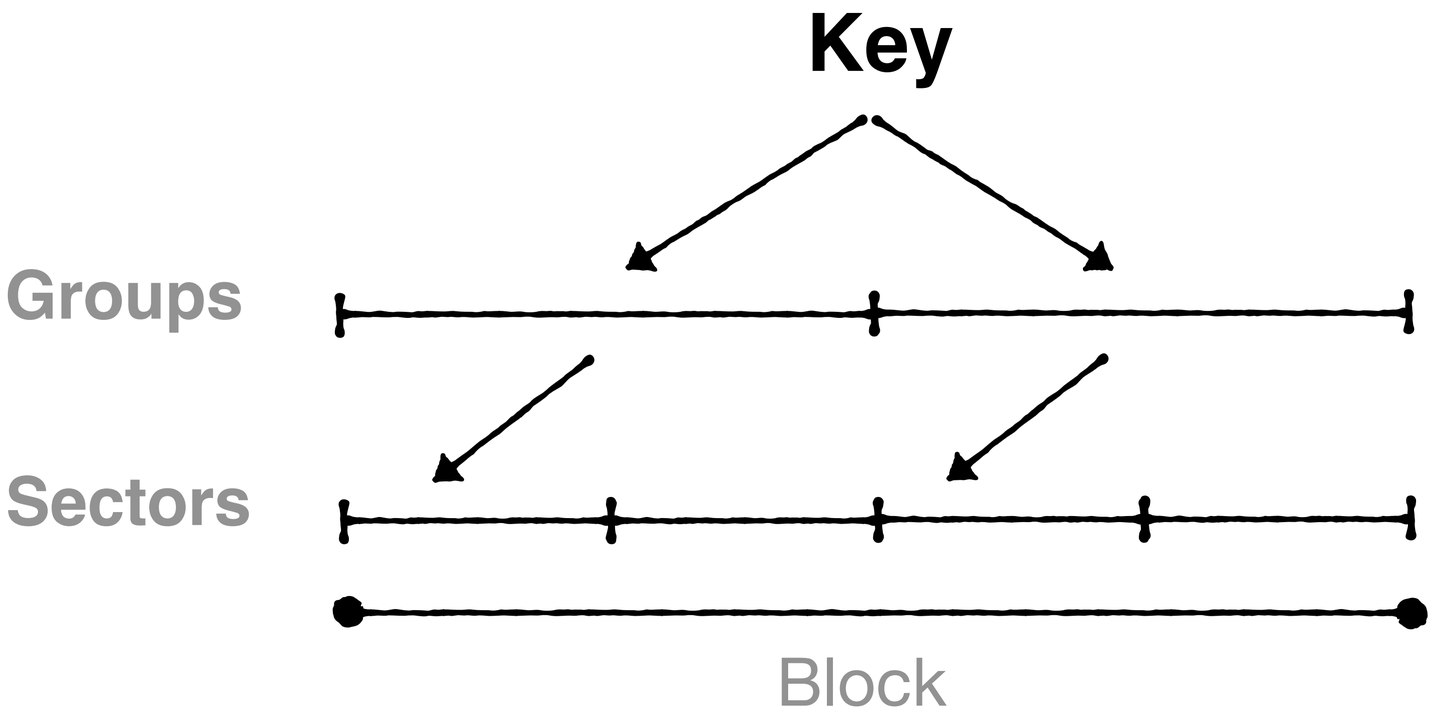
Harm FPR - solutions?



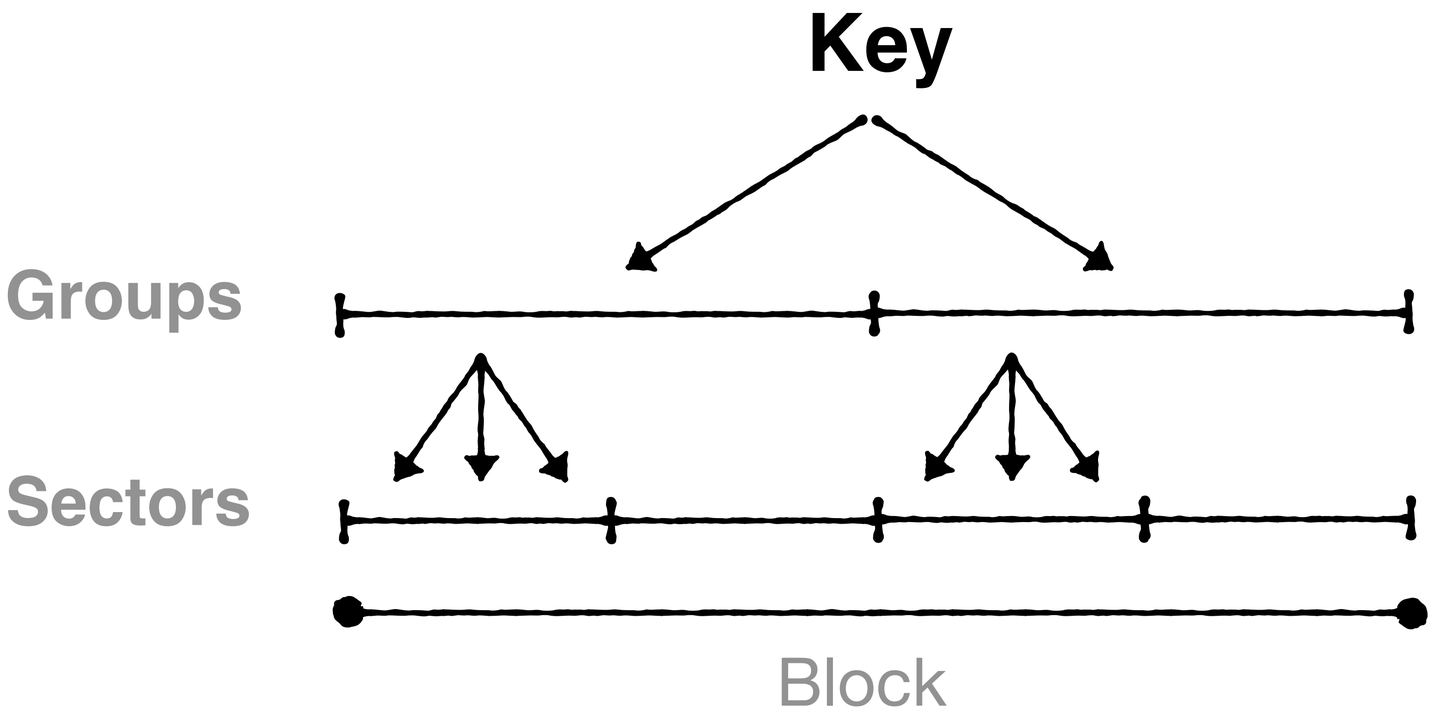
Divide sectors into Z groups



Map each key to one sector per group based on its hash

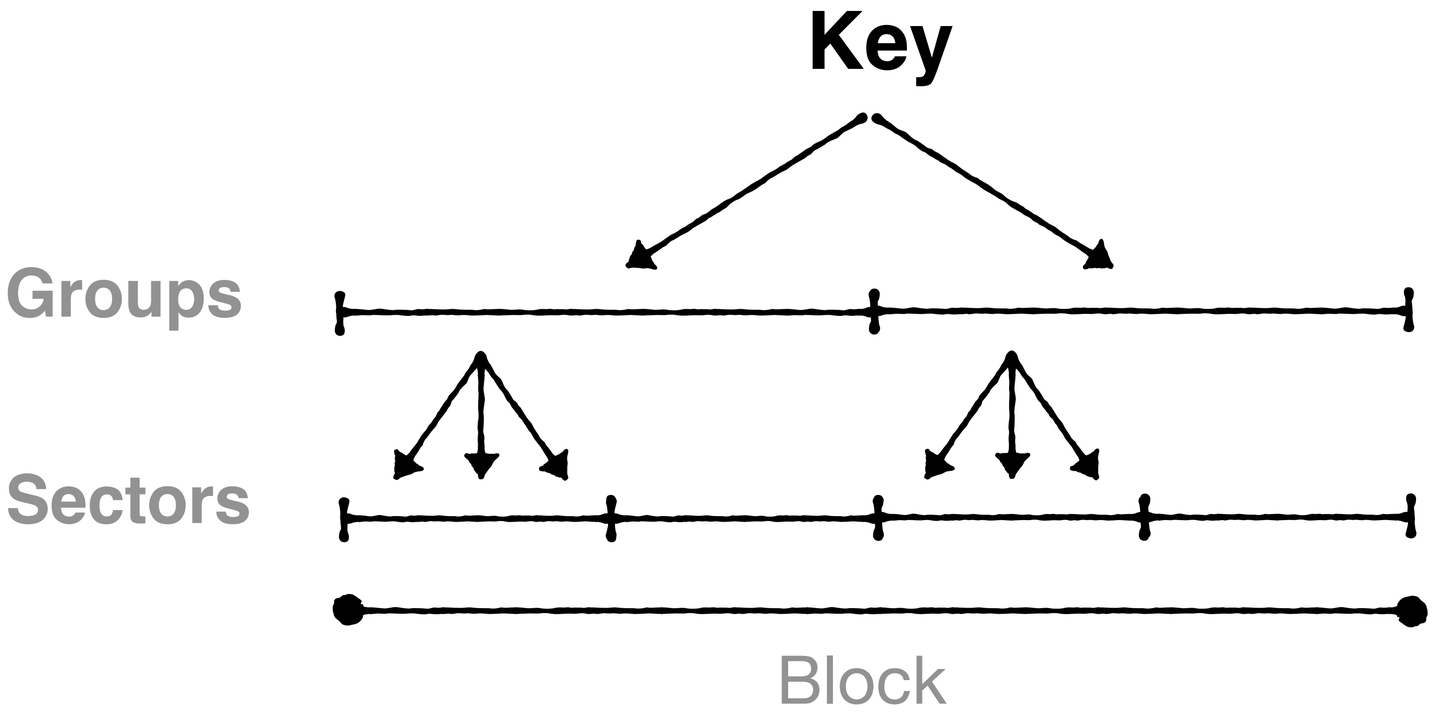


Hash bits only to relevant sector in each group

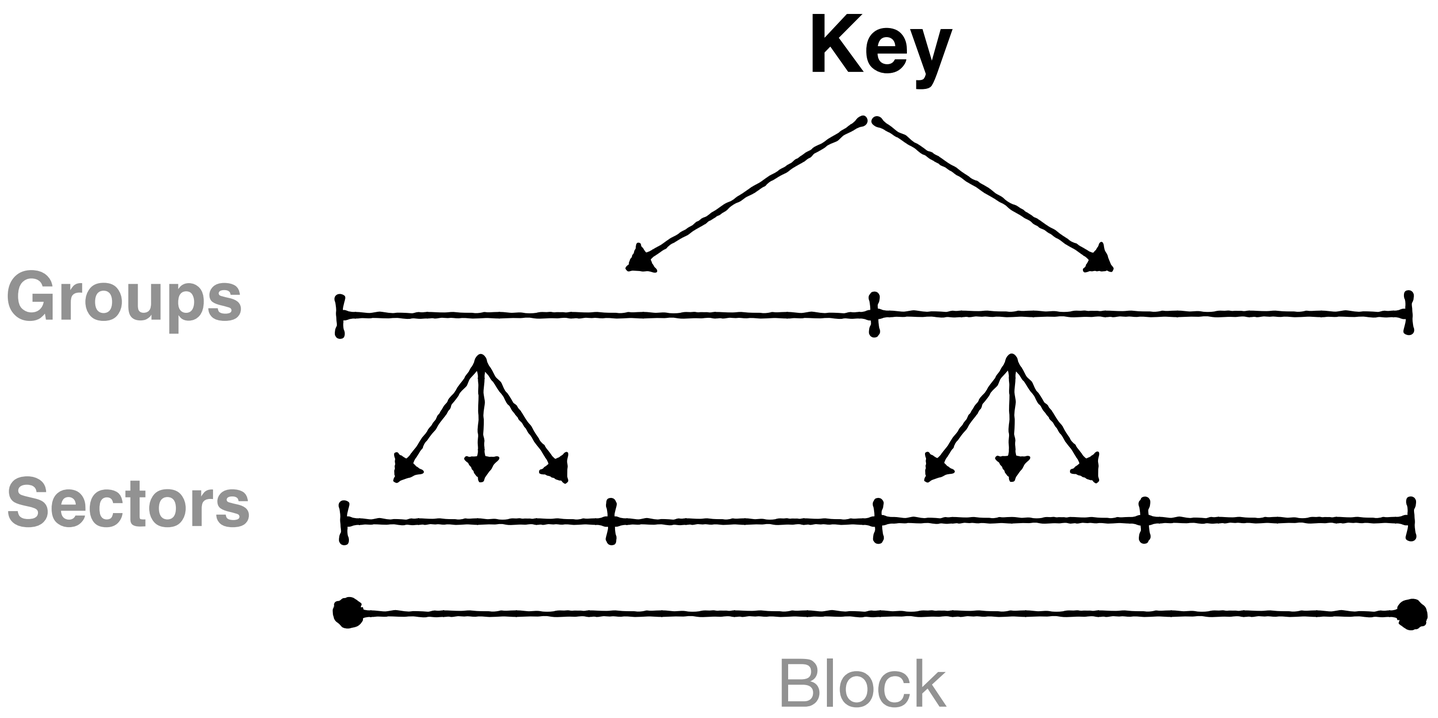


Hash bits only to relevant sector in each group

e.g., here we can use 6 hashes :)



Hash bits only to relevant sector in each group



Nearly best of both worlds :) fast & low FPR

Break

Bloom

$$FPR\ \varepsilon \approx 2^{-M/N \cdot \ln(2)}$$

Bloom

$$FPR\ \varepsilon \approx 2^{-M/N \cdot \ln(2)}$$

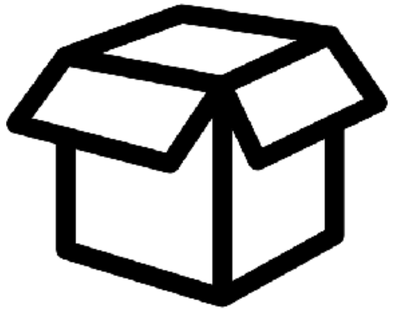
Lower Bound

???

Lower Bound for Filter Memory

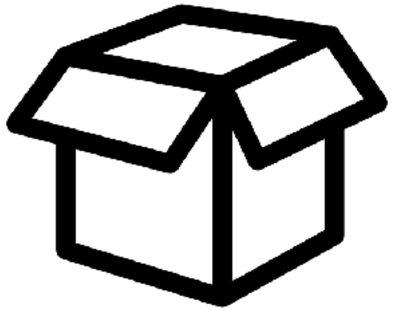
Lower Bound for Filter Memory

Assume nothing about implementation



Lower Bound for Filter Memory

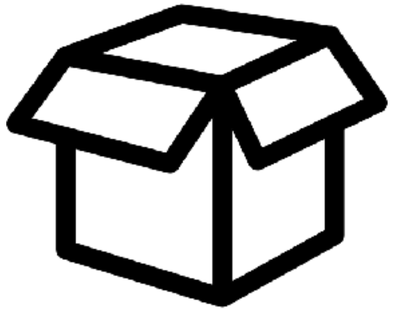
Assume nothing
about implementation



Analyze with respect to filter specification

Lower Bound for Filter Memory

Assume nothing about implementation



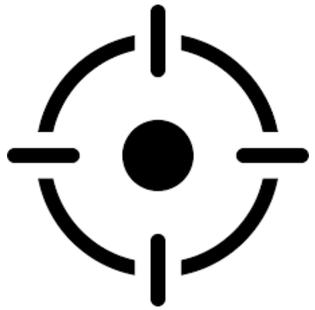
Analyze with respect to filter specification

ε - FPR

N - # entries

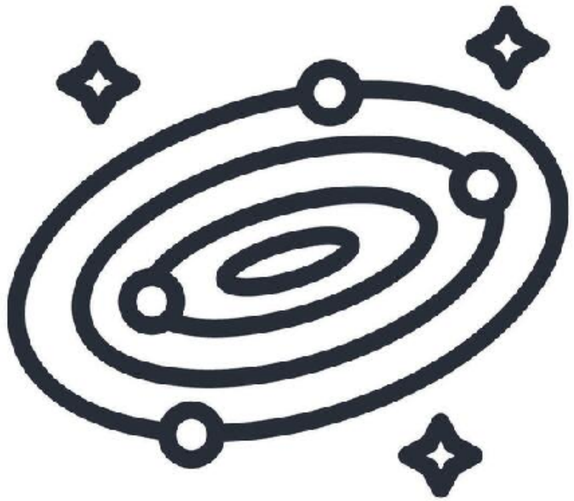
U - Universe size

Lower Bound for **Exact Set**



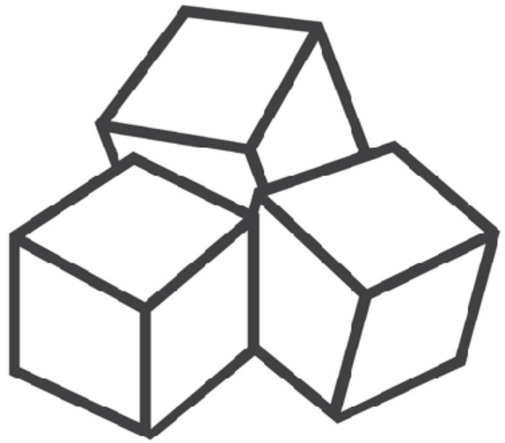
Lower Bound for Exact Set

Out of Universe U, store N entries



Lower Bound for Exact Set

(U choose N) combinations



Lower Bound for Exact Set

$\log_2$(U choose N) bits

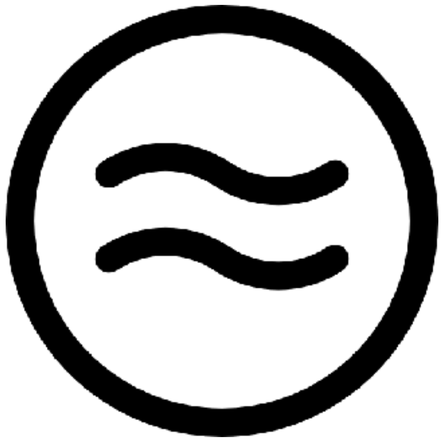
to encode a unique combination

Lower Bound for Exact Set

$\log_2(\text{U choose N}) \approx \mathbf{N \cdot \log_2(U / N)}$ bits

for large U

Lower Bound for **Filter - Approximate Set**



Lower Bound for **Filter**

$$|\text{Filter}| + |\text{Disambiguation}| \geq |\text{Exact Set}|$$

$$|\text{Filter}| + |\text{Disambiguation}| \geq |\text{Exact Set}|$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\textbf{Disambiguation}| \geq |\text{Exact Set}|$$

What information must we add the filter to turn it into an exact set?

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\text{Disambiguation}| \geq N \cdot \log_2(U / N)$$

Plug in

Legend

ε - FPR
N - # entries
U - Universe size

$$|\mathbf{Filter}| + |\mathrm{Disambiguation}| \geq N \cdot \log_2(U / N)$$

Query filter U times

Legend

ε - FPR
N - # entries
U - Universe size

$$\mathbf{|Filter|} + \mathbf{|}\text{Disambiguation}\mathbf{|} \geq N \cdot \log_2(U / N)$$

Tells us all positive keys

$$\mathbf{N + \varepsilon \cdot U}$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\mathbf{Filter}| + |\mathrm{Disambiguation}| \geq N \cdot \log_2(U / N)$$

Tells us all positive keys

$$\varepsilon \cdot U$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\textbf{Disambiguation}| \geq N \cdot \log_2(U / N)$$

Of all positives ε · U, which keys are positive N

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\textbf{Disambiguation}| \geq N \cdot \log_2(U / N)$$

ε · U choose N

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\textbf{Disambiguation}| \geq N \cdot \log_2(U / N)$$

$$\log_2(\varepsilon \cdot U \text{ choose } N)$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + |\textbf{Disambiguation}| \geq N \cdot \log_2(U / N)$$

$$\textbf{N} \cdot \textbf{log}_2((\varepsilon \cdot \textbf{U}) / \textbf{N})$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| + N \cdot \log_2((\varepsilon \cdot U) / N) \geq N \cdot \log_2(U / N)$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| \geq N \cdot \log_2(U / N) - \mathbf{N \cdot \log_2((\varepsilon \cdot U) / N)}$$

Legend

ε - FPR
N - # entries
U - Universe size

$$|\text{Filter}| \geq N \cdot \log_2(1 / \varepsilon)$$

Legend

ε - FPR
N - # entries
U - Universe size

$$\varepsilon \geq 2^{-M/N}$$

Legend

ε - FPR
N - # entries
U - Universe size

Bloom

$\approx 2^{-M/N} \cdot 0.69$

Lower bound

$\boldsymbol{2^{-M/N}}$

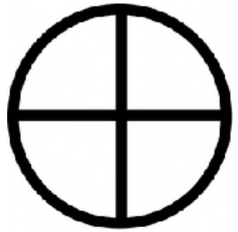
Bloom

$\approx 2^{-M/N} \cdot 0.69$

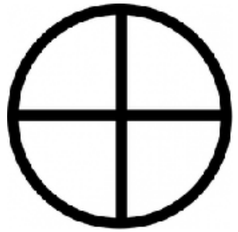
???

Lower bound

$2^{-M/N}$

Bloom	**XOR Filter**	Lower bound
		
$\approx 2^{-M/N \cdot 0.69}$	$\approx 2^{-M/N \cdot 0.81}$	$\approx 2^{-M/N}$

XOR Filter

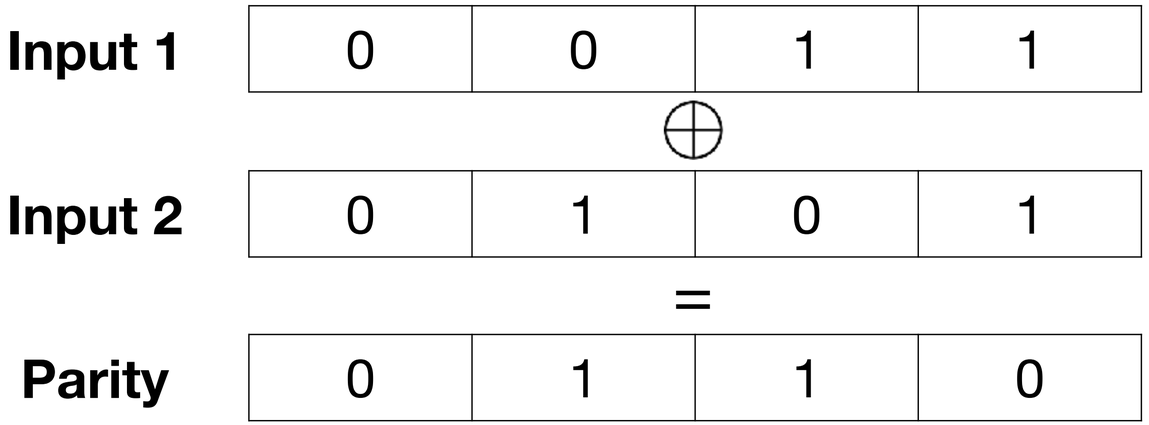


Xor Filters: Faster and Smaller Than Bloom Filters

Thomas Mueller Graf, Daniel Lemire

Journal of Experimental Algorithmics, 2020

XOR Operator



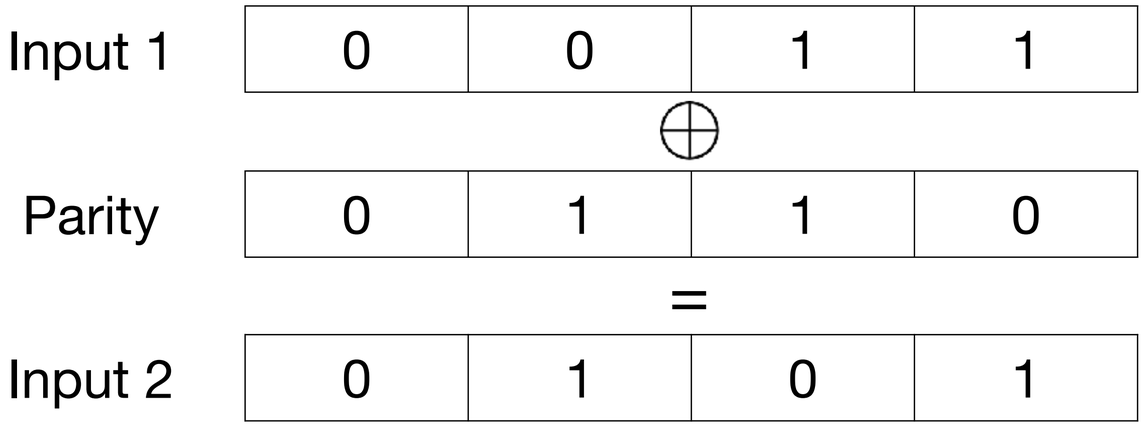
Parity can help recover any input

Suppose we lost input 2

Input 1	0	0	1	1
Parity	0	1	1	0

Parity can help recover any input

Suppose we lost input 2



Recovered

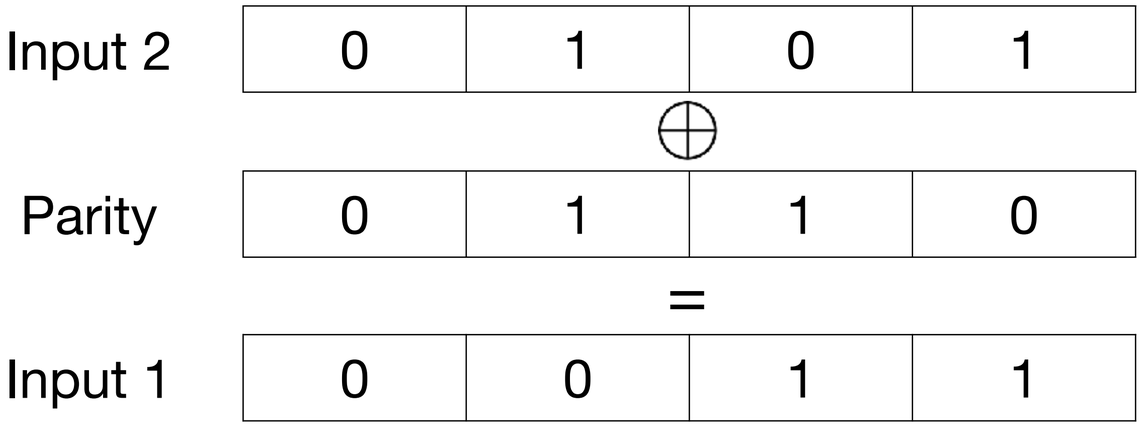
Parity can help recover any input

Or suppose we lost input 1

Input 2	0	1	0	1
Parity	0	1	1	0

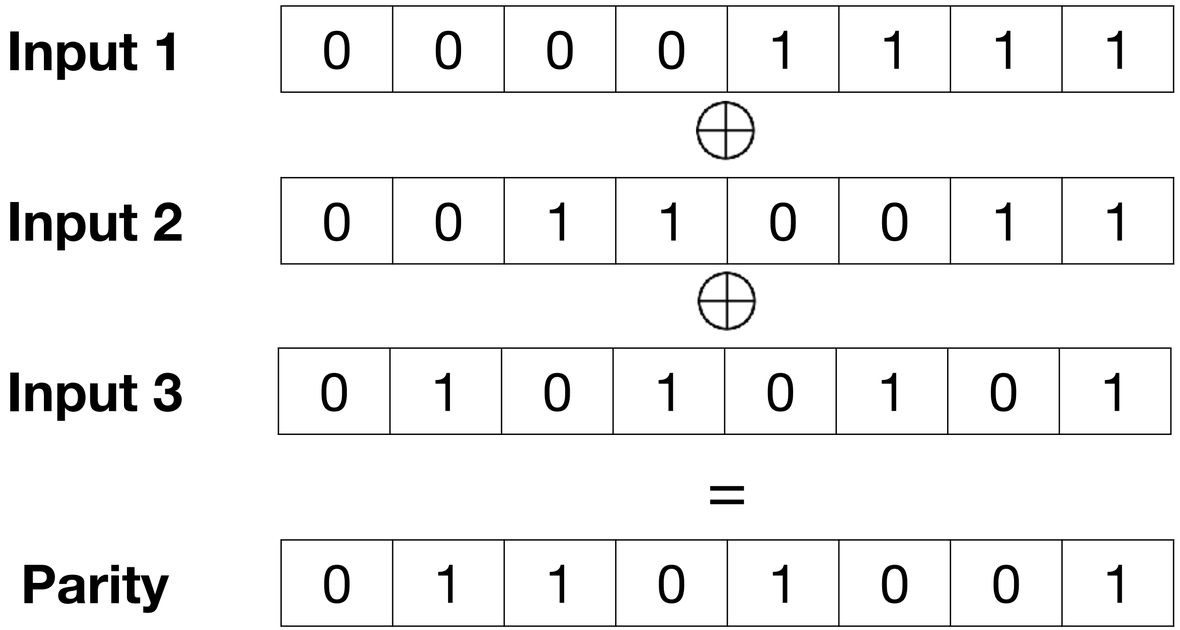
Parity can help recover any input

Or suppose we lost input 1

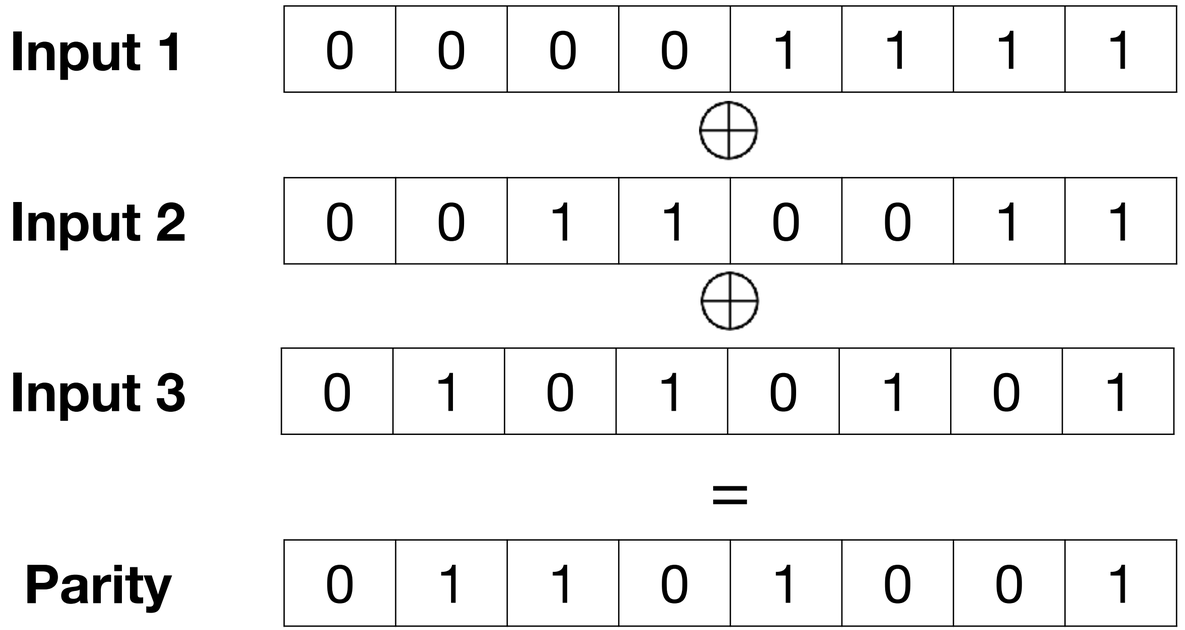


Recovered

XOR is commutative and associative



XOR is commutative and associative



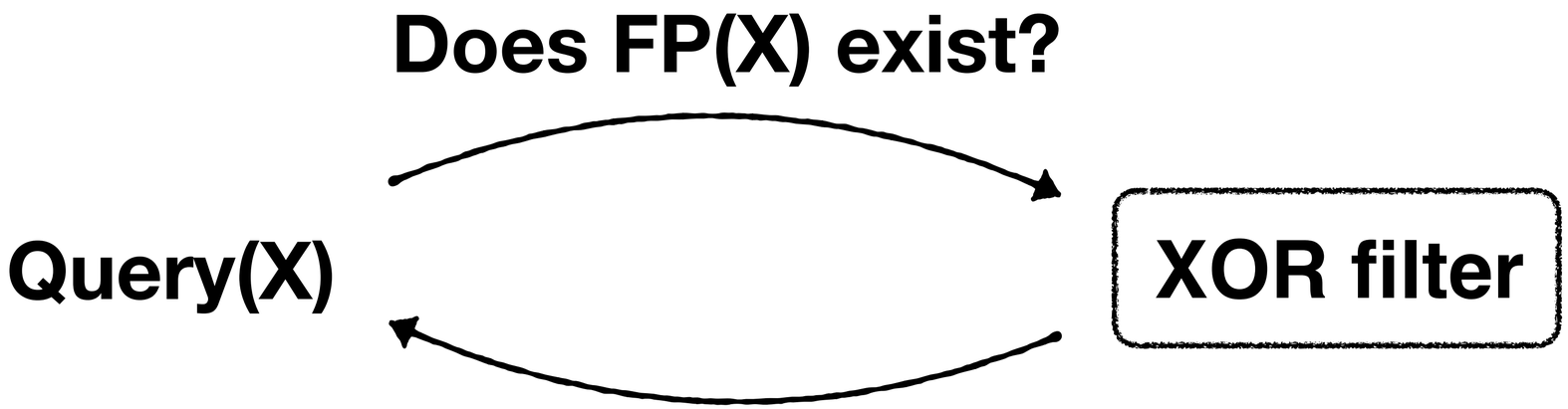
Parity can recover any input, as long as we also have all the other inputs

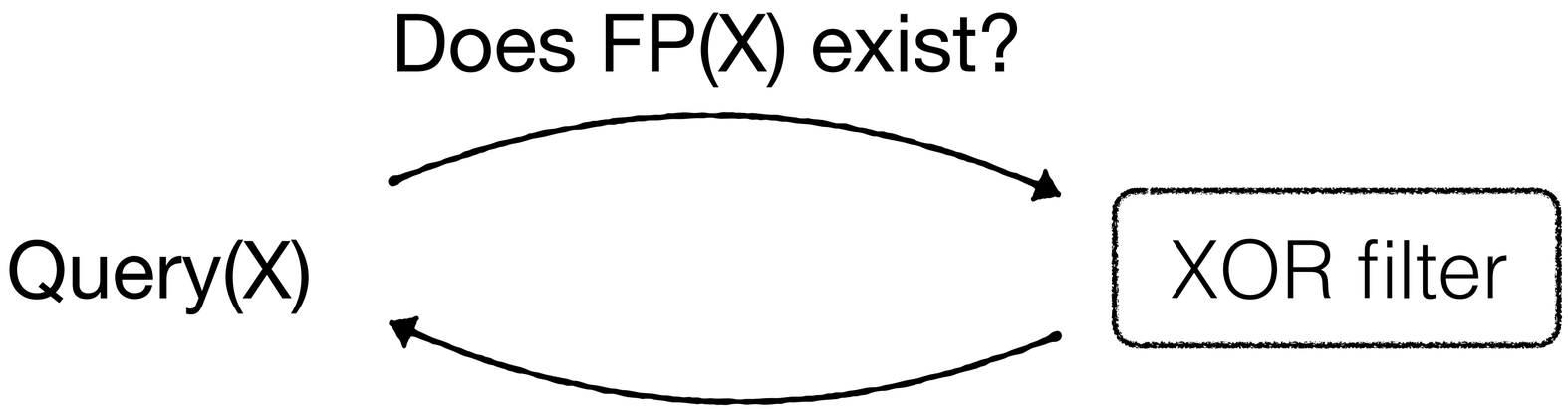
XOR filter stores a fingerprint for each key

FP(🔑) = 

XOR filter stores a fingerprint for each key

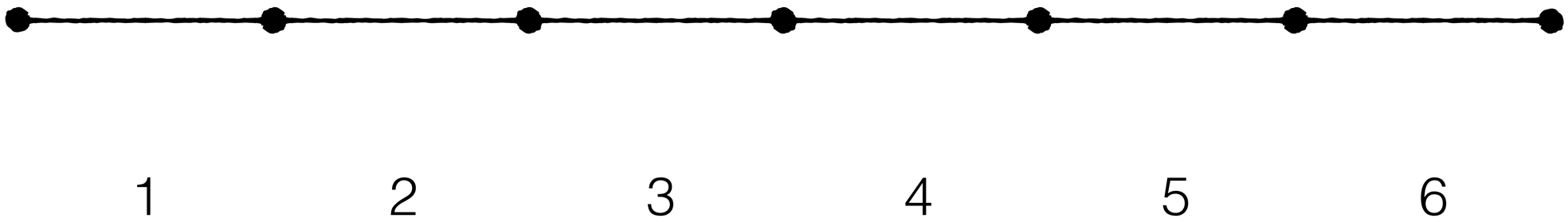
Example: **FP(X) =** $\overbrace{0100}^{\textbf{F bits}}$


Does FP(X) exist?
Query(X)
XOR filter

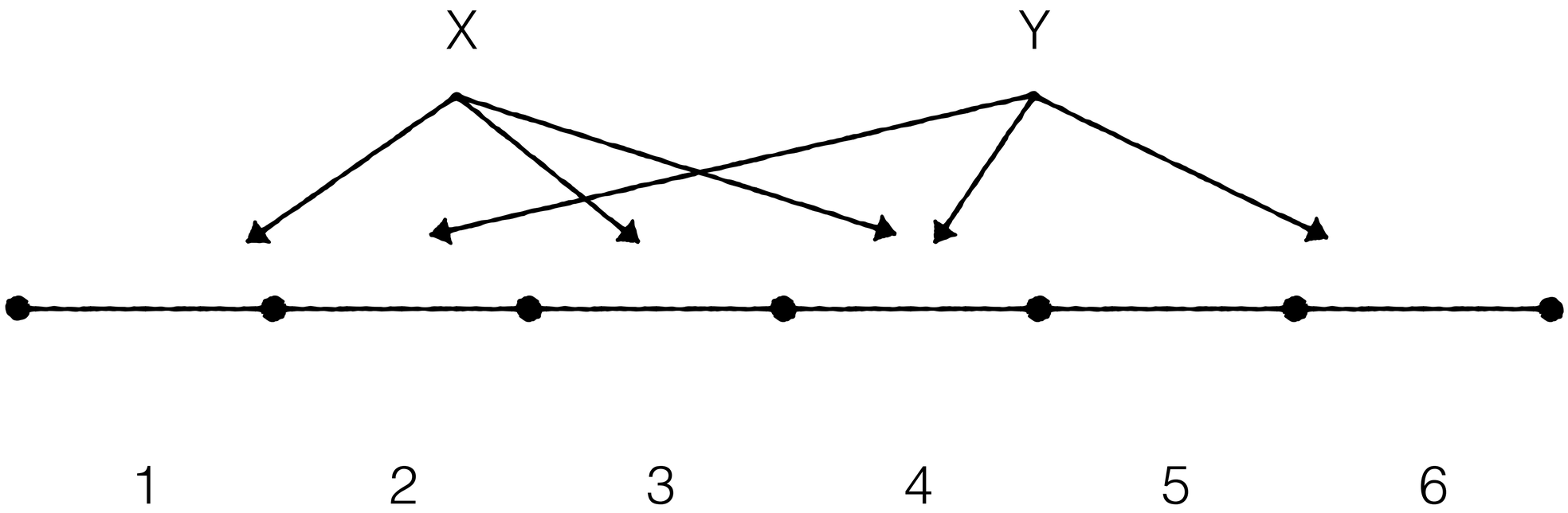


1. **True negative**
2. **True positive**
3. **False positive with probability 2^{-F}**

How does XOR filter store its fingerprints?

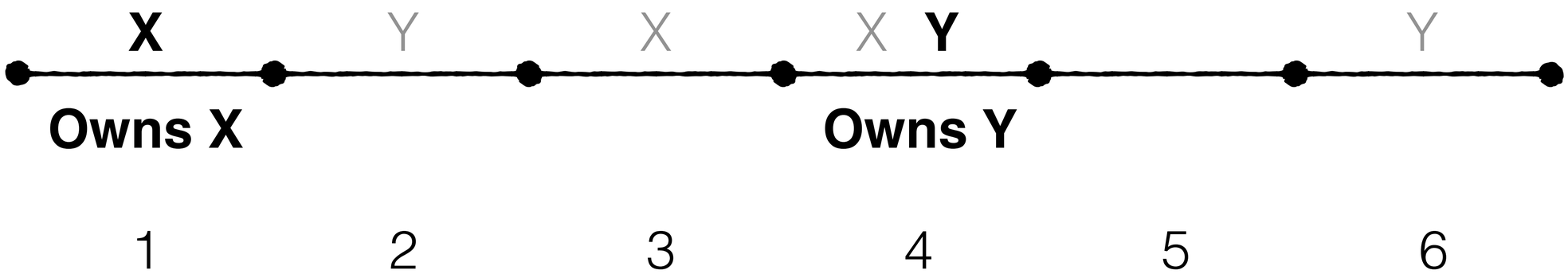


Hash each entry to three slots

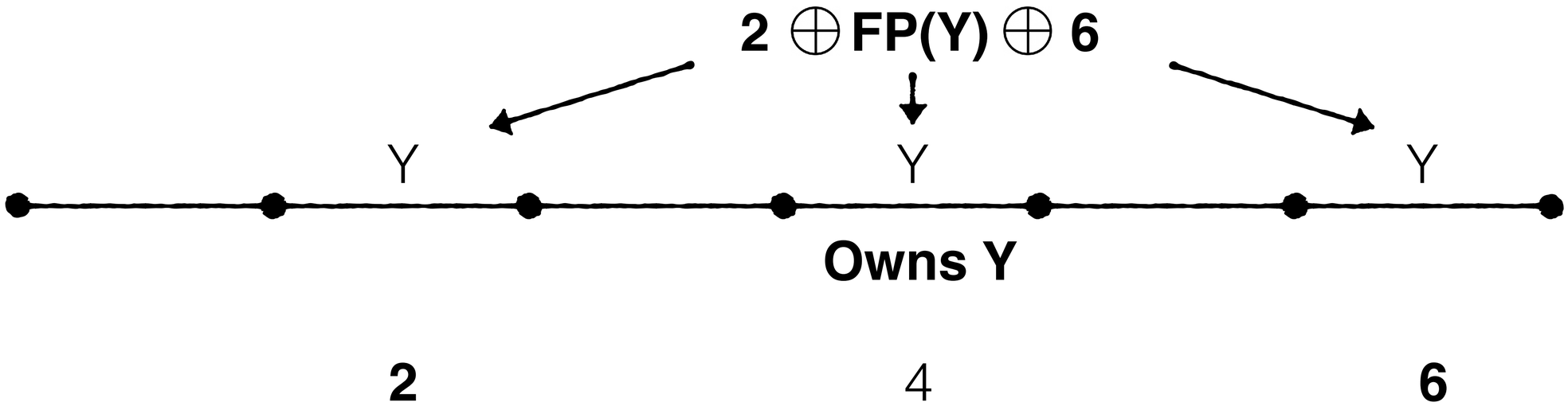


Assign one slot to uniquely own each entry

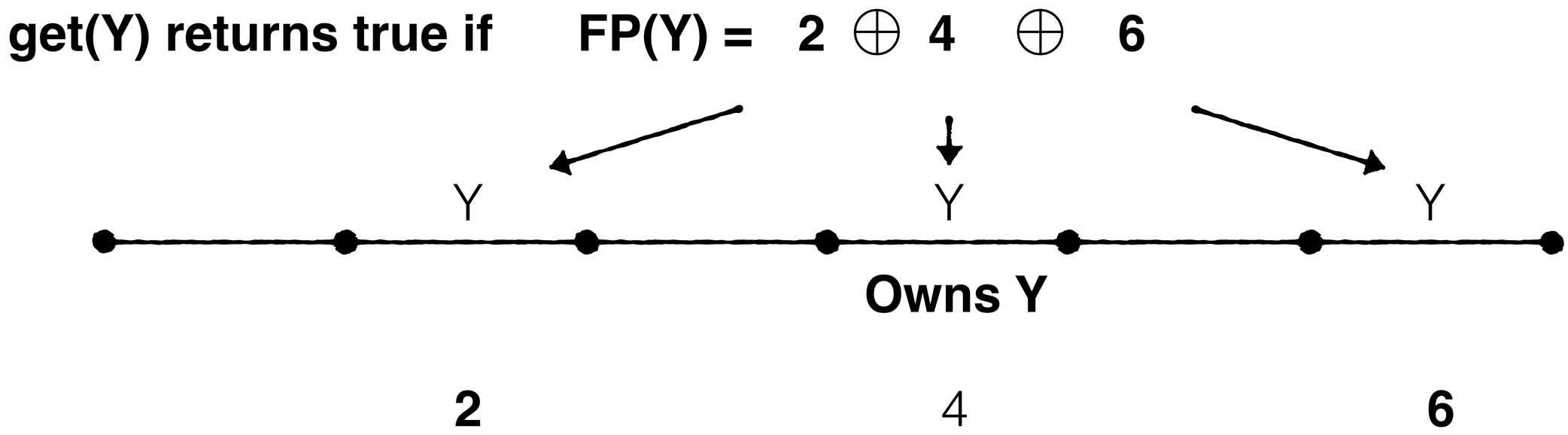
(More on this shortly)



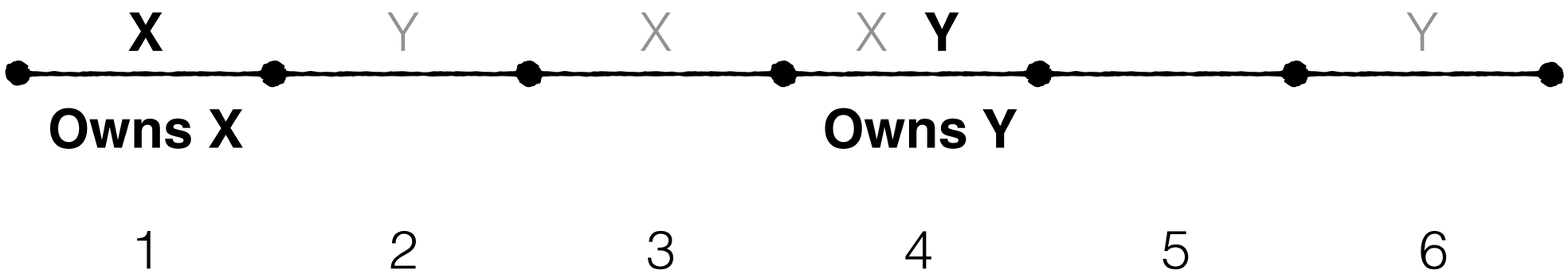
Each bucket stores XOR of fingerprint and other two slots



During queries, recover fingerprints by xoring three slots



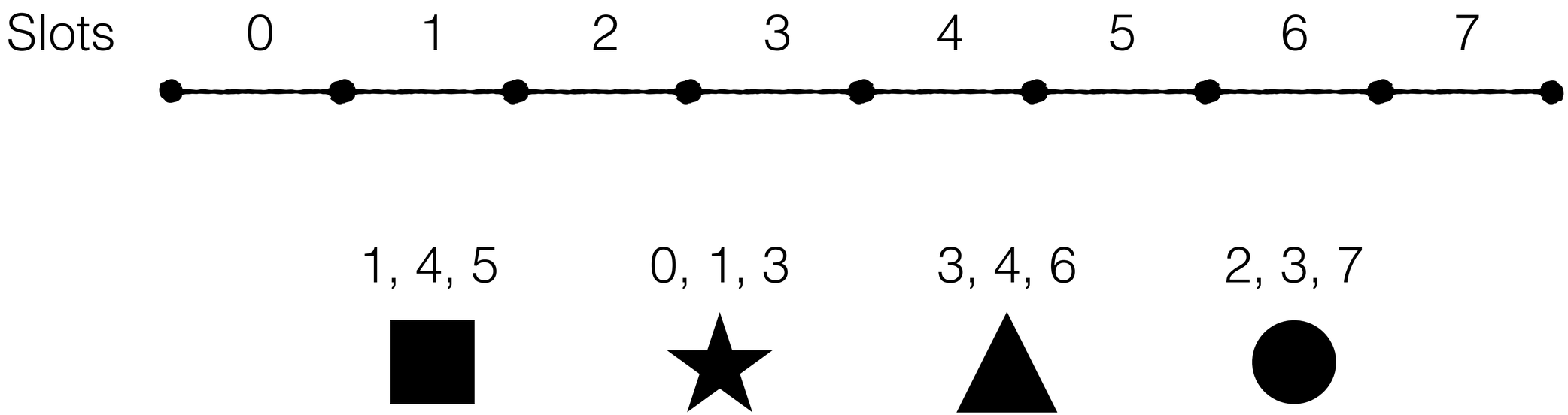
How to assign slots to own different entries?



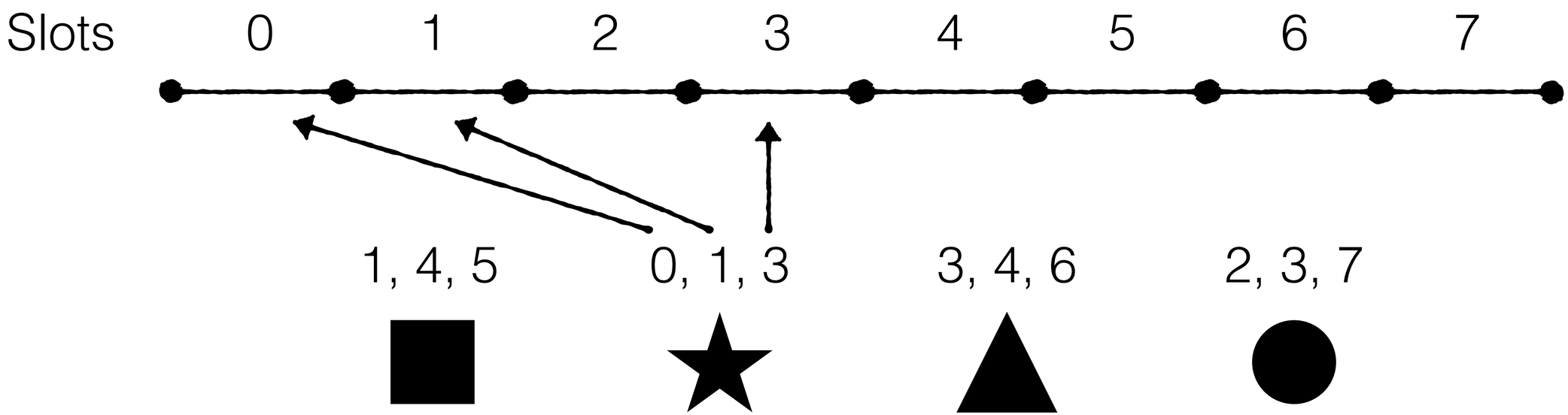
How to assign slots to own different entries?

Peeling

Peeling

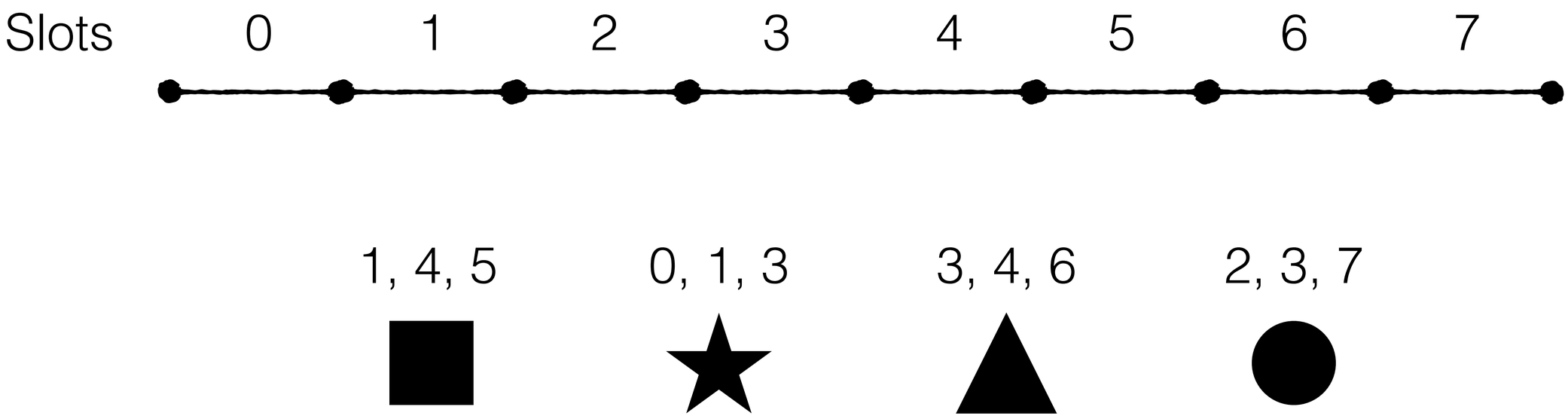


Peeling



Peeling

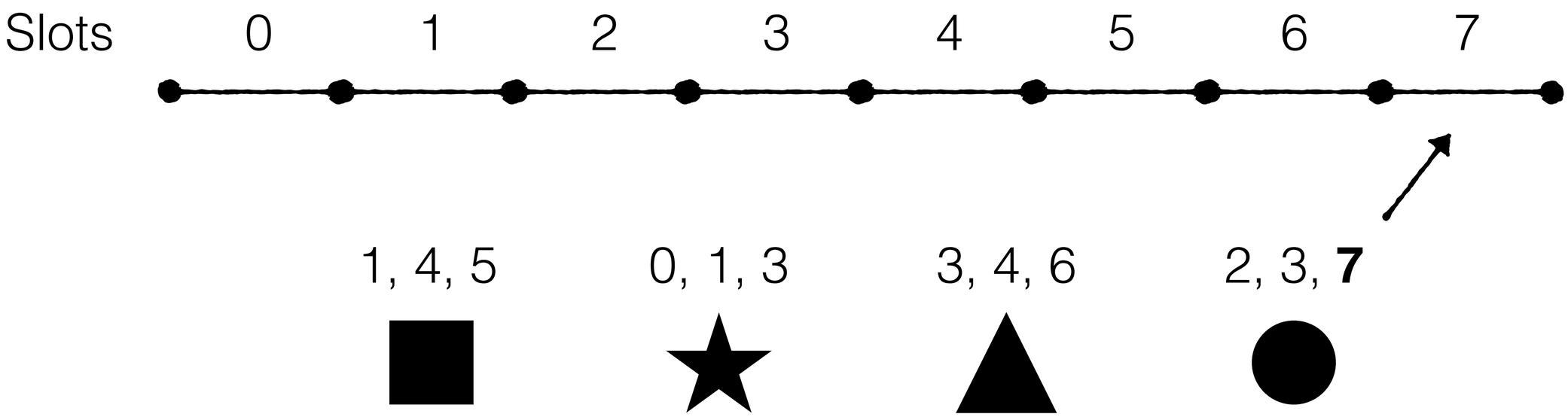
While not all keys have been assigned to a slot



Peeling

While not all keys have been assigned to a slot

Assign some entry x to some slot y that only entry x maps to



Peeling

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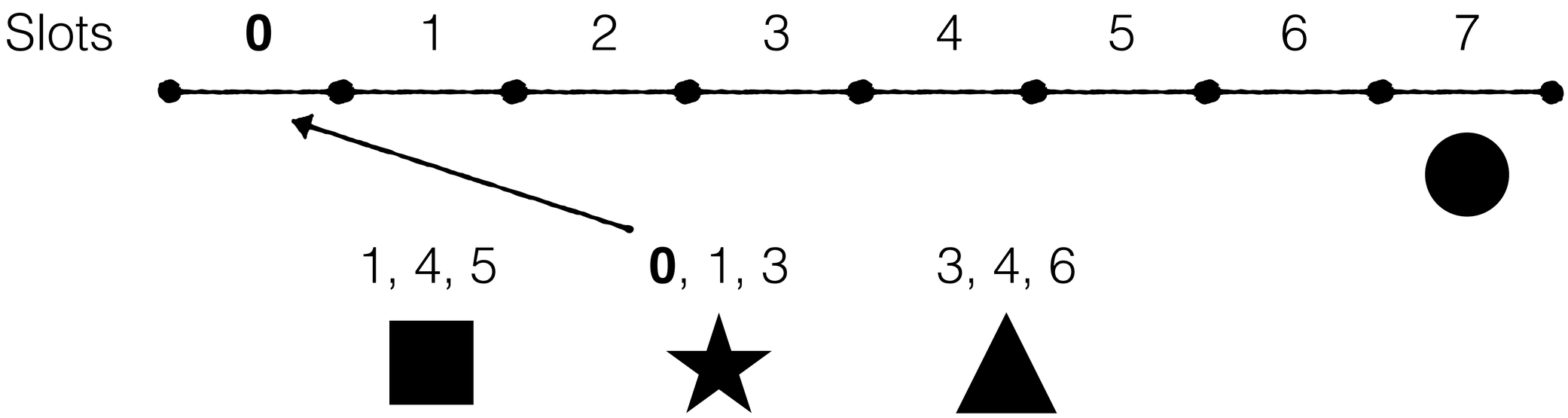

Peeling

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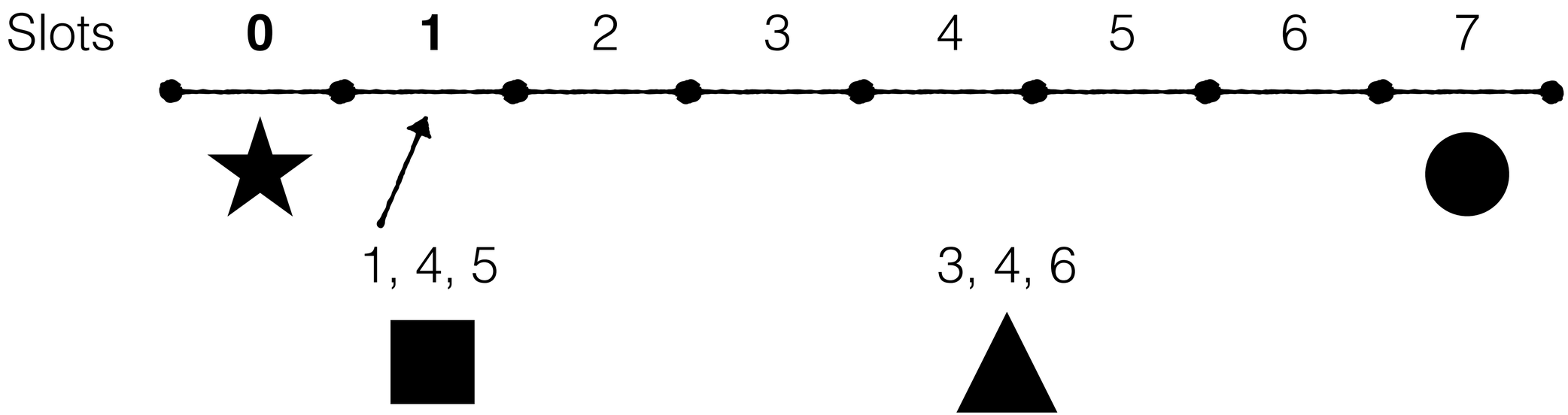

Peeling

While not all keys have been assigned to a slot

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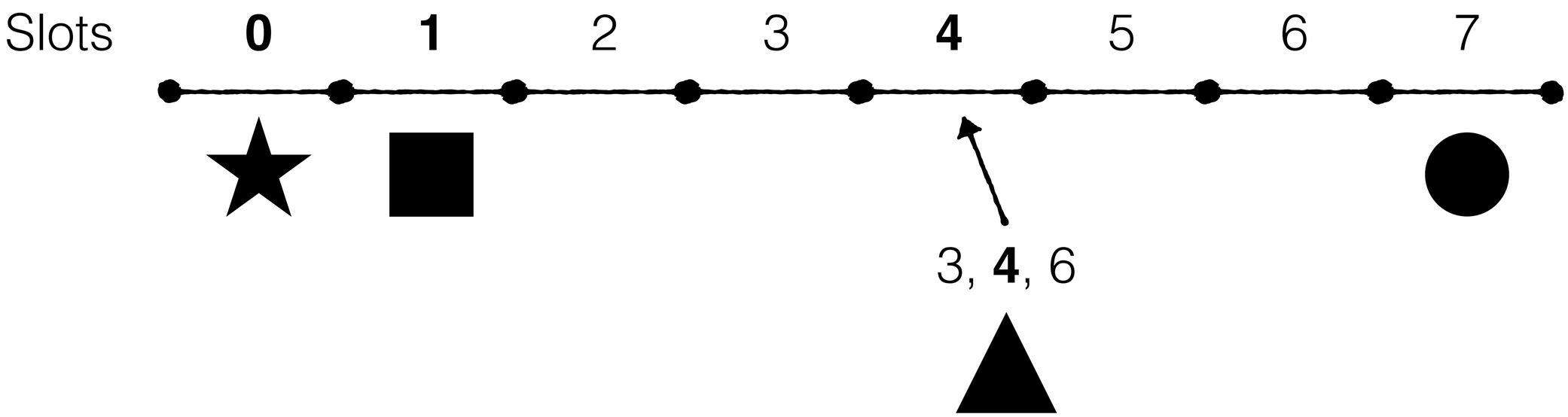
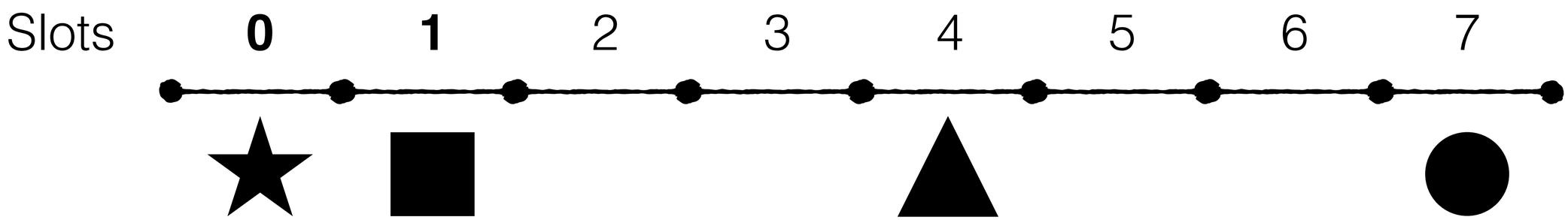
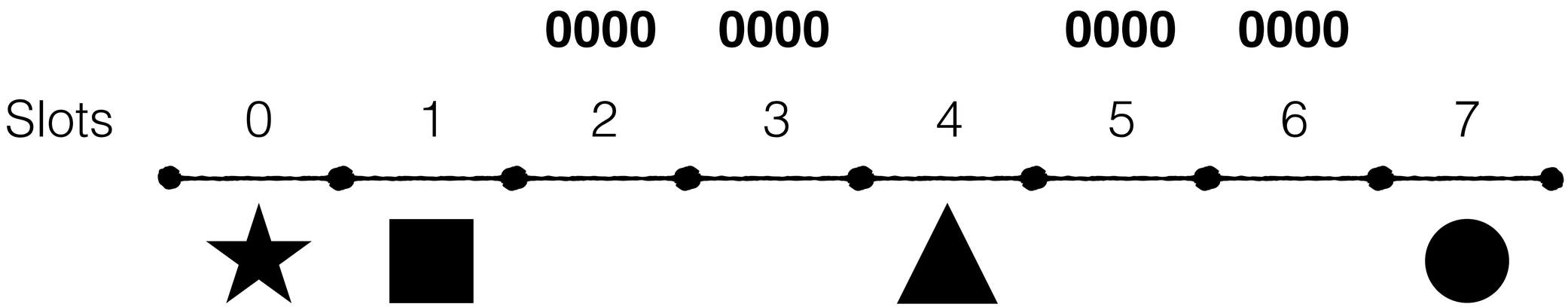


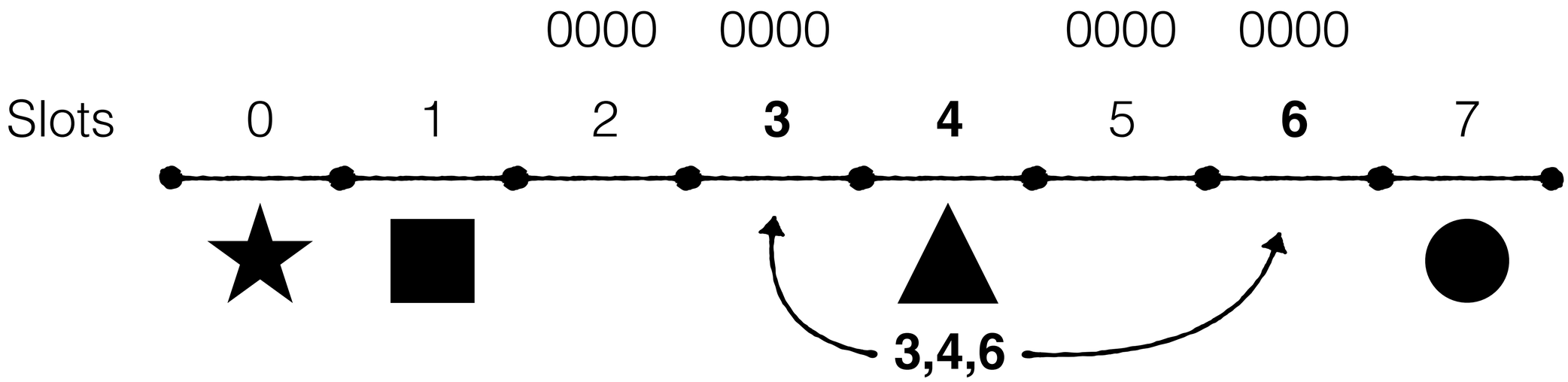

Slots
0
1
2
3
4
5
6
7

Populate all unassigned slots with zeros



Populate all unassigned slots with zeros

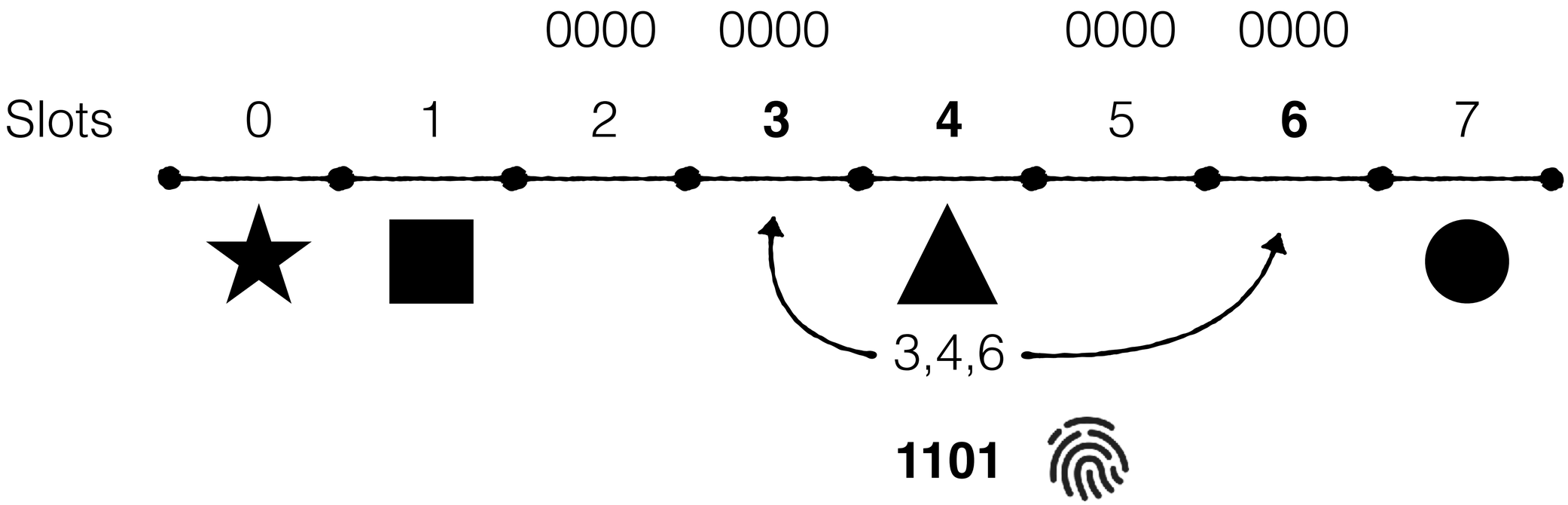
Find some entry whose only other candidate slots are populated



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

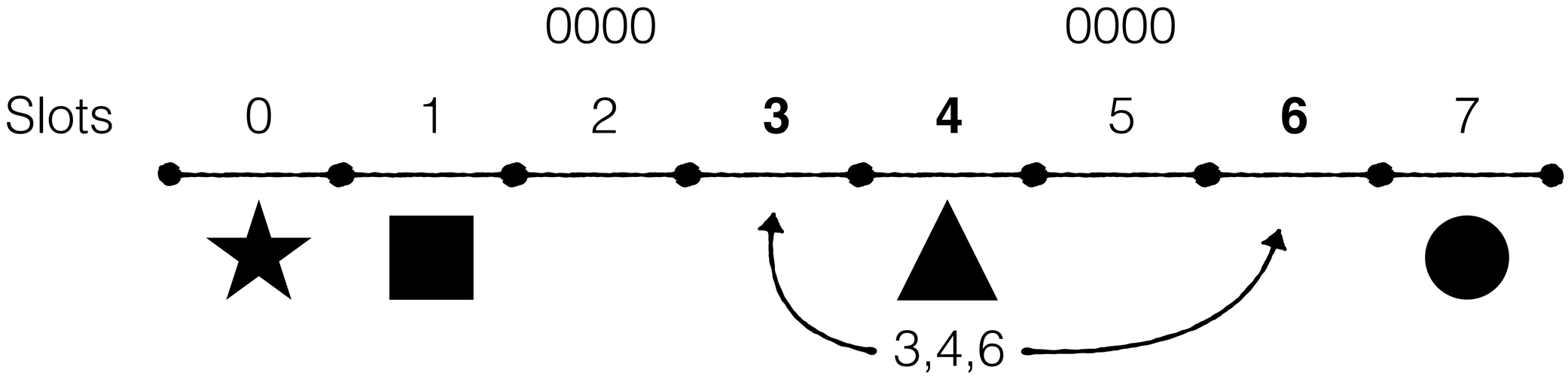
Xor its fingerprint with content at other slots and store



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

Xor its fingerprint with content at other slots and store

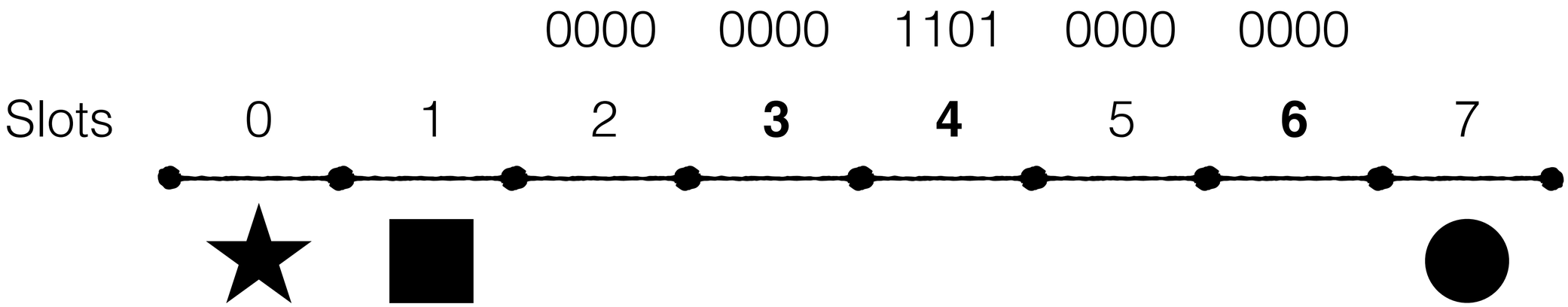


0000 ⊕ **1101** ⊕ 0000 = **1101**

Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

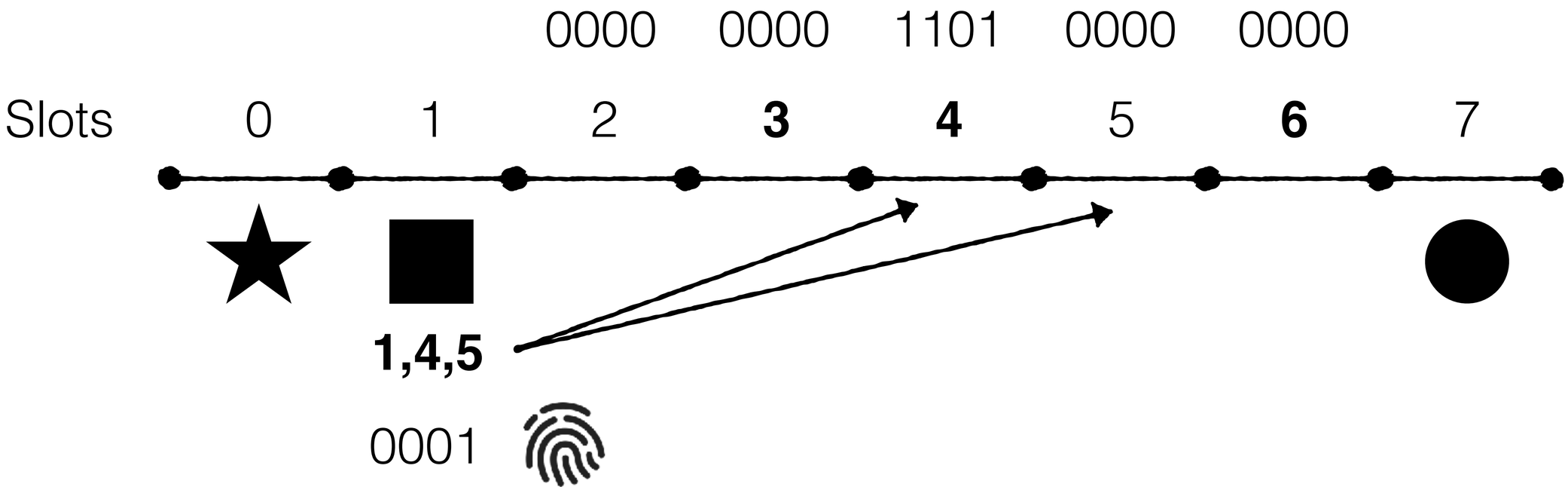
Xor its fingerprint with content at other slots and store



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

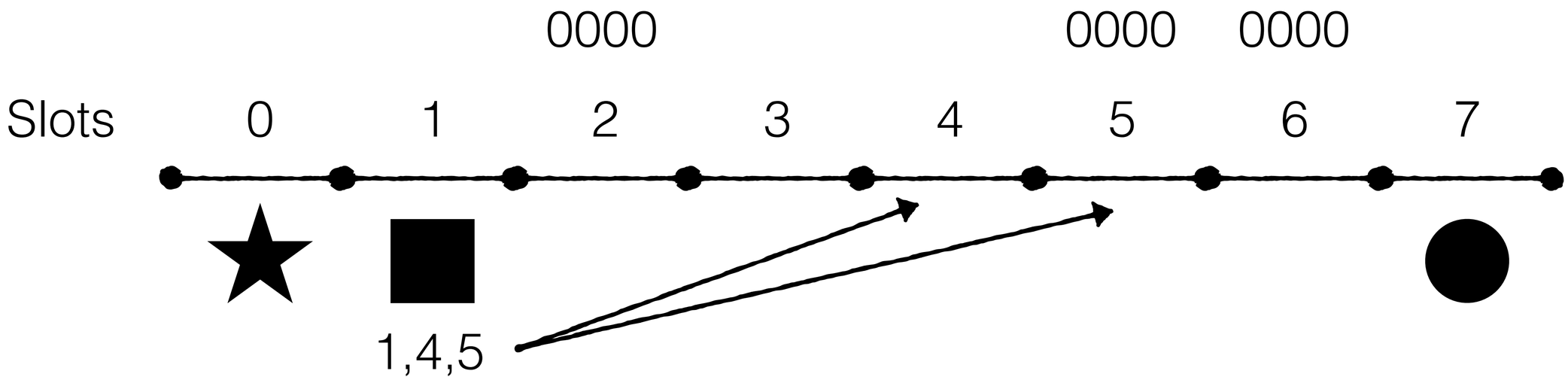
Xor its fingerprint with content at other slots and store



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

Xor its fingerprint with content at other slots and store

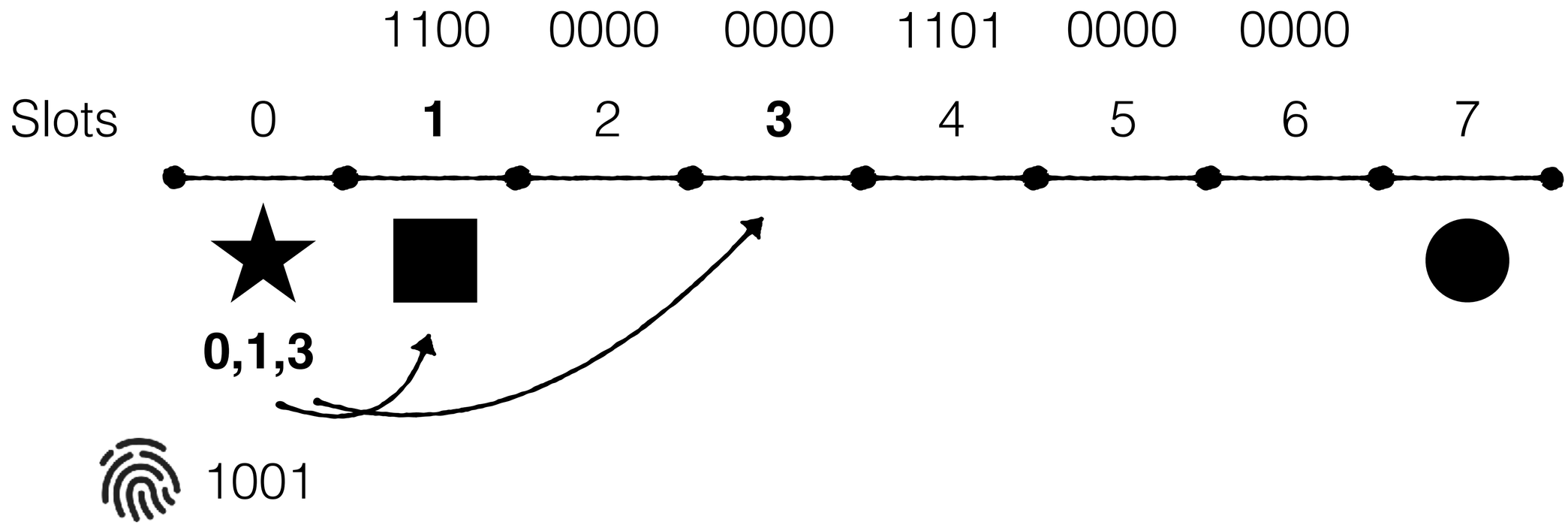


0000 ⊕ 0001 ⊕ 1101 = **1100**

Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

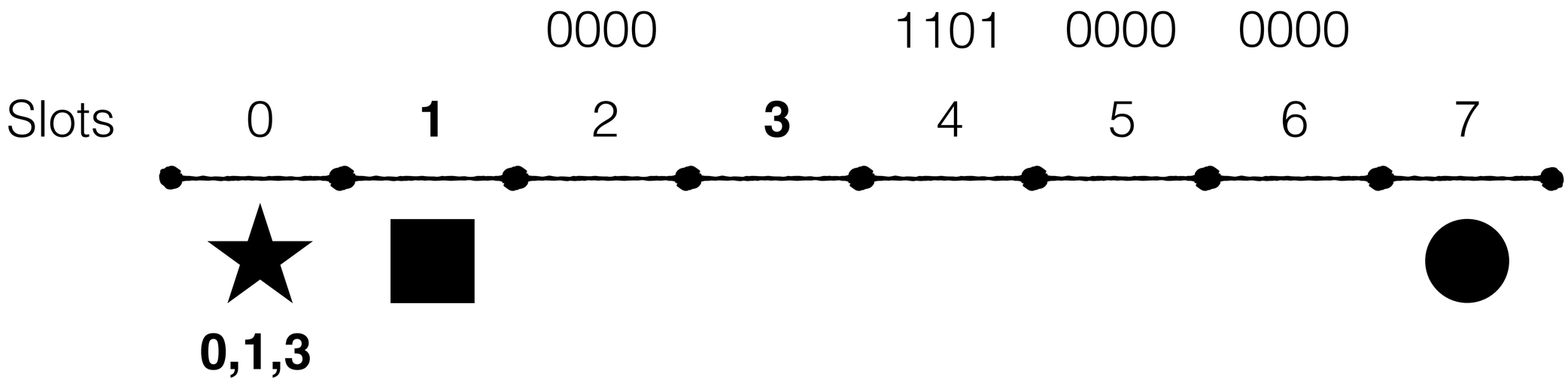
Xor its fingerprint with content at other slots and store



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

Xor its fingerprint with content at other slots and store

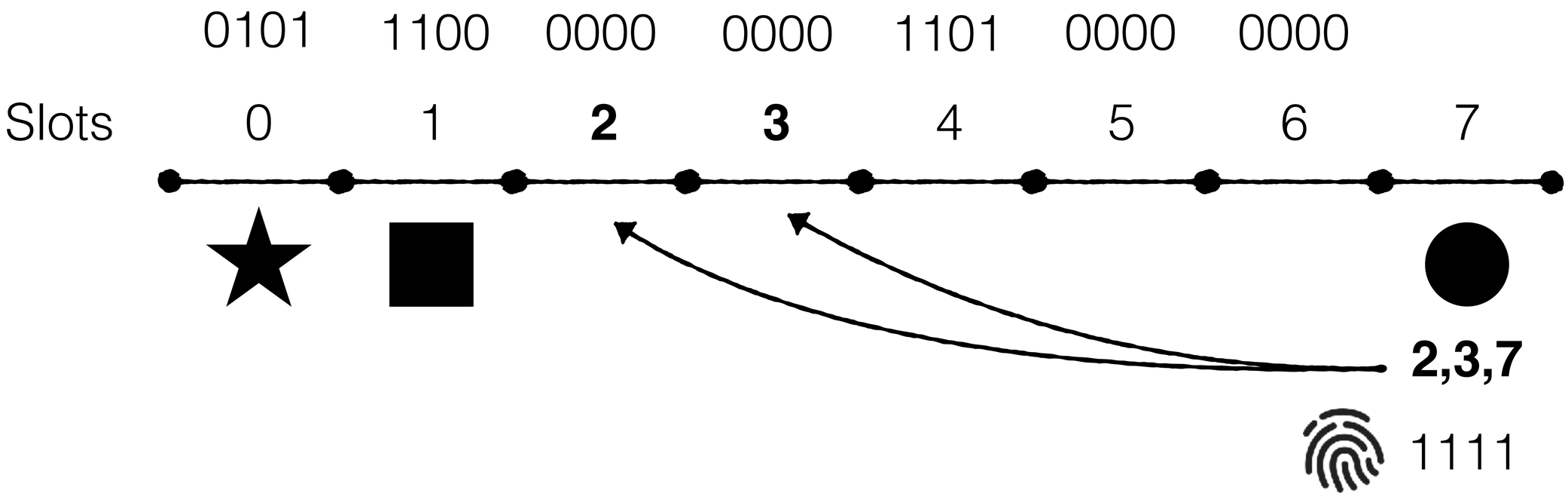


1100 ⊕ 1001 ⊕ 0000 = **0101**

Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

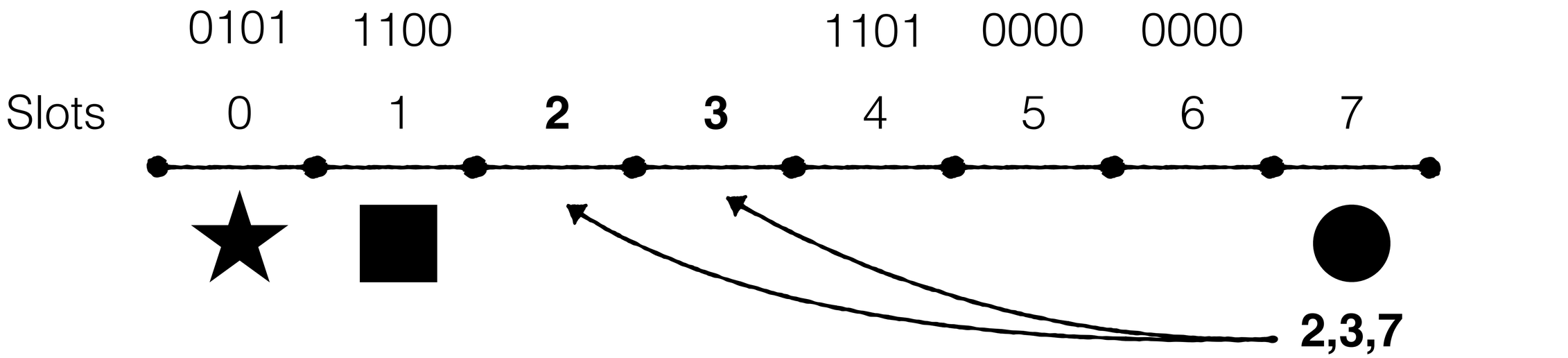
Xor its fingerprint with content at other slots and store



Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

Xor its fingerprint with content at other slots and store

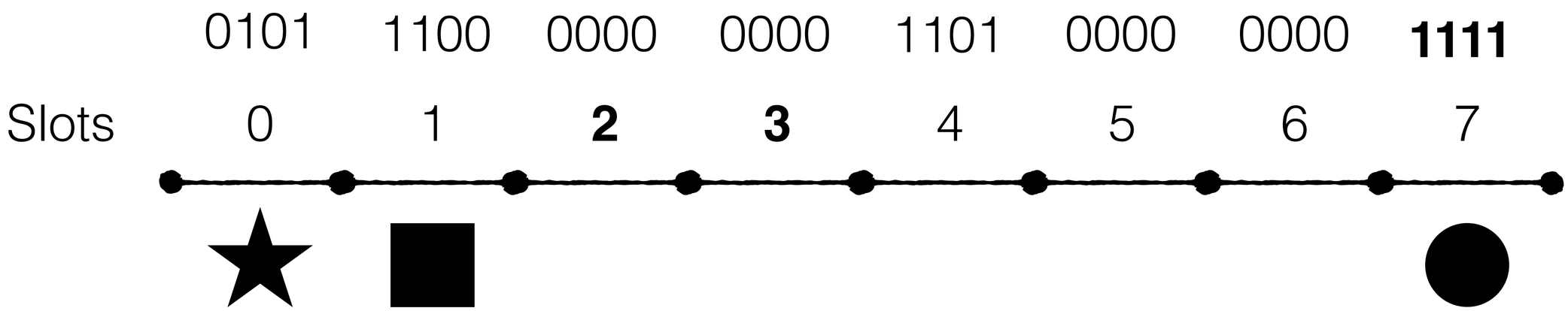


1111 = 0000 ⊕ 1111 ⊕ 0000

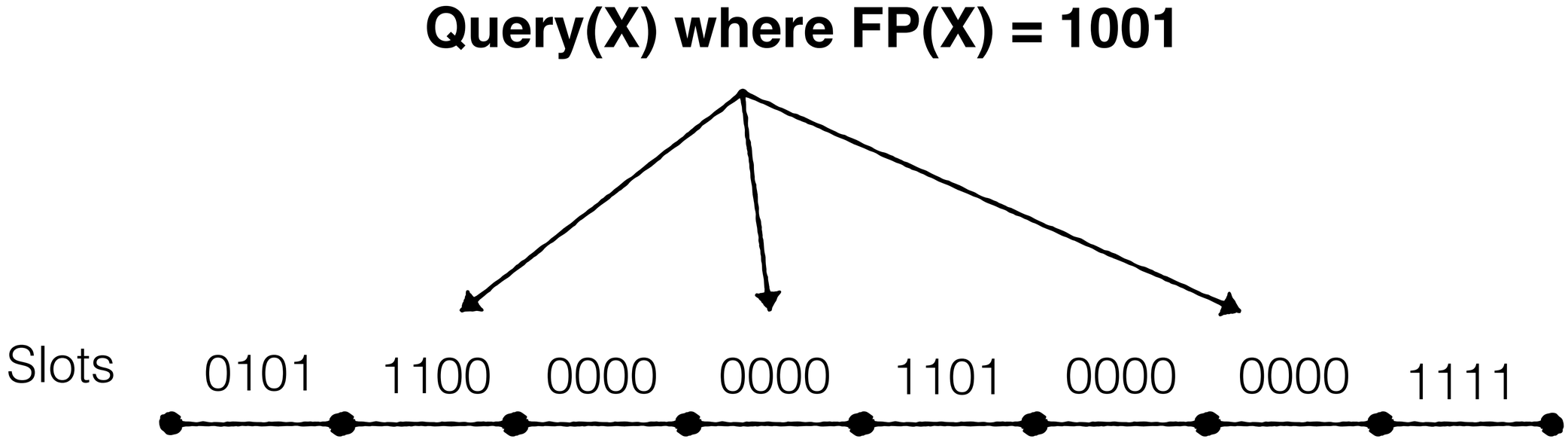
Populate all unassigned slots with zeros

Find some entry whose only other candidate slots are filled

Xor its fingerprint with content at other slots and store



We're done :)


Query(X) where FP(X) = 1001
Slots
0101
1100
0000
0000
1101
0000
0000
1111

Query(X) where FP(X) = **1001**

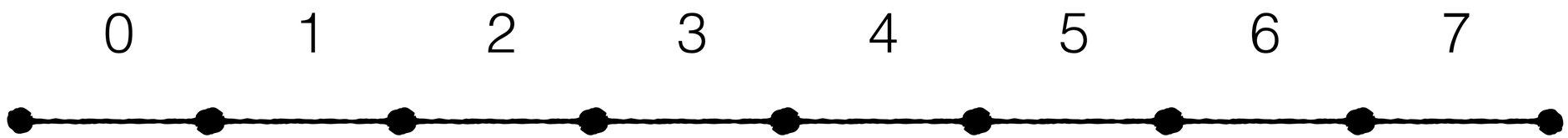
1100 ⊕ 0000 ⊕ 0000 = **1100**

Not a fingerprint match so return negative

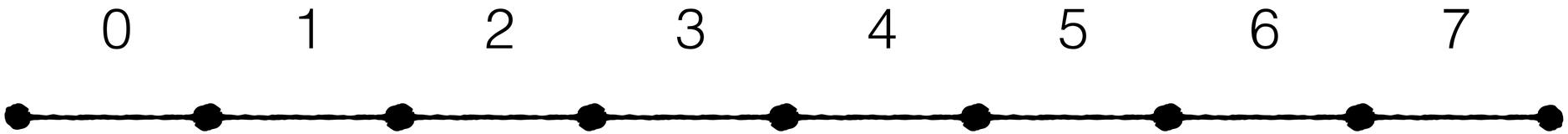
Query(X) where FP(X) = **1001**

1100 ⊕ 0000 ⊕ 0000 = **1100**

Construction can fail if there is no entry we can peel



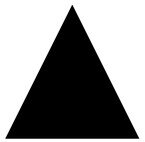
Construction can fail if there is no entry we can peel



Example:

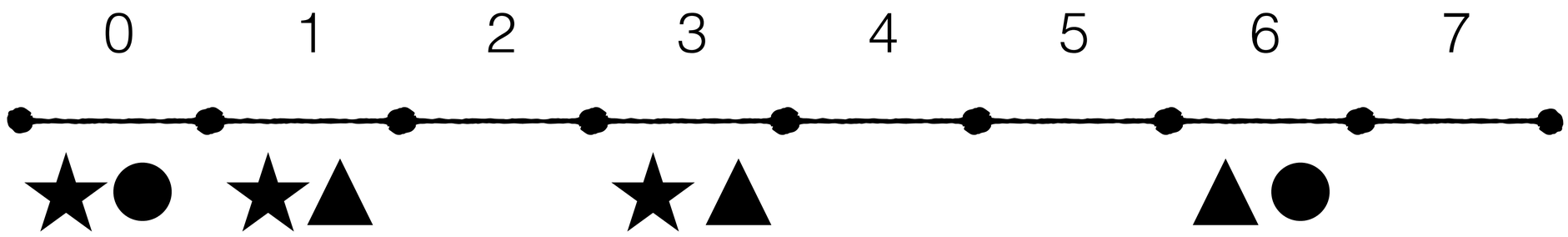
0, 1, 3

1, 3, 6



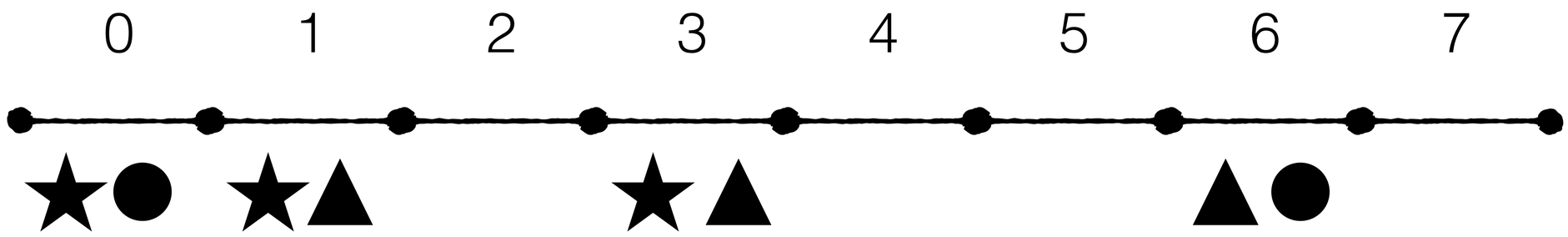
3, 6, 0

Construction can fail if there is no entry we can peel



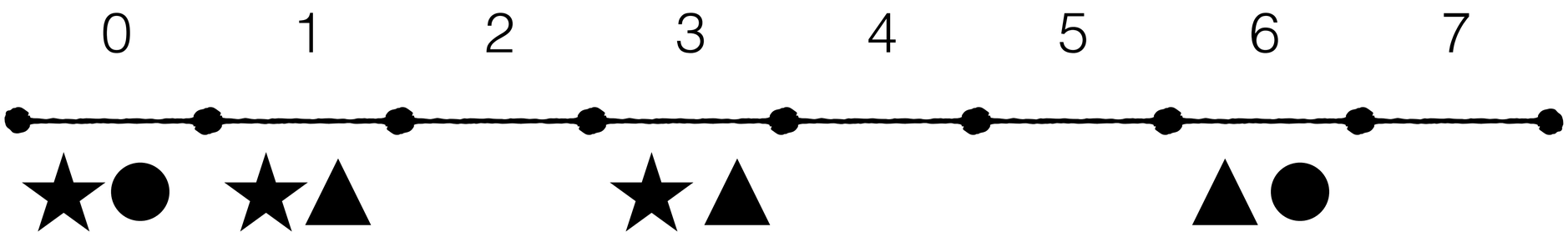
No slot has one entry uniquely mapping to it

If we fail, we must restart from scratch.



If we fail, we must restart from scratch.

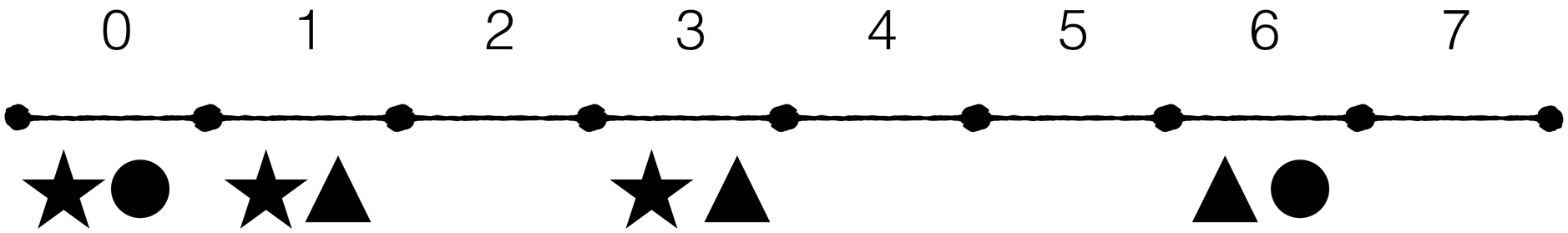
free space is necessary to succeed with high probability



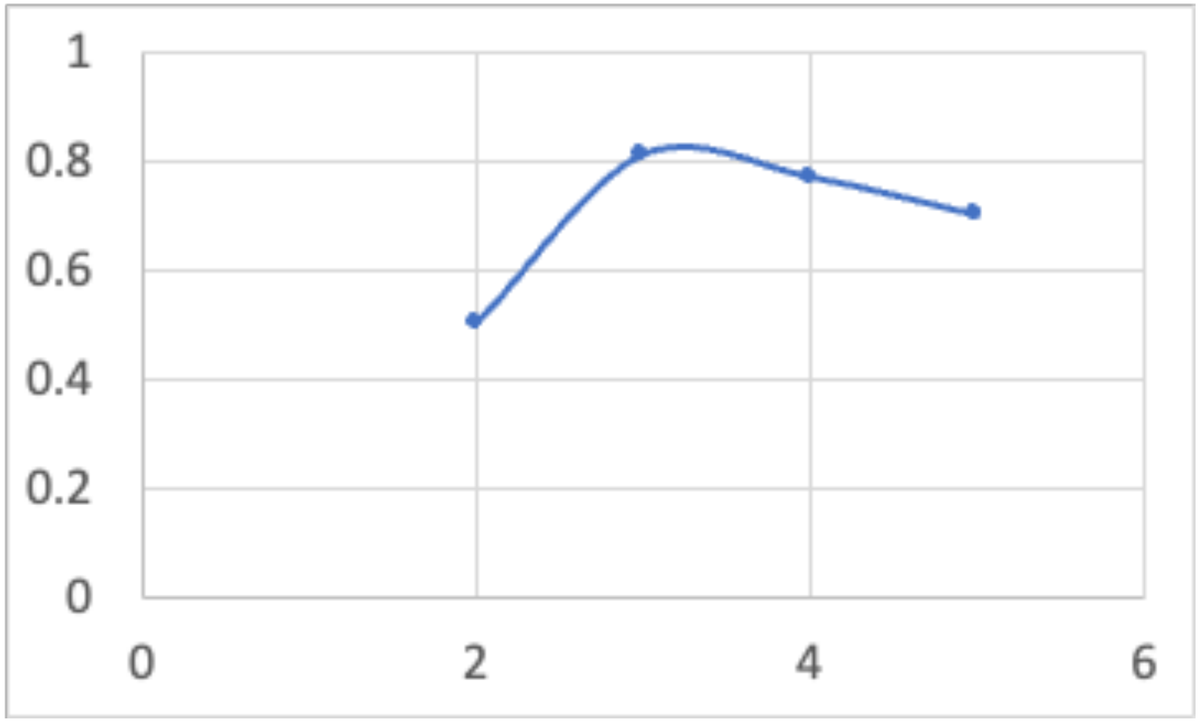
If we fail, we must restart from scratch.

free space is necessary to succeed with high probability

What's the interplay between free space and # number of hash functions?

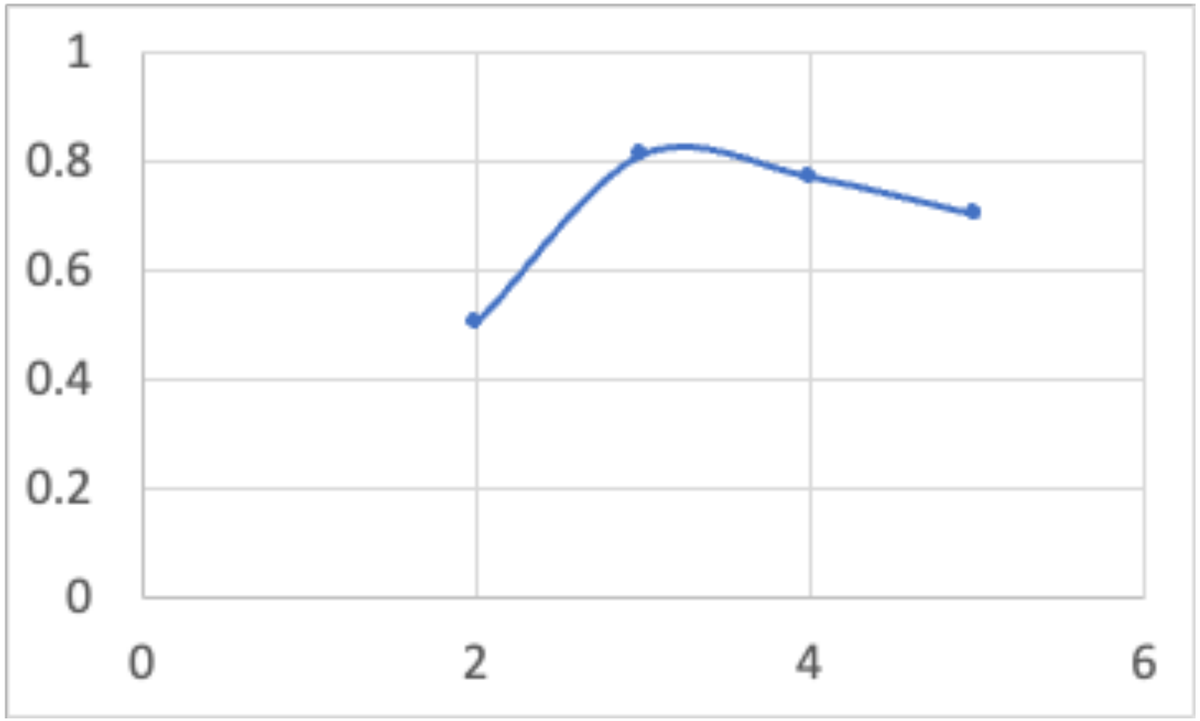


Utilization

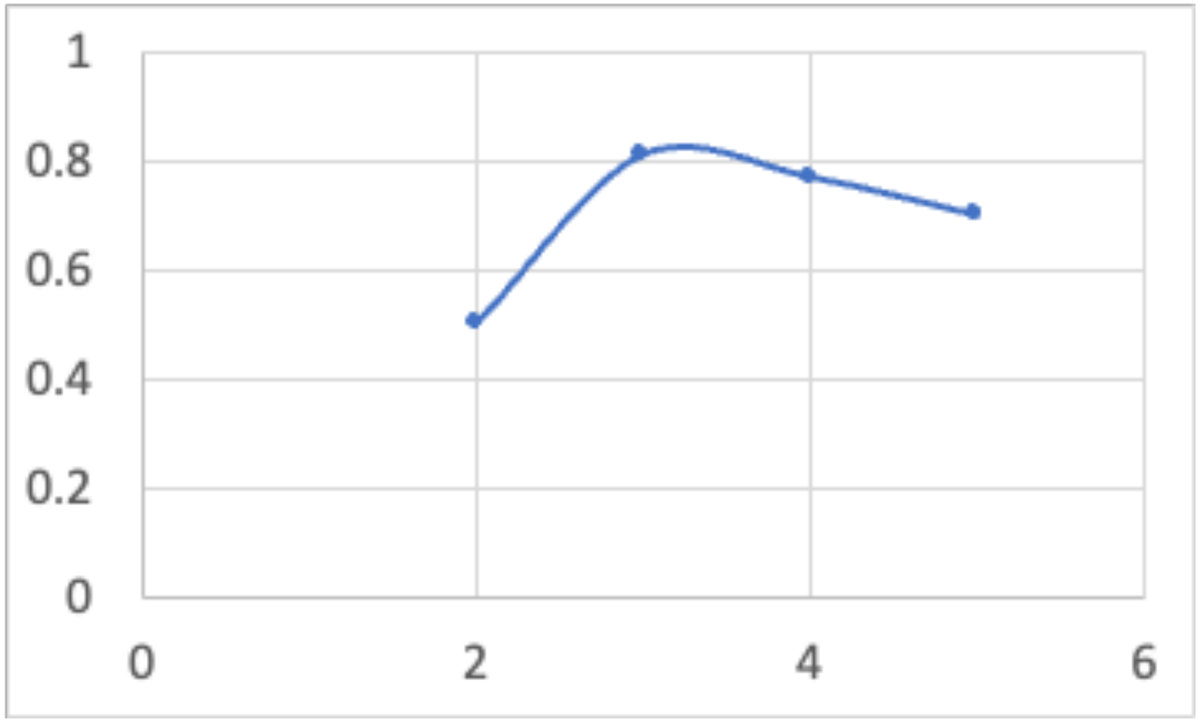


hash functions

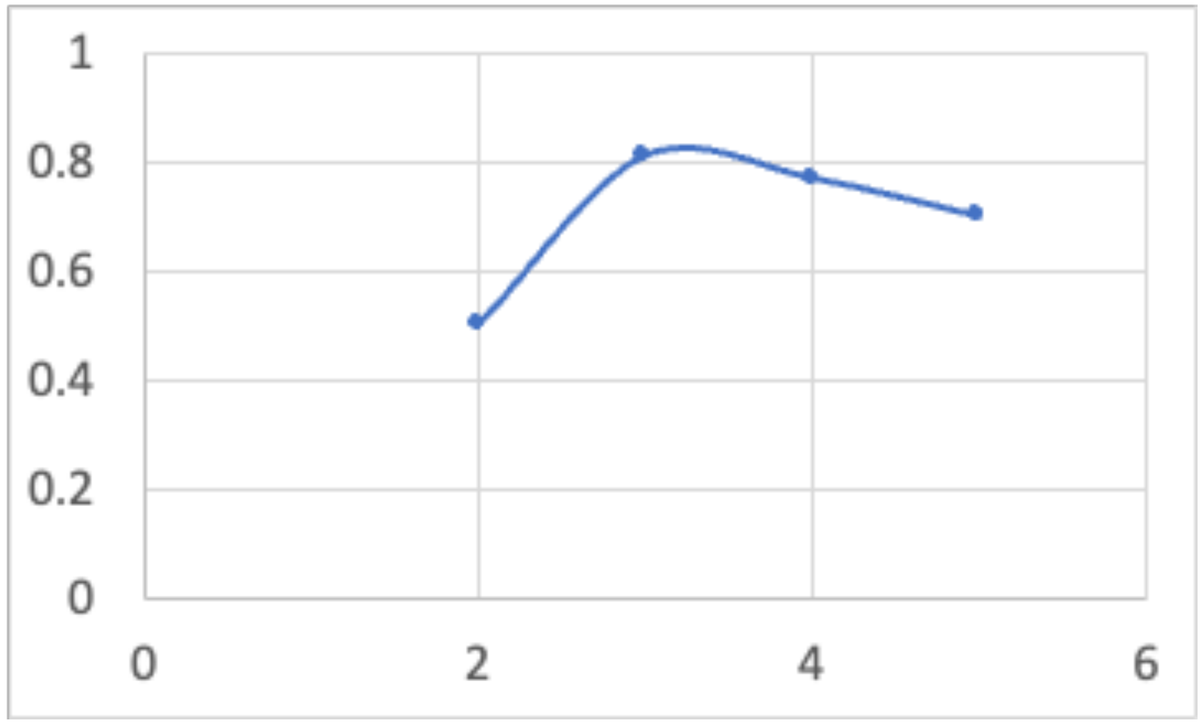
Not enough placement flexibility



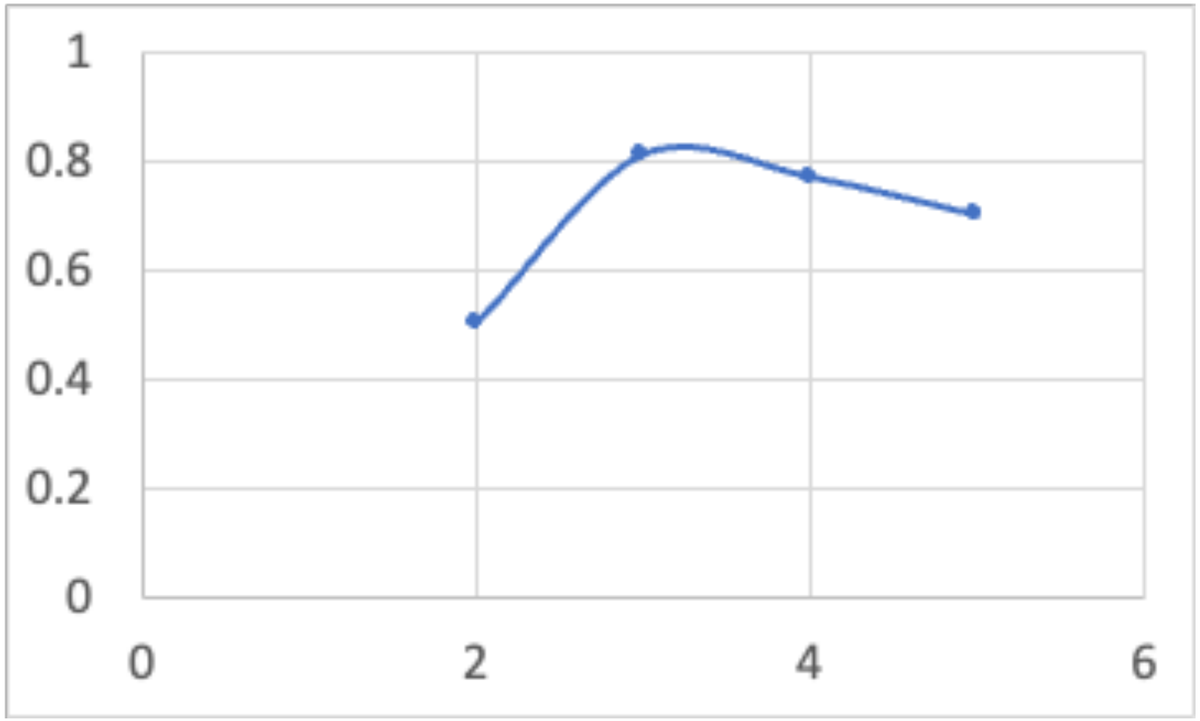
Too many items hashing to each slot



Optimal 0.81



Optimal 0.81

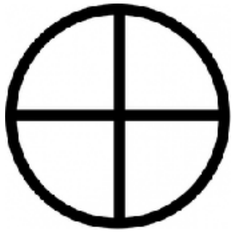


Similar to finding the optimal # hash functions with Bloom filters :)

Bloom

$\approx 2^{-M/N} \cdot 0.69$

XOR



$\boldsymbol{\approx 2^{-M/N} \cdot 0.81}$

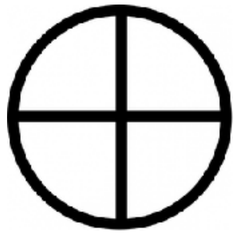
Idealized

$\approx 2^{-M/N}$

Bloom

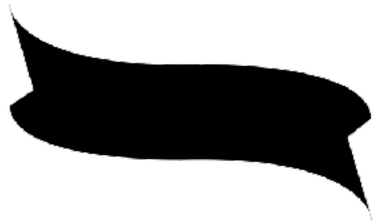
$\approx 2^{-M/N \cdot 0.69}$

XOR



$\approx 2^{-M/N \cdot 0.81}$

Ribbon

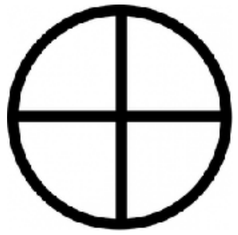
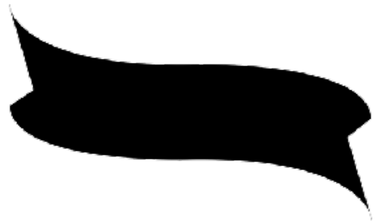


$\approx 2^{-M/N \cdot 0.92}$

Idealized

$\approx 2^{-M/N}$

Denser XOR filter

Bloom	XOR	**Ribbon**	Idealized
			
$\approx 2^{-M/N \cdot 0.69}$	$\approx 2^{-M/N \cdot 0.81}$	$\boldsymbol{\approx 2^{-M/N \cdot 0.92}}$	$\approx 2^{-M/N}$

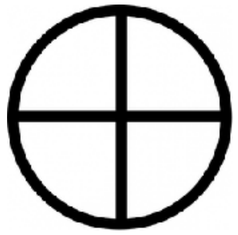
Denser XOR filter

In RocksDB since 2020

Bloom

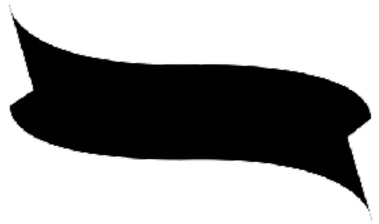
$\approx 2^{-M/N \cdot 0.69}$

XOR



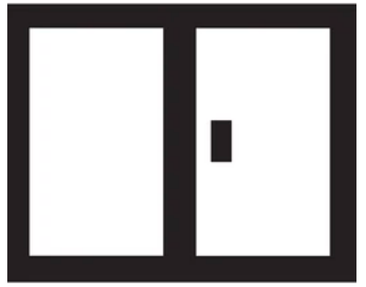
$\approx 2^{-M/N \cdot 0.81}$

Ribbon



$\approx 2^{-M/N \cdot 0.92}$

XOR filter w. Spatial Coupling



$\approx 2^{-M/N}$

Approach ideal

Operation Costs (in hash functions computed)

Construction =

Positive Query =

Avg. Negative Query =

Operation Costs (in hash functions computed)

Construction = **O(N)**

Positive Query =

Avg. Negative Query =

Operation Costs (in hash functions computed)

Construction = O(N)

Positive Query = **3**

Avg. Negative Query = **3**

Operation Costs (in hash functions computed)

Construction = O(N)

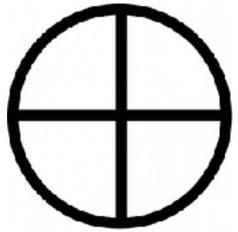
Positive Query = **3**

Avg. Negative Query = **3**

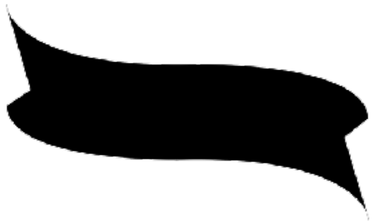
Not as good as blocked Bloom filters

Blocked Bloom

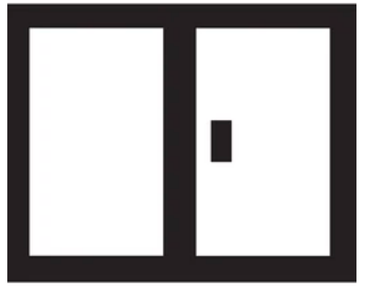
XOR



Ribbon



Spatial Coupling



Faster

Lower FPR

And now: office hours :)